

# BOXER-6645U-RPL

Fanless Embedded Box PC

User's Manual 1st Ed

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### Packing List

Before setting up your product, please make sure the following items have been shipped:

ltem		Quantity
•	BOXER-6645U-RPL	1
•	Wallmount Bracket	2
•	3 Pin DC-In Power Connector	1
•	Remote ON/OFF Cable	1
•	Screw Package	1

If any of these items are missing or damaged, please contact your distributor or sales representative immediately.

#### About this Document

This User's Manual contains all the essential information, such as detailed descriptions and explanations on the product's hardware and software features (if any), its specifications, dimensions, jumper/connector settings/definitions, and driver installation instructions (if any), to facilitate users in setting up their product.

Users may refer to the product page at AAEON.com for the latest version of this document.

## Safety Precautions

Please read the following safety instructions carefully. It is advised that you keep this manual for future references

- 1. All cautions and warnings on the device should be noted.
- 2. Make sure the power source matches the power rating of the device.
- Position the power cord so that people cannot step on it. Do not place anything over the power cord.
- Always completely disconnect the power before working on the system's hardware.
- 5. No connections should be made when the system is powered as a sudden rush of power may damage sensitive electronic components.
- If the device is not to be used for a long time, disconnect it from the power supply to avoid damage by transient over-voltage.
- 7. Always disconnect this device from any power supply before cleaning.
- 8. While cleaning, use a damp cloth instead of liquid or spray detergents.
- 9. Make sure the device is installed near a power outlet and is easily accessible.
- 10. Keep this device away from humidity.
- 11. Place the device on a solid surface during installation to prevent falls.
- 12. Do not cover the openings on the device to ensure optimal heat dissipation.
- 13. Watch out for high temperatures when the system is running.
- 14. Do not touch the heat sink or heat spreader when the system is running
- 15. Never pour any liquid into the openings. This could cause fire or electric shock.
- 16. As most electronic components are sensitive to static electrical charge, be sure to ground yourself to prevent static charge when installing the internal components. Use a grounding wrist strap and contain all electronic components in any static-shielded containers.

- 17. If any of the following situations arises, please the contact our service personnel:
  - i. Damaged power cord or plug
  - ii. Liquid intrusion to the device
  - iii. Exposure to moisture
  - iv. Device is not working as expected or in a manner as described in this manual
  - v. The device is dropped or damaged
  - vi. Any obvious signs of damage displayed on the device
- Do not leave this device in an uncontrolled environment with temperatures beyond the device's permitted storage temperatures (see chapter 1) to prevent damage.
- 19. Do NOT disassemble the motherboard so as not to damage the system or void your warranty.
- 20. If the thermal pad had been damaged, please contact AAEON's salesperson to purchase a new one. Do NOT use those of other brands.
- 21. The Hex Cylinder Coppers on the front panel are not removable.
- 22. Repeatedly assemble and disassemble the system may cause damages to the exterior paint and surface and screw holes.
- 23. Use the right size screwdriver.
- 24. Use the screwdriver correctly to remove screws from the system.



This device complies with Part 15 FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received including interference that may cause undesired operation.

#### Caution:

There is a danger of explosion if the battery is incorrectly replaced. Replace only with the same or equivalent type recommended by the manufacturer. Dispose of used batteries according to the manufacturer's instructions and your local government's recycling or disposal directives.

#### Attention:

Il y a un risque d'explosion si la batterie est remplacée de façon incorrecte. Ne la remplacer qu'avec le même modèle ou équivalent recommandé par le constructeur. Recycler les batteries usées en accord avec les instructions du fabricant et les directives gouvernementales de recyclage.

#### China RoHS Requirements (CN)

#### 产品中有毒有害物质或元素名称及含量

AAEON System

QO4-381 Rev.A2

	有毒有害物质或元素						
部件名称	铅	汞	镉	六价铬	多溴联苯	多溴二苯醚	
	(Pb)	(Hg)	(Cd)	(Cr(VI))	(PBB)	(PBDE)	
印刷电路板	×	0	0	0	0	0	
及其电子组件	×	0	0	0	0	0	
外部信号	~	$\sim$	C	0	0	0	
连接器及线材	×	0	0	0	0	0	
外壳	0	0	0	0	0	0	
中央处理器	~	0	$\bigcirc$	0	0	0	
与内存	~	0	0	0	0	0	
硬盘	×	0	0	0	0	0	
液晶模块	×	0	0	0	0	0	
光驱	×	0	0	0	0	0	
触控模块	×	0	0	0	0	0	
电源	×	0	0	0	0	0	
电池	×	0	0	0	0	0	

本表格依据 SJ/T 11364 的规定编制。

〇: 表示该有毒有害物质在该部件所有均质材料中的含量均在 GB/T 26572 标准规定的限量要求以下。

×: 表示该有害物质的某一均质材料超出了 GB/T 26572 的限量要求, 然而该部件仍 符合欧盟指令 2011/65/EU 的规范。

环保使用期限(EFUP (Environmental Friendly Use Period)) : 10 年 备注:

一、此产品所标示之环保使用期限,系指在一般正常使用状况下。

二、上述部件物质中央处理器、内存、硬盘、光驱、电源为选购品。

三、上述部件物质液晶模块、触控模块仅一体机产品适用。

BOXER-6645U-RPI

#### Name and content of hazardous substances in product

#### AAEON System

QO4-381 Rev.A2

	Hazardous Substances						
Part Name	铅	汞	镉	六价铬	多溴联苯	多溴二苯醚	
	(Pb)	(Hg)	(Cd)	(Cr(VI))	(PBB)	(PBDE)	
PCB Assemblies	×	0	0	0	0	0	
Connector and		0	0	0	0	0	
Cable	×	0	0	0	0	0	
Chassis	0	0	0	0	0	0	
CPU and Memory	×	0	0	0	0	0	
Hard Disk	×	0	0	0	0	0	
LCD Modules	×	0	0	0	0	0	
CD-ROM/DVD-ROM	×	0	0	0	0	0	
Touch Modules	×	0	0	0	0	0	
Power	×	0	0	0	0	0	
Battery	×	0	0	0	0	0	

The table is prepared in accordance with the provisions of SJ/T 11364.

O : Indicates that said hazardous substance contained in all of the homogenous materials for this product is below the limit requirement of GB/T 26572.

× : Indicates that said hazardous substance contained in at least one of the homogenous materials used for this part is above the limit requirement of GB/T 26572. But this product still be compliance with 2011/65/EU Directive (allowed with 2011/65/EU Annex III of RoHS exemption with number 6(c),7(a),7(c)-1).

EFUP (Environment Friendly Use Period) value: 10 years.

1. This product defined period of use is under normal condition.

2. In above part, CPU/Memory/ Hard Disk/CD-ROM/DVD-ROM/ Power are optional.

3. In above part, LCD Modules/ Touch Modules are for all-in-one product model.

# Table of Contents

Chapter 1 - Product Specifications				
1.1	Specifications	2		
Chapter 2 –	Hardware Information	5		
2.1	Dimensions	6		
2.2	Jumpers and Connectors	7		
2.3	List of Jumpers	8		
2.3.1	Setting Jumpers	8		
2.3.2	Clear CMOS Jumper (JP1)	9		
2.3.3	ATX/AT Mode Selection (JP3)	9		
2.4	List of Connectors	10		
2.4.1	HDMI (CN2)	11		
2.4.2	2.5GbE LAN + USB (CN3)	12		
2.4.3	Gbe LAN + USB Port (CN4)	14		
2.4.4	M.2 2230 E-Key (CN5)	15		
2.4.5	M.2 2280 M-Key (CN6)	16		
2.4.6	Remote Button (CN8)	17		
2.4.7	SPI Flash Port (CN9)	18		
2.4.8	eSPI Connector (CN10)	18		
2.4.9	SATA Connector (CN12/CN13)	19		
2.4.10	SATA Power Connector (CN14/CN15)	20		
2.4.11	DIO Port (CN16)	20		
2.4.12	COM 1 + COM 2 (CN17)	21		
2.4.13	COM Port 3 (Wafer Box, Optional) (CN18)	22		
2.4.14	COM Port 4 (Wafer Box, Optional) (CN19)	23		
2.4.15	COM Port 5 (Wafer Box, Optional) (CN20)	24		
2.4.16	COM Port 6 (Wafer Box, Optional) (CN21)	25		
2.4.17	USB 2.0 Wafer (CN22, CN23)	26		

	2.4.18	Dual USB 3.2 Port (CN24)	26
	2.4.19	Audio Connector (CN25)	27
	2.4.20	) Audio Wafer (CN26)	
	2.4.21	DC Terminal Block (CN28)	29
	2.4.22	2 SIM Slot (CN30)	29
	2.4.23	Fan Connector (CN32)	
	2.5	CPU & RAM Installation	31
	2.6	2.5" SATA Drive Installation	
	2.7	Expansion Module Installation	
	2.7.1	NVMe Module Installation	41
	2.8	Wall Mount Installation	
	2.9	DIN Rail Installation	45
Cł	napter 3 -	AMI BIOS Setup	46
	3.1	System Test and Initialization	
	3.2	AMI BIOS Setup	
	3.3	Setup Submenu: Main	
	3.4	Setup Submenu: Advanced	50
	3.4.1	CPU Configuration	51
	3.4.2	Memory Configuration	
	3.4.3	PCH-FW Configuration	53
	3.4	4.3.1 Firmware Update Configuration	54
	3.4.4	Hardware Monitor	55
	3.4.5	Power Management	56
	3.4.6	AAEON BIOS Robot	57
	3.4	4.6.1 Device Detecting Configuration	
	3.5	Setup Submenu: System I/O	65
	3.5.1	Storage Configuration	
	3.5.2	NVMe Configuration	67

3.5.3	HD	Audio Configuration	68	
3.5.4	Leg	acy Logical Devices Configuration	69	
3.	5.4.1	Serial Port 1	70	
3.	5.4.2	Serial Port 2	71	
3.5.5	Seri	ial Port Console Redirection	72	
3.	5.5.1	Console Redirection Settings (COM0)	73	
3.	5.5.2	Console Redirection Settings (Out-of-Band Mgmt Port)	75	
3.6	Setup	Submenu: Security	77	
3.6.1	Trus	sted Computing	78	
3.6.2	Sec	ure Boot	80	
3.	6.2.1	Key Management	81	
3.7	Setup	Submenu: Boot	83	
3.7.1	UEF	BBS Priorities	84	
3.8	Setup	Submenu: Save & Exit	85	
Chapter 4 -	- Driver	s Installation	86	
4.1	Drive	rs Download and Installation	87	
Appendix A	√ – I/O	Information	88	
A.1	I/O A	ddress Map	89	
A.2	A.2 Memory Address Map			
A.3	IRQ N	Napping Chart	92	

# Chapter 1

Product Specifications

# 1.1 Specifications

System	
CPU	13th/14th Generation Intel® Core™ LGA 1700 Socket-Type
	Processor, Max TDP 65W
	13th Generation Intel® Core™ Processors:
	Intel® Core™ i9-13900TE/Intel® Core™ i9-13900E
	Intel® Core™ i7-13700TE/Intel® Core™ i7-13700E
	Intel® Core™ i5-13500TE/Intel® Core™ i5-13500E
	Intel® Core™ i3-13100TE/Intel® Core™ i3-13100E
	14th Generation Intel® Core™ Processors:
	Intel® Core™ i9 processor 14900
	Intel® Core™ i9 processor 14900T
	Intel® Core™ i7 processor 14700
	Intel® Core™ i7 processor 14700T
	Intel® Core™ i5 processor 14500
	Intel® Core™ i5 processor 14500T
	Intel® Core™ i3 processor 14100
	Intel® Core™ i3 processor 14100T
Chipset	Intel® H610E
System Memory	DDR5 SODIMM x 2, up to 64GB
Display Interface	HDMI 1.4a (Type-A) x 2, 4K @30Hz
Storage	2.5″ SATA Drive Bay x 2
	M.2 2280 M-Key x 1 (PCIe Gen 3 [x4]) for NVMe
Ethernet	Intel® Ethernet Connection I219-LM, GbE RJ-45 x 1
	Intel® Ethernet Controller I226-LM, 2.5GbE RJ-45 x 1
I/O	USB 3.2 Gen 2 x 4
	USB 2.0 x 2

System	
I/O Cont.	DB-9 x 2 for RS-232/422/485
	Audio x 1 (Mic-in/Line-out)
	Power Button with Power LED x 1
	Remote Power On/Off x 1
Expansion	M.2 2280 M-Key x 1 (NVMe)
	M.2 2230 E-Key x 1 (Wi-Fi/Bluetooth)
	Full Size mPCle x 1 (optional for mSATA)
Indicator	System Power LED x 1
OS Support	Windows® 10 IoT Enterprise (64-bit)
	Windows® 11 Pro (64-bit)
	Linux Ubuntu 22.04

Power Supply		
Power Requirement	3-pin DC Input 10~35V	
Mechanical		
Mounting	Wall Mount	
Dimensions (W x H x D)	7.09" x 3.04" x 8.66" (180mm x 77.2mm x 220mm)	
	8.43" x 3.31" x 8.66" (214mm x 84.2mm x 220mm) with	

bracketsGross Weight8.5 lb. (3.9Kg)

**Net Weight** 6.3 lb. (2.9Kg)

Environmental	
Operating	-13°F ~ 131°F (-25°C ~ 55°C), IEC60068-2 with 0.7 m/s
Temperature	Airflow, with W.T memory/storage (TDP 65W CPU)
	-13°F $\sim$ 158°F (-25°C $\sim$ 70°C), IEC60068-2 with 0.7 m/s
	Airflow, with W.T memory/storage (TDP 35W CPU)
Storage Temperature	-40 °F ~ 176°F (-40°C ~ 80°C)
Storage Humidity	5 ~ 95% @ 40°C, non-condensing
Anti-Vibration	3 Grms/ 5 $\sim$ 500Hz/ operation (with SSD)
Anti-Shock	50G, IEC68-2-27, half sine, 11ms duration (with SSD)
Certification	CE/FCC Class A/LVD

Note: Industrial grade memory modules are recommended (temperature range: -40°F  $\sim$  185°F (-40°C  $\sim$  85°C) or above).

**Note**: For Gen 4 storage module, a thermal solution is mandatory for heat-dissipation. Please check with your AAEON representative if you have any queries regarding this requirement.

# Chapter 2

Hardware Information

#### 2.1 Dimensions



#### 2.2 Jumpers and Connectors



#### 2.3 List of Jumpers

Please refer to the table below for all of the system's jumpers that you can configure for your application.

Label	Function
JP1	CMOS Control Selection
JP3	Auto-Power Button Selection

#### 2.3.1 Setting Jumpers

The BOXER-6645U-RPL comes with several jumpers which allow you to configure the system by either setting the jumper to "open" or "closed"; or by selecting certain pins. A closed jumper has two pins connected with a jumper clip, while an open jumper has no pins connected.

For jumpers with multiple pins, this guide uses "pins A-B" to notate which pins should be connected by a jumper clip. For example, "pins 1-2" means you should connect pins 1 and 2, while "pins 2-3" means you should connect pins 2 and 3.



A pair of needle-nose pliers may be helpful when working with jumpers.

If you have any questions about how best to configure the system for your application, contact your AAEON representative or visit our website to talk with our support team.



Normal (Default)





#### 2.3.3 ATX/AT Mode Selection (JP3)



ATX (default)



AT

### 2.4 List of Connectors

Please refer to the table below for all of the system's connectors that you can configure for your application

Label	Function
CN2	HDMI
CN3	2.5GbE LAN + USB Port
CN4	Gbe LAN + USB Port
CN5	M.2 2230 E-Key
CN6	M.2 2280 M-Key
CN8	Remote Button
CN9	SPI Flash Port
CN10	eSPI Connector
CN12	SATA Connector
CN13	SATA Connector
CN14	SATA Power Connector n
CN15	SATA Power Connector
CN16	DIO
CN17	COM 1 + COM 2
CN18	COM 3
CN19	COM 4
CN20	COM 5
CN21	COM 6
CN22	USB 2.0 Wafer
CN23	USB 2.0 Wafer
CN24	Dual USB 3.2 Port
CN25	Audio
CN26	Audio Wafer
CN28	DC Terminal Block
CN30	SIM Slot
PCIE1	Mini Card Slot



Pin	Pin Name	Signal Type	Signal level
P1	HDMI1_DATA2_P	DIFF	
P2	GND	GND	
P3	HDMI1_DATA2_N	DIFF	
P4	HDMI1_DATA1_P	DIFF	
P5	GND	GND	
P6	HDMI1_DATA1_N	DIFF	
P7	HDMI1_DATA0_P		
P8	GND	GND	
P9	HDMI1_DATA0_n		
P10	HDMI1_CLK_P	DIFF	
P11	GND	GND	
P12	HDMI1_CLK_N	DIFF	
P13	CEC		3.3V
P14	NC		
P15	HDMI1_SCL		
P16	HDMI1_SDA		
P17	GND	GND	
P18	+V5S_HDMI_CON	PWR	5V
P19	HDMI1_HPD		5V
P20	HDMI2_DATA2_P		

Pin	Pin Name	Signal Type	Signal level
P21	GND	GND	
P22	HDMI2_DATA2_N		
P23	HDMI2_DATA1_P		
P24	GND	GND	
P25	HDMI2_DATA1_N		
P26	HDMI2_DATA0_P		
P27	GND	GND	
P28	HDMI2_DATA0_N		
P29	HDMI2_CLK_P		
P30	GND	GND	
P31	HDMI2_CLK_N		
P32	CEC		3.3V
P33	NC		
P34	HDMI2_SCL		
P35	HDMI2_SDA		
P36	GND	GND	
P37	+V5S_HDMI_CON		5V
P38	HDMI2_HPD		5V

# 2.4.2 2.5GbE LAN + USB (CN3)



Pin	Pin Name	Signal Type	Signal level
1	MDI0+	DIFF	
2	MDI0-	DIFF	
3	MDI1+	DIFF	
4	MDI2+	DIFF	

Chapter 2 – Hardware Information

12

Pin	Pin Name	Signal Type	Signal level
5	MDI2-	DIFF	
6	MDI1-	DIFF	
7	MDI3+	DIFF	
8	MDI3-	DIFF	



Pin	Pin Name	Signal Type	Signal level
1	+5VSB	PWR	+5V
2	USB1_D-	DIFF	
3	USB1_D+	DIFF	
4	GND	GND	
5	USB1_SSRX-	DIFF	
6	USB1_SSRX+	DIFF	
7	GND	GND	
8	USB1_SSTX-	DIFF	
9	USB1_SSTX+	DIFF	
10	+5VSB	PWR	+5V
11	USB2_D-	DIFF	
12	USB2_D+	DIFF	
13	GND	GND	
14	USB2_SSRX-	DIFF	
15	USB2_SSRX+	DIFF	
16	GND	GND	
17	USB2_SSTX-	DIFF	
18	USB2_SSTX+	DIFF	



Pin	Pin Name	Signal Type	Signal level
1	MDI0+	DIFF	
2	MDI0-	DIFF	
3	MDI1+	DIFF	
4	MDI2+	DIFF	
5	MDI2-	DIFF	
6	MDI1-	DIFF	
7	MDI3+	DIFF	
8	MDI3-	DIFF	



Pin	Pin Name	Signal Type	Signal level
1	+5VSB	PWR	+5V
2	USB2_D-	DIFF	
3	USB2_D+	DIFF	
4	GND	GND	
5	+5VSB	PWR	+5V

Chapter 2 – Hardware Information

Pin	Pin Name	Signal Type	Signal level
6	USB2_D-	DIFF	
7	USB2_D+	DIFF	
8	GND	GND	

### 2.4.4 M.2 2230 E-Key (CN5)



Standard specification.

#### 2.4.5 M.2 2280 M-Key (CN6)



Pin	Pin Name	Signal Type	Signal Level	Pin	Pin Name	Signal Type	Signal Level
1	GND	GND		2	+3.3V	PWR	+3.3V
3	GND	GND		4	+3.3V	PWR	+3.3V
5	PCIE_RXN0	IN		6	CARD_PWR_OFF_N	OUT	+3.3V
7	PCIE_RXP0	IN		8	NC		
9	GND	GND		10	NC		
11	PCIE_TXN0	OUT		12	+3.3V	PWR	+3.3V
13	PCIE_TXP0	OUT		14	+3.3V	PWR	+3.3V
15	GND	PWR		16	+3.3V	PWR	+3.3V
17	PCIE_RXN1	IN		18	+3.3V	PWR	+3.3V
19	PCIE_RXP1	IN		20	NC		
21	GND	PWR		22	NC		
23	PCIE_TXN1	OUT		24	NC		
25	PCIE_TXP1	OUT		26	NC		
27	GND	PWR		28	NC		
29	PCIE_RXN2	IN		30	NC		
31	PCIE_RXP2	IN		32	NC		
33	GND	GND		34	NC		
35	PCIE_TXN2	OUT		36	NC		
37	PCIE_TXP2	OUT		38	DEVSLP	IN	+3.3V
39	GND	GND		40	SMB_CLK_M2		+1.8V
41	PCIE_RXP3	IN		42	SMB_DATA_M2		+1.8V
43	PCIE_RXN3	IN		44	NC		
45	GND	GND		46	NC		
47	PCIE_TXN3	OUT		48	NC		

Pin	Pin Name	Signal Type	Signal Level	Pin	Pin Name	Signal Type	Signal Level
49	PCIE_TXP3	OUT		50	RESET#	IN	+3.3V
51	GND	PWR		52	CLKREQ#	OUT	+3.3V
53	PCIE_M.2_CLK#	OUT		54	WAKE#	OUT	+3.3V
55	PCIE_M.2_CLK	OUT		56	NC		
57	GND	GND		58	NC		

67	NC		68	NC		
69	NC		70	+3.3V	PWR	+3.3V
71	GND	GND	72	+3.3V	PWR	+3.3V
73	GND	GND	74	+3.3V	PWR	+3.3V
75	GND	GND				

# 2.4.6 Remote Button (CN8)



Pin	Pin Name	Signal Type	Signal level
1	PWR_BUTTON	IN	
2	GND	GND	

#### 2.4.7 SPI Flash Port (CN9)

Pin	Pin Name	Signal Type	Signal level
1	spi_miso	OUT	
2	GND	GND	
3	SPI_CLK	IN	
4	+3.3VSB	PWR	+3.3V
5	spi_mosi	IN	
6	SPI_CS	IN	
7	NC		
8	NC		

#### 2.4.8 eSPI Connector (CN10)



Pin	Pin Name	Signal Type	Signal level
1	ESPI_IO_0	I/O	+1.8V
2	ESPI_IO_1	I/O	+1.8V
3	ESPI_IO_2	I/O	+1.8V
4	ESPI_IO_3	I/O	+1.8V
5	+3.3V	PWR	+3.3V
6	ESPI_IO_CS#	IN	
7	ESPI_IO_RST#	IN	
8	GND	GND	

Chapter 2 – Hardware Information

Pin	Pin Name	Signal Type	Signal level
9	EPSI_IO_LCLK	IN	
10	SMCLK	IN	
11	SMDAT	I/O	
12	NC		

# 2.4.9 SATA Connector (CN12/CN13)



Pin	Pin Name	Signal Type	Signal level
1	GND	GND	
2	SATA_TX+	DIFF	
3	SATA_TX-	DIFF	
4	GND	GND	
5	SATA_RX-	DIFF	
6	SATA_RX+	DIFF	
7	GND	GND	

#### 2.4.10 SATA Power Connector (CN14/CN15)



Pin	Pin Name	Signal Type	Signal level
1	+12V	PWR	+12V
2	GND	GND	
3	GND	GND	
4	+5V	PWR	+5V

# 2.4.11 DIO Port (CN16)



Pin	Pin Name	Signal Type	Signal level
1	DIO0	I/O	+5V
2	DIO1	I/O	+5V
3	DIO2	I/O	+5V
4	DIO3	I/O	+5V
5	DIO4	I/O	+5V
6	DIO5	I/O	+5V
7	DIO6	I/O	+5V
8	DIO7	I/O	+5V

Pin	Pin Name	Signal Type	Signal level
9	+5V	PWR	+5V
10	GND	GND	

# 2.4.12 COM 1 + COM 2 (CN17)



Pin	Pin Name	Signal Type	RS-422	RS-485
1	DCD	IN	RS422_TX-	RS485_D-
2	RX	IN	RS422_TX+	RS485_D+
3	ТХ	OUT	RS422_RX+	
4	DTR	OUT	RS422_RX-	
5	GND	GND		
6	DSR	IN		
7	RTS	OUT		
8	CTS	IN		
9	RI1	IN		

### 2.4.13 COM Port 3 (Wafer Box, Optional) (CN18)



Pin	Pin Name	Signal Type	RS-422	RS-485
1	DCD	IN	RS422_TX-	RS485_D-
2	DSR	IN		
3	RX	IN	RS422_TX+	RS485_D+
4	RTS	OUT		
5	ТХ	OUT	RS422_RX+	
6	CTS	IN		
7	DTR	OUT	RS422_RX-	
8	RI	IN		
9	GND	GND		

### 2.4.14 COM Port 4 (Wafer Box, Optional) (CN19)



Pin	Pin Name	Signal Type	RS-422	RS-485
1	DCD	IN	RS422_TX-	RS485_D-
2	DSR	IN		
3	RX	IN	RS422_TX+	RS485_D+
4	RTS	OUT		
5	ТХ	OUT	RS422_RX+	
6	CTS	IN		
7	DTR	OUT	RS422_RX-	
8	RI	IN		
9	GND	GND		
#### 2.4.15 COM Port 5 (Wafer Box, Optional) (CN20)



Pin	Pin Name	Signal Type	RS-422	RS-485
1	DCD	IN	RS422_TX-	RS485_D-
2	DSR	IN		
3	RX	IN	RS422_TX+	RS485_D+
4	RTS	OUT		
5	ТХ	OUT	RS422_RX+	
6	CTS	IN		
7	DTR	OUT	RS422_RX-	
8	RI	IN		
9	GND	GND		

#### 2.4.16 COM Port 6 (Wafer Box, Optional) (CN21)



Pin	Pin Name	Signal Type	RS-422	RS-485
1	DCD	IN	RS422_TX-	RS485_D-
2	DSR	IN		
3	RX	IN	RS422_TX+	RS485_D+
4	RTS	OUT		
5	ТХ	OUT	RS422_RX+	
6	CTS	IN		
7	DTR	OUT	RS422_RX-	
8	RI	IN		
9	GND	GND		

#### 2.4.17 USB 2.0 Wafer (CN22, CN23)

Pin	Pin Name	Signal Type	Signal level
1	+5V	GND	+5V
2	USBD-	DIFF	
3	USBD+	DIFF	
4	GND	GND	
5	GND	GND	

#### 2.4.18 Dual USB 3.2 Port (CN24)



Pin	Pin Name	Signal Type	Signal level
1	+5VSB	PWR	+5V
2	USB1_D-	DIFF	
3	USB1_D+	DIFF	
4	GND	GND	
5	USB1_SSRX-	DIFF	
6	USB1_SSRX+	DIFF	
7	GND	GND	
8	USB1_SSTX-	DIFF	
9	USB1_SSTX+	DIFF	
10	+5VSB	PWR	+5V
11	USB2_D-	DIFF	
12	USB2_D+	DIFF	

Pin	Pin Name	Signal Type	Signal level
13	GND	GND	
14	USB2_SSRX-	DIFF	
15	USB2_SSRX+	DIFF	
16	GND	GND	
17	USB2_SSTX-	DIFF	
18	USB2_SSTX+	DIFF	

## 2.4.19 Audio Connector (CN25)



Pin	Pin Name	Signal Type	Signal level
5	AUD_GND	GND	
24	LOUT_L	OUT	
21	LOUT_R	OUT	
2P	HP_DET_3	IN	
2Q	HP_DET_4	IN	
14	MIC_L	IN	
11	MIC_R	IN	
1P	HP_DET_1	IN	
1Q	HP_DET2	IN	

#### 2.4.20 Audio Wafer (CN26)



Pin	Pin Name	Signal Type	Signal level
1	MIC_L	IN	
2	MIC_R	IN	
3	GND_AUDIO	GND	
4	LINE_L_IN	IN	
5	LINE_R_IN	IN	
6	GND_AUDIO	GND	
7	LEFT_OUT	OUT	
8	GND_AUDIO	GND	
9	RIGHT_OUT	OUT	
10	+5V_AUDIO	PWR	+5V

## 2.4.21 DC Terminal Block (CN28)



## PIN1 PIN2 PIN3

Pin	Pin Name	Signal Type	Signal level
1	VIN	PWR	+12V ~ +24V
2	GND	GND	
3	GND_EARTH		

## 2.4.22 SIM Slot (CN30)

Pin	Pin Name	Signal Type	Signal level
1	UIM_PWR	PWR	
2	UIM_RST	IN	
3	UIM_CLK	IN	
4	GND	GND	
5	UIM_VPP	PWR	
6	UIM_DATA	I/O	

## 2.4.23 Fan Connector (CN32)



Pin	Pin Name	Signal Type	Signal level
1	GND	GND	
2	+V12S	PWR	+12V
3	FAN_PWM	OUT	
4	FAN_CTL	OUT	

#### 2.5 CPU & RAM Installation

Before installing the CPU, RAM, or any other components, ensure the system is powered down and disconnect the power cord from the system. See Chapter 1 Specifications for list of compatible CPU/processors.

**Note**: When using memory modules with ICs on both sides, choose a thin thermal pad (1 mm thickness) to ensure proper contact with their heatsinks. Conversely, if the memory modules have ICs on only one side, choose a thick thermal pad (2mm thickness) to ensure effective contact with their heatsinks.



**Step 1:** Remove the six (6) screws on the top of the BOXER-6645U-RPL as shown in the figure below, and remove the top heatsink.



**Step 2:** Insert CPU and your first SODIMM into the slots on the system's motherboard. Reference section 2.2 for DIMM1 location. Ensure thermal pads are placed between the modules being installed and the motherboard.



**Step 3:** Remove the bottom panel of the system by removing the eight (8) screws, as shown below.



**Step 4:** Insert second SODIMM module, noting the location of the slot as shown below. Ensure a thermal pad is placed between the module being installed and the motherboard.





Step 5: Reassemble system, ensuring to affix the side panel with the two (2) screws as

#### 2.6 2.5" SATA Drive Installation

Before installing the SATA Drives, ensure the system is powered down and disconnect the power cord from the system. Make sure you have the SATA Drive ready to install. See Chapter 1 for SATA drive specifications for compatibility.

**Step 1**: Remove the bottom panel of the system by removing the eight (8) screws, as shown below.



Step 2: Attach each SATA drive to the HDD Brackets using the screws provided.



**Step 3:** Attach the HDD Brackets for each drive to the bottom panel using four (4) screws per drive as shown in the figure below.





Step 4: Attach the SATA and SATA Power cables to the board and the SATA drives.

**Step 5:** Replace the bottom panel and secure with the eight (8) screws you removed in Step 1.

**Step 1**: Note the location of each expansion slot. Follow standard practice for module installation.



#### 2.7.1 NVMe Module Installation

**Step 1**: Remove the three (3) screws as shown, then affix the NVMe module to the motherboard.





**Step 2**: Install the thermal pad and heatsink panel using the three (3) screws previously removed.

Chapter 2 – Hardware Information





Affix each wall mounting bracket by securing them to the chassis using the two (2) screws per bracket provided.



Affix each DIN rail bracket by securing them to the chassis using the three (3) screws per bracket provided.



# Chapter 3

AMI BIOS Setup

BOXER-6645U-RP

#### 3.1 System Test and Initialization

The system uses certain routines to perform testing and initialization. If an error, fatal or non-fatal, is encountered, a few short beeps or an error message will be outputted. The board can usually continue the boot up sequence with non-fatal errors.

The system configuration verification routines check the current system configuration against the values stored in the CMOS memory. If they do not match, an error message will be outputted, in which case you will need to run the BIOS setup program to set the configuration information in memory.

There are three situations in which you will need to change the CMOS settings:

- You are starting your system for the first time
- You have changed your system's hardware
- The CMOS memory has lost power and the configuration information is erased

The system's CMOS memory uses a backup battery for data retention, which is to be replaced once emptied.

#### 3.2 AMI BIOS Setup

The AMI BIOS ROM has a pre-installed Setup program that allows users to modify basic system configurations, which is stored in the battery-backed CMOS RAM and BIOS NVRAM so that the information is retained when the power is turned off.

To enter BIOS Setup, press <Del> or <F2> immediately while your computer is powering up.

The function for each interface can be found below.

Main – Date and time can be set here. Press <Tab> to switch between date elements

Advanced – Enable/ Disable boot option for legacy network devices

System I/O – Enable/ Disable system I/O device

Security - The setup administrator password can be set here

Boot - Enable/ Disable quiet Boot Option

Save & Exit – Save your changes and exit the program

MEBx - Intel® Management Engine BIOS Extension

## 3.3 Setup Submenu: Main

Main Advanced Chip	Aptio Setup – AMI set Security Boot Save & Exit	
== BIOS Information = BOXER-6645U-RPL F == CPU Information = Intel(R) Celeron(R) G	:= (1.0 (B645UM10)(03/29/2024) := :6900E	Set the Date. Use Tab to switch between Date elements. Default Ranges: Year: 1930–2199 Months: 1–12 Days: dependent on month
== MEM Information = Total Memory Memory Frequency	≔ 8192 MB 4800 MHz	
== SATA Information = Serial ATA Port 1 Serial ATA Port 2 mSATA Port System Date System Time Access Level	Empty Empty Empty [Tue 01/05/2021] [00:44:00] Administrator	++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit

## 3.4 Setup Submenu: Advanced

Aptio Setup – AMI Main Advanced Chipset Security Boot Save & Exit	
System Information CPU Configuration Memory Configuration PCH-FW Configuration Hardware Monitor AAEON Features Power Management AAEON BIOS Robot	CPU Configuration Parameters
	<pre>++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>
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45U-RPL

## 3.4.1 CPU Configuration

Advanced	Aptio Setup – AMI	
CPU Configuration		When enabled, a VMM can
Brand String	Intel(R) Celeron(R) G6900E	hardware capabilities provided by Vanderpool Technology.
Stepping	HO	
ID Microcodo Powicion	0x90675	
VMX	Supported	
SMX/TXT	Not Supported	
Intel (VMX) Virtualization Technology		
Intel(R) SpeedStep(tm)	[Enabled]	
C states	[Enabled]	↔: Select Screen t: Select Item
		Enter: Select
		+/−: Change Opt.
		F1: General Help
		F3: Optimized Defaults
		F4: Save & Exit
		ESC: Exit
Venci	on 2 22 1292 Conunidht (C) 2	004 ANT

Options Summary			
Intel (VMX)Virtualization	Disabled		
Technology	Enabled	Optimal Default, Failsafe Default	
When enabled, a VMM can	utilize the additional hard	lware capabilities provided by	
Vanderpool Technology.			
Hyper-Threading	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Enable or Disable Hyper-Thr	eading Technology		
Intel® SpeedStep™	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Allows more than two freque	ency ranges to be suppor	ted	
Turbo Mode	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Enable/Disable processor Turbo Mode (requires EMTTM enabled too).			
AUTO means enabled.			

Options Summary		
C states	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable/Disable CPU Power Management. Allows CPU to go to C states when it's not		
100% utilized.		

## 3.4.2 Memory Configuration

Advanced	Aptio Setup — AMI	
Advanced Memory Configuration Total Memory Memory Frequency tCL-tRCD-tRP-tRAS MC 0 Ch 0 DIMM 0 Size MC 0 Ch 1 DIMM 0 MC 1 Ch 0 DIMM 0	Aptio Setup - AMI 8192 MB 4800 HHz 40-39-39-77 Populated & Enabled 8192 MB (DDR5) Not Populated / Disabled Not Populated / Disabled	
MC 1 Ch 1 DIMM O	Not Populated / Disabled	<pre>++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>
	rsion 2.22.1293 Copyright (C) 2024	AMI

## 3.4.3 PCH-FW Configuration

Advanced	Aptio Setup – AMI	
ME Firmware Version	16.1.30.2269	Configure Management Engine Technology Parameters
▶ Firmware Update Configuration		
		++: Select Screen fl: Select Item Enter: Select +/-: Change Opt. Fl: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
Versio	n 2.22.1293 Copyright (C) 202	4 AMI

Options Summary		
AMT BIOS Features	Enabled	Optimal Default, Failsafe Default
	Disabled	
When disabled AMT BIOS Features are no longer supported and user is no longer able		
to access MEBx Setup.		

Note: This option does not disable Manageability Features in FW.

## 3.4.3.1 Firmware Update Configuration



Options Summary		
Me FW Image Re-Flash	Enabled	
	Disabled	Optimal Default, Failsafe Default
Enabled/ Disable Me FW Ir	nage Re-Flash function.	
FW Update	Enabled	
	Disabled	Optimal Default, Failsafe Default
Enabled/ Disable Me FW Update function.		

#### 3.4.4 Hardware Monitor

Advanced	Aptio Setup — AMI	
Advanced Pc Health Status CPU Temperature System Temperature 2 VCORE VMEM +5V +12V +3.3V 3VSB SVSB SVSB VRAT	Aptio Setup - AHI : +28 % : +27 % : +33 % : +0.736 V : +1.112 V : +5.087 V : +12.056 V : +3.360 V : +3.360 V : +5.064 V : +3.136 V	
		<pre>++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>

## 3.4.5 Power Management

	Antio Setup – AMI	
Advanced	hptib betup hhi	
Power Management		Select system power mode.
Power Mode Restore AC Power Loss	[ATX Type] [Last State]	
Wake Events System Wake On RTC	[Disabled]	
		++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
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Options Summary		
Power Mode	АТХ Туре	Optimal Default, Failsafe Default
	АТ Туре	
Select system power mode		
Restore AC Power Loss	Last State	Optimal Default, Failsafe Default
	Always On	
	Always Off	
Set GPI [3:0] Output as Hi or	Low	
System Wake On RTC	Disabled	Optimal Default, Failsafe Default
	By Date	
	By Weekday	
	Bypass	
By Date: System will wake on the day with hr::min::sec specified./n By Weekday: System		
will wake on the enabled weekday with hr::min::sec specified./n Bypass: BIOS will not		
control RTC wake function		

## 3.4.6 AAEON BIOS Robot

Advanced	Aptio Setup – AMI	
AAEON BIOS Robot Sends watch dog before BIOS POST POST Timer (second) Sends watch dog before booting OS OS Timer (minute) Delayed POST (PEI phase) Delayed time (second) Delayed time (second) Reset system once	[Disabled] 30 [Disabled] 3 [Disabled] 10 [Disabled] 10 [Disabled]	Enabled - Robot set Watch Dog Timer(WDT) right after power on, before BIOS start POST process. And then Robot will clear WDT on compeletion of POST. WDT will reset system automatically if it is not cleared before its timer counts down to zero.
Soft on hard reset • Device detecting configuration	[Soft reset]	<pre>++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>

Options Summary			
Sends watch dog before	Disabled	Optimal Default, Failsafe Default	
BIOS POST	Enabled		
Enabled – Robot set Watch D	Dog Timer (WDT) right af	ter power on, before BIOS start	
POST process. And then Rob	ot will clear WDT on con	npletion of POST. WDT on	
completion of POST. WDT. W	DT will reset system auto	matically if it is not cleared before	
its timer counts down to zero.			
Sends watch dog before	Disabled	Optimal Default, Failsafe Default	
booting OS	Enabled		
Enabled – Robot set Watch Dog Timer (WDT) after POST completion, before BIOS			
transfer control to OS. WARNING: Before enabling this function, a program in OS must			
be in responsible for clearing WDT. Also, this function should be disabled if OS I going			
to update itself.			
Delayed POST	Disabled	Optimal Default, Failsafe Default	
(PEI phase)	Enabled		

Options Summary				
Enabled -Robot holds BIOS from starting POST, right after power on. This allows BIOS				
POST to start with stable power or start after system is physically warmed-up.				
Note: Robot does this before 'Sends watch dog'.				
Delayed POST (DXE phase)	Disabled	Optimal Default, Failsafe Default		
	Enabled			
Enabled -Robot holds BIOS before POST completion. This allows BIOS POST to start				
with stable power or start after system is physically warmed-up.				
Note: Robot does this after 'Sends watch dog before BIOS POST'.				

## 3.4.6.1 Device Detecting Configuration

Aptio Setup - AMI Main				
Device detecting configuration Device #1 detecting configuration Device #2 detecting configuration Device #3 detecting configuration Device #4 detecting configuration Device #5 detecting configuration If any device is detected in unexper condition, the robot will do follow Action Soft or hard reset Device work	ed g [Reset System] [Soft]	Device #1 detecting configuration		
At time	[After show logo]	++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit		
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Options Summary				
Action	Reset System	Optimal Default, Failsafe Default		
	Hold System			
Select action that robot should do.				

Options Summary				
Soft or hard reset	Soft	Optimal Default, Failsafe Default		
	Hard			
Select reset type robot should send on each boot.				
Retry-Count	3	Optimal Default, Failsafe Default		
Fill retry counter here. Robot will reset system at most counter times, and then let				
system continue its POST.				
At time	After show logo	Optimal Default, Failsafe Default		
	Before show logo			
Select robot action time: After show logo -Robot will do action after logo is displayed.				
System devices are almost ready. Before show logo - Robot will do action earlier before				
logo, but some devices may not be ready.				
## 3.4.6.1.1 Device #1 Detecting Configuration

Device #1 detecting configuration       Select interface robot should use to communicate with device         Robot detects device with       [Disabled]         Interface       [Disabled]         #:: Select Screen       14: Select Item         Enter: Select       +/-: Change Opt.         F1: General Help       F2: Previous Values         F3: Optimized Defaults       F4: Save & Exit         ESC: Exit       Exit	Main	Aptio Setup - AMI	
++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit	Device #1 detecting configuration Robot detects device with Interface	[Disabled]	Select interface robot should use to communicate with device
			++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit

Options Summary		
Interface	Disabled	Optimal Default, Failsafe Default
	PCI	
	DIO	
	SMBUS	
	Legacy I/O	
	Super I/O	
	MMIO	
Select interface robot should	use to communicate wit	h device

## 3.4.6.1.2 Device #2 Detecting Configuration

Device #2 detecting configuration       Select interface robot should use to communicate with device         Robot detects device with       [Disabled]         Interface       [Disabled]         ++: Select Screen       14: Select Item         Enter: Select       +/-: Change Opt.         F1: General Help       F2: Previous Values         F3: Optimized Defaults       F4: Save & Exit         ESC: Exit	Main	Aptio Setup – AMI	
+: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit	Device #2 detecting configuration Robot detects device with Interface	on [Disabled]	Select interface robot should use to communicate with device
			<pre>++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>

Options Summary		
Interface	Disabled	Optimal Default, Failsafe Default
	PCI	
	DIO	
	SMBUS	
	Legacy I/O	
	Super I/O	
	MMIO	
Select interface robot should	d use to communicate wit	th device

## 3.4.6.1.3 Device #3 Detecting Configuration

Main	Aptio Setup – AMI	
Device #3 detecting configuration Robot detects device with Interface	[Disabled]	Select interface robot should use to communicate with device
		++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values
		F3: Optimized Defaults F4: Save & Exit ESC: Exit
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Options Summary		
Interface	Disabled	Optimal Default, Failsafe Default
	PCI	
	DIO	
	SMBUS	
	Legacy I/O	
	Super I/O	
	MMIO	
Select interface robot shoul	d use to communicate wit	th device

## 3.4.6.1.4 Device #4 Detecting Configuration

Main	Aptio Setup - AMI	
Device #4 detecting configuration Robot detects device with Interface	[Disabled]	Select interface robot should use to communicate with device
		++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
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Options Summary		
Interface	Disabled	Optimal Default, Failsafe Default
	PCI	
	DIO	
	SMBUS	
	Legacy I/O	
	Super I/O	
	MMIO	
Select interface robot should	l use to communicate wit	h device

## 3.4.6.1.5 Device #5 Detecting Configuration

Main	Aptio Setup — AMI	
Device #5 detecting configuration Robot detects device with Interface	[Disabled]	Select interface robot should use to communicate with device
		++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
Version 2	.22.1286 Copyright (C) 2022	AMI

Options Summary		
Interface	Disabled	Optimal Default, Failsafe Default
	PCI	
	DIO	
	SMBUS	
	Legacy I/O	
	Super I/O	
	MMIO	
Select interface robot sho	uld use to communicate wi	th device

## 3.5 Setup Submenu: System I/O

Aptio Setup – AMI Main Advanced <mark>Chipset</mark> Security Boot Save & Exit		
Main       Advanced       Chipset       Security       Boot       Save & Exit         System I/O       Storage Configuration         HD       Audio Configuration         Legacy Logical Devices Configuration         Serial Port Console Redirection	Storage Configuration ++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit	
Version 2.22.1293 Copyright (C) 2024 AMI		

## 3.5.1 Storage Configuration



Options Summary		
SATA Controller(s)	Enabled	Optimal Default, Failsafe Default
	Disabled	
Enable/Disable to SATA Devi	ce	
Port 1	Enabled	Optimal Default, Failsafe Default
	Disabled	
Enable or Disable SATA Port		
Port 2	Enabled	Optimal Default, Failsafe Default
	Disabled	
Enable or Disable SATA Port		
mSATA	Enabled	Optimal Default, Failsafe Default
	Disabled	
Enable or Disable SATA Port		

## 3.5.2 NVMe Configuration

Aptio Setup - AMI Chipset		
NVMe Configuration		
No NVME Device Found		
	++: Select Screen  11: Select Item	
	Enter: Select +/-: Change Opt.	
	F1: General Help F2: Previous Values	
	F3: Optimized Defaults F4: Save & Exit	
	ESC: Exit	
Version 2.22.1293 Copyright (C) 2024	AMI	

## 3.5.3 HD Audio Configuration

System I/O	Aptio Setup – AMI	
HD Audio Subsystem Configuration Set	tings	Control Detection of the
HD Audio		Disabled = HOA will be unconditionally disabled Enabled = HOA will be unconditionally enabled.
		<pre>++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>
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Options Summary		
HD Audio	Disabled	
	Enabled	Optimal Default, Failsafe Default
Control Detection of the HD-Audio device. Disabled = HDA will be unconditionally		
disabled Enabled = HDA will be unconditionally enabled.		

## 3.5.4 Legacy Logical Devices Configuration

Aptio Setup – AMI Chipset	
<ul> <li>AMI SIO Driver Version : A5.19.00</li> <li>Super IO Chip Logical Device(s) Configuration</li> <li>[*Active*] Serial Port 1</li> <li>[*Active*] Serial Port 2</li> <li>WARNING: Logical Devices state on the left side of the control, reflects the current Logical Device state. Changes made during Setup Session will be shown after you restart the system.</li> </ul>	View and Set Basic properties of the SIO Logical device. Like IO Base, IRQ Range, DMA Channel and Device Mode.
	<pre>++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>
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## 3.5.4.1 Serial Port 1

System I/O	Aptio Setup — AMI	
Serial Port 1 Configuration		UART RS232, 422, 485 selection
Use This Device	[Enabled]	
Logical Device Settings: Current : IO=3F8h; IRQ=4;		
Possible:	[Use Automatic Settings] [Decool	
WARNING: Disabling SIO Logical Devic side effects. PROCEED WITH CAUTION.	es may have unwanted	++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
Version 2	.22.1286 Copyright (C) 2022	AMI

Options Summary			
Use This Device	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Enable or Disable this Logica	l Device		
Possible:	Use Automatic Settings	Optimal Default, Failsafe Default	
	10=3F8; IRQ=4;		
	IO=2F8; IRQ=3;		
Allows the user to change the device resource settings. New settings will be reflected			
on this setup page after syste	em restarts.		
Mode	RS232	Optimal Default, Failsafe Default	
	RS422		
	RS485		
UART RS232, 422, 485, select	tion		

## 3.5.4.2 Serial Port 2

System I/O	Aptio Setup — AMI	
Serial Port 2 Configuration		Enable or Disable this Logical
Use This Device		
Logical Device Settings: Current : IO=2F8h; IRQ=3;		
Possible:	[Use Automatic Settings]	
WARNING: Disabling SIO Logical Device side effects. PROCEED WITH CAUTION.	es may have unwanted	++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
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Options Summary		
Use This Device	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable or Disable this Logica	l Device	
Possible:	Use Automatic Settings	Optimal Default, Failsafe Default
	10=2F8; IRQ=3;	
	10=3F8; IRQ=4;	
Allows the user to change the device resource settings. New settings will be reflected		
on this setup page after syste	em restarts.	
Mode	RS232	Optimal Default, Failsafe Default
	RS422	
	RS485	
UART RS232, 422, 485, select	tion	

## 3.5.5 Serial Port Console Redirection

System I/O	Aptio Setup – AMI	
COMO Console Redirection ► Console Redirection Settings COM1(Pci Bus0,Dev0,Func0) (Disabled) Console Redirection Serial Port for Out-of-Band Managemen Windows Emergency Management Services Console Redirection EMS ► Console Redirection Settings	[Disabled] Port Is Disabled ht/ s (EMS) [Disabled]	Console Redirection Enable or Disable.
		<pre>++: Select Screen 14: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>
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Options Summary			
Console Redirection	Disabled	Optimal Default, Failsafe Default	
	Enabled		
Console Redirection Enable or Disable			
Console Redirection EMS	Disabled	Optimal Default, Failsafe Default	
	Enabled		
Console Redirection Enable or Disable			

## 3.5.5.1 Console Redirection Settings (COM0)



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Options Summary		
Terminal Type	VT100	
	VT100Plus	
	VT-UTF8	
	ANSI	Optimal Default, Failsafe Default
Emulation: ANSI: Extended A	SCII char set. VT100: ASC	Ell char set.
VT100Plus: Extends VT100 to	support color, function k	eys, etc.
VT-UTF8: Uses UTF8 encodir	ng to map Unicode chars	onto 1 or more bytes.
Bits per second	9600	
	19200	
	38400	
	57600	
	115200	Optimal Default, Failsafe Default
Selects serial port transmission speed.		
The speed must be matched	l on the other side. Long	or noisy lines may require lower
speeds.		

Options Summary				
Data Bits	7			
	8	Optimal Default, Failsafe Default		
Data Bits				
Parity	None	Optimal Default, Failsafe Default		
	Even			
	Odd			
	Mark			
	Space			
A parity bit can be sent with	the data bits to detect so	ome transmission errors. Even:		
parity bit is 0 if the num of 1	s in the data bits is even.			
Odd: parity bit is 0 if num of	1's in the data bits is odd	I.		
Mark: parity bit is always 1. S	pace: Parity bit is always	0.		
Mark and Space Parity do no	ot allow for error detection	n. They can be used as an		
additional data bit.				
Stop Bits	1	Optimal Default, Failsafe Default		
	2			
Stop bits indicate the end of	a serial data packet. (A s	tart bit indicates the beginning).		
The standard setting is 1 stop	bit. Communication wit	h slow devices may require more		
than 1 stop bit.				
Flow Control	None	Optimal Default, Failsafe Default		
	Hardware RTS/CTS			
Flow control can prevent dat	a loss from buffer overflo	ow. When sending data, if the		
receiving buffers are full, a 's	top' signal can be sent to	stop the data flow. Once the		
buffers are empty, a 'start' sig	gnal can be sent to re-sta	art the flow. Hardware flow control		
uses two wires to send start/	stop signals.	1		
VT-UTF8 Combo Key	Disabled			
Support	Enabled	Optimal Default, Failsafe Default		
Enable VT-UTF8 Combinatio	n Key Support for ANSI/	VT100 terminals		
Recorder Mode	Disabled	Optimal Default, Failsafe Default		
	Enabled			
With this mode enabled only	r text will be sent. This is	to capture Terminal data.		
Resolution 100x31	Disabled	Optimal Default, Failsafe Default		
	Enabled			
Enables or disables extended terminal resolution				
Putty KeyPad	VT100	Optimal Default, Failsafe Default		
	LINUX			
	XTERMR6			
	SCO			
	ESCN			
	VT400			

Select FunctionKey and KeyPad on Putty.

## 3.5.5.2 Console Redirection Settings (Out-of-Band Mgmt Port)



Options Summary		
Out-of-Band Mgmt Port	COM0	Optimal Default, Failsafe Default
	COM1 (Pci Bus0, Dev0,	
	Func0) (Disabled)	
Microsoft Windows Emergency Management Services (EMS) allows for remote		
management of a Windows	Server OS through a seri	al port.
Terminal Type EMS	VT100	
	VT100Plus	
	VT-UTF8	Optimal Default, Failsafe Default
	ANSI	
VT-UTF8 is the preferred terminal type for out-of-band management. The next best		
choice is VT100+ and then VT100. See above, in Console Redirection Settings page, for		
more Help with Terminal Type/Emulation.		

Options Summary		
Bits per second EMS	9600	
	19200	
	57600	
	115200	Optimal Default, Failsafe Default
Selects serial port transmission speed. The speed must be matched on the other side.		
Long or noisy lines may require lower speeds.		
Flow Control EMS	None	Optimal Default, Failsafe Default
	Hardware RTS/CTS	
	Software Xon/Xoff	
Flow control can prevent data loss from buffer overflow. When sending data, if the		
receiving buffers are full, a 'stop' signal can be sent to stop the data flow. Once the		
buffers are empty, a 'start' signal can be sent to re-start the flow. Hardware flow control		

uses two wires to send start/stop signals.

## 3.6 Setup Submenu: Security

Aptio Setup – AMI Main Advanced System I/O <mark>Security</mark> Boot Save & Exit MEBx		
Password Description		Set Administrator Password
If ONLY the Administrator then this only limits accu- only asked for when enter. If ONLY the User's passwor is a power on password and boot or enter Setup. In So have Administrator rights The password length must b in the following range: Minimum length	's password is set, ess to Setup and is ing Setup. 'd is set, then this d must be entered to etup the User will pe 3	
Maximum iength	20	++: Select Screen
Administrator Password		f↓: Select Item Enter: Select
<ul> <li>Trusted Computing</li> </ul>		+/-: Change Opt.
▶ Secure Boot		F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
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### Change User/Administrator Password

You can set a User Password once an Administrator Password. The password will be required during boot up, or when the user enters the Setup utility. Please Note that a User Password does not provide access to many of the features in the Setup utility. Select the password you wish to set, press Enter to open a dialog box to enter your password (you can enter no more than six letters or numbers). Press Enter to confirm your entry, after which you will be prompted to retype your password for a final confirmation. Press Enter again after you have retyped it correctly.

#### Removing the Password

Highlight this item and type in the current password. At the next dialog box press Enter to disable password protection.

## 3.6.1 Trusted Computing

Aptio Setup – AMI Security		
TPM 2.0 Device Found Firmware Version: Vendor: Security Device Support Active PCR banks Available PCR bank SHA256 PCR Bank SHA364 PCR Bank Pending operation Platform Hierarchy Storage Hierarchy Endorsement Hierarchy Physical Presence Spec Version TPM 2.0 InterfaceType Device Select	7.2 NTC Enable] SHA256 SHA256,SHA384 [Enabled] [Disabled] [Enabled] [Enabled] [Enabled] [1.3] [TIS] [Auto]	Enables or Disables BIOS support for security device. O.S. will not show Security Device. TCG EFI protocol and INT1A interface will not be available. ++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
Version	2 22 1286 Conuright (C) 202	2 AMT

Options Summary		
Security Device Support	Enable	Optimal Default, Failsafe Default
	Disable	
Enables or Disables BIOS sup	port for security device.	O.S. will not show Security Device.
TCG EFI protocol and INT1A	interface will not be avail	able.
SHA256 PCR Bank	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable or Disable SHA256 P	CR Bank	
SHA384 PCR Bank	Disabled	Optimal Default, Failsafe Default
	Enabled	
Enable or Disable SHA384 PCR Bank		
Pending operation	None	Optimal Default, Failsafe Default
	TPM Clear	
Schedule an Operation for the Security Device.		
NOTE: Your Computer will re	boot during restart in or	der to change State of Security
Device		

Options Summary			
Platform Hierarchy	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Enable or Disable Platform H	Enable or Disable Platform Hierarchy		
Storage Hierarchy	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Enable or Disable Storage H	ierarchy		
Endorsement Hierarchy	Disabled		
	Enabled	Optimal Default, Failsafe Default	
Enable or Disable Endorsement Hierarchy			
Physical Presence Spec	1.2		
Version	1.3	Optimal Default, Failsafe Default	
Select to Tell O.S. to support	PPI Spec Version 1.2 or 1.	.3. Note some HCK tests might not	
support 1.3.			
Device Select	TPM 1.2		
	TPM 2.0		
	Auto	Optimal Default, Failsafe Default	
TPM 1.2 will restrict support to TPM 1.2 devices.			
TPM 2.0 will restrict support to TPM 2.0 devices.			
Auto will support both with the default set to TPM 2.0 devices if not found.			

TPM 1.2 devices will be enumerated

## 3.6.2 Secure Boot



Options Summary		
Secure Boot	Disabled	Optimal Default, Failsafe Default
	Enabled	
Secure Boot feature is Active	if Secure Boot is Enabled	I, Platform Key (PK) is enrolled and
the System is in User mode.	The mode change requir	es platform reset
Secure Boot Mode	Standard	
	Custom	Optimal Default, Failsafe Default
Secure Boot mode options: S	Custom Standard or Custom. In C	Optimal Default, Failsafe Default ustom mode, Secure Boot Policy
Secure Boot mode options: S variables can be configured I	Custom Standard or Custom. In C by a physically present us	Optimal Default, Failsafe Default ustom mode, Secure Boot Policy ser without full authentication
Secure Boot mode options: S variables can be configured I Restore Factory Keys	Custom Standard or Custom. In C by a physically present us Yes	Optimal Default, Failsafe Default ustom mode, Secure Boot Policy ser without full authentication
Secure Boot mode options: S variables can be configured I Restore Factory Keys	Custom itandard or Custom. In C by a physically present us Yes No	Optimal Default, Failsafe Default ustom mode, Secure Boot Policy ser without full authentication

## 3.6.2.1 Key Management



Options Summary		
Factory Key Provision	Disabled	Optimal Default, Failsafe Default
	Enabled	
Install factory default Secure	Boot keys after the platfo	orm reset and while the System is
in Setup mode		
Restore Factory Keys	Yes	
	No	
Force System to User Mode.	Install factory default Sec	cure Boot key databases
Enroll Efi Image		
Allow Efi image to run in Secure Boot mode. Enroll SHA256 Hash certificate of a PE		
image into Authorized Signature Database (db)		
Platform Key (PK)	Update	
Key Exchange Keys (KEK)	Update	
	Append	
Authorized Signatures (db)	Update	
	Append	

Options Summary		
Forbidden Signatures (dbx)	Update	
	Append	
Authorized TimeStamps	Update	
(dbt)	Append	
OsRecovery Signatures	Update	
(dbr)	Append	
Enroll Factory Defaults or loa	ad certificates from a file:	1. Public Key Certificate:
a) EFI_SIGNATURE_LIST		
b) EFI_CERT_X509 (DER)		
c) EFI_CERT_RSA2048 (bin)		
d) EFI_CERT_SHAXXX		
2. Authenticated UEFI Variable 3.EFI PE/COFF Image (SHA256)		
Kay Source: Factory External Mixed		
Ney Source. Factory, External, Ivilxed		

## 3.7 Setup Submenu: Boot

Boot Configuration	Enables or disables Quiet Boot
Quiet Boot [Enabled] Network Stack [Disabled]	0,000
FIXED BOOT ORDER Priorities	
Boot Option #1 [Hard Disk] Boot Option #2 [NVME] Boot Option #3 [USB Device:UEFI: KingstonDataTraveler 3.0PMAP, Partition 1]	
Boot uption #4 [Network] ▶ UEFI USB Drive BBS Priorities	<pre>++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>

Options Summary		
Quiet Boot	Disabled	
	Enabled	Default
Enables/disables Quiet Boot	option.	
Network Stack	Disabled	Default
	Enabled	
Enable/Disable UEFI Network Stack.		
Boot Option #1	Hard Disk	
Boot Option #2	NVME	
Boot Option #3	USB Device	
Boot Option #4	Network	
Sets the system boot order		

## 3.7.1 UEFI BBS Priorities

	Aptio Setup - AMI Boot	
Boot Option #1	[UEFI: Generic Flash Disk 8.07, Partition 1]	Sets the system boot order
		<pre>H: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save &amp; Exit ESC: Exit</pre>

Options Summary		
Quiet Boot	Disabled	
	Enabled	Default
Enables/disables Quiet Boot	option.	
Network Stack	Disabled	Default
	Enabled	
Enable/Disable UEFI Network Stack.		
Boot Option #1	Hard Disk	
Boot Option #2	NVME	
Boot Option #3	USB Device	
Boot Option #4	Network	
Sets the system boot order		

## 3.8 Setup Submenu: Save & Exit

Aptio Setup – AMI Main Advanced Chipset Security Boot <mark>Save &amp; Exit</mark>	
Save Options Save Changes and Reset Discard Changes and Exit Default Options Restore Defaults	Reset the system after saving the changes.
	++: Select Screen 11: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F3: Optimized Defaults F4: Save & Exit ESC: Exit
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## Chapter 4

Drivers Installation

## 4.1 Drivers Download and Installation

Drivers for the BOXER-6645U-RPL can be downloaded from the product page on the AAEON website:

https://www.aaeon.com/en/

# Appendix A

I/O Information

## A.1 I/O Address Map

## V 🛃 DESKTOP-QBP7RPH

Input/output (IO)	

to [000000000000000 - 000000000000CF7] PCI Express Root Complex	
to 1000000000000000000000000000000000000	er
to 1000000000000000024 - 0000000000000000000	er
to 1000000000000000028 - 0000000000000000000	er
ta [00000000000002C - 000000000000002D] Programmable interrupt controll	er
ta [00000000000002E - 00000000000002F] Motherboard resources	
ta [00000000000000000 - 00000000000000000	er
🚛 [000000000000034 - 000000000000035] Programmable interrupt controlle	er
ta [000000000000038 - 0000000000000000000000	er
ta [00000000000003C - 0000000000000000] Programmable interrupt controll	er
timer [000000000000040 - 00000000000000043] System timer	
늘 [00000000000004E - 0000000000004F] Motherboard resources	
timer [000000000000000 - 0000000000000000000	
늘 [000000000000061 - 000000000000061] Motherboard resources	
to the resources [00000000000000000000000000000000] [10000000000	
to the resources [000000000000000000000000000000000000	
to the resources [0000000000007 - 0000000000000000] Motherboard resources	
to the resources [00000000000070 - 000000000000000] Motherboard resources	
to the resources [000000000000000000000000000000] [10000000000	
to the resources [0000000000002] [0000000000000000000000	
to an anticological anticologi	er
E [0000000000000004 - 0000000000000000000	er
E [0000000000000A8 - 0000000000000000000000	er
E [0000000000000AC - 0000000000000AD] Programmable interrupt control	ler
to 1000000000000000000000000000000000000	er
[0000000000000082 - 0000000000083] Motherboard resources	
to 1000000000000000000000000000000000000	er
E [000000000000088 - 00000000000089] Programmable interrupt controlle	er
to an anticological anticologi	ler
[0000000000002F8 - 000000000002FF] Communications Port (COM2)	
[0000000000003F8 - 000000000003FF] Communications Port (COM1)	
to 1000000000000000000000000000000000000	er

terr [0000000000004D0 - 0000000000004D1] Programmable interr	upt controller
ta [000000000000680 - 0000000000069F] Motherboard resource	25
Tan [000000000000000 - 0000000000000000000	es
tesource [0000000000000000 - 000000000000000000	es
ta [000000000000000000000000000000000000	es
to 10000000000000000 - 000000000000000000	nplex
tan [00000000000164E - 00000000000164F] Motherboard resource	es
tesource [000000000001854 - 000000000001857] Motherboard resource	25
Tap [000000000000000 - 0000000000000000000	2S
[00000000000000000 - 00000000000000303F] Intel(R) UHD Graphics	710
a [0000000000003060 - 00000000000307F] Standard SATA AHCI C	ontroller
💼 [000000000003080 - 00000000003083] Standard SATA AHCI C	Controller
a [0000000000003090 - 000000000003097] Standard SATA AHCI C	Controller
T0000000000000000000000000000000000000	3

## A.2 Memory Address Map

	DESKTOP-QBP7RPH
>	Input/output (IO)
>	Interrupt request (IRQ)
~	Large Memory
	to 000000400000000 - 0000007FFFFFFFF PCI Express Root Complex
¥	Memory
	time [000000000000000 - 0000000000000000000
	🖵 [000000080400000 - 0000000804FFFFF] Intel(R) Ethernet Controller I226-LM
	🏣 [000000080400000 - 0000000805FFFFF] Intel(R) PCI Express Root Port #4 - 7ABB
	time [000000080400000 - 00000000BFFFFFF] PCI Express Root Complex
	🚽 [000000080500000 - 000000080503FFF] Intel(R) Ethernet Controller I226-LM
	ma [0000000080620000 - 000000080621FFF] Standard SATA AHCI Controller
	📹 [000000080622000 - 0000000806227FF] Standard SATA AHCI Controller
	ma [000000080623000 - 0000000806230FF] Standard SATA AHCI Controller
	[00000000BFFE0000 - 00000000BFFFFFF] Intel(R) Ethernet Connection (17) 1219-LM
	E [00000000C0000000 - 00000000CFFFFFF] Motherboard resources
	🏣 [00000000FE010000 - 00000000FE010FFF] Intel(R) SPI (flash) Controller - 7AA4
	The construction of the construction of the construction and the construction and the construction of the
	te [00000000FED20000 - 00000000FED7FFF] Motherboard resources
	[00000000FED40000 - 00000000FED44FFF] Trusted Platform Module 2.0
	E [00000000FED45000 - 00000000FED8FFF] Motherboard resources
	Tea [00000000FED90000 - 00000000FED93FFF] Motherboard resources
	time [00000000FEDA0000 - 00000000FEDA0FFF] Motherboard resources
	E [00000000FEDA1000 - 00000000FEDA1FFF] Motherboard resources
	E [00000000FEDC0000 - 00000000FEDC7FFF] Motherboard resources
	E [00000000FEE00000 - 00000000FEEFFFF] Motherboard resources
	🙀 [000000400000000 - 000000400FFFFFF] Intel(R) UHD Graphics 710
	[000000600000000 - 0000006000FFFFF] Intel(R) UHD Graphics 710
	[0000006001100000 - 000000600110FFFF] Intel(R) USB 3.20 eXtensible Host Controller - 1.20 (Microsoft)
	🏣 [0000006001118000 - 00000060011180FF] Intel(R) SMBus - 7AA3
	🏣 [0000007FFFEFB000 - 0000007FFFEFBFFF] Intel(R) Management Engine Interface #1
	는 [0000007FFFEFC000 - 0000007FFFEFFFFF] Intel® Smart Sound Technology BUS
	to [0000007FFFF00000 - 0000007FFFFFFFF] Intel® Smart Sound Technology BUS

#### **IRQ Mapping Chart** A.3

- A DESKTOP-QBP7RPH V
  - Input/output (IO) >
  - ✓ Interrupt request (IRQ)
    - timer (ISA) 0x00000000 (00) System timer
    - (ISA) 0x00000003 (03) Communications Port (COM2)

- (ISA) 0x00000004 (04) Communications Port (COM1)