

# PICO-APL1

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PICO-ITX Board

User's Manual 3<sup>rd</sup> Ed

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## Packing List

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Before setting up your product, please make sure the following items have been shipped:

Item	Quantity
● PICO-APL1	1
● Product DVD with drivers	1
● Heat Spreader (optional)	1
● COM + Line-out Cable (optional)	1

If any of these items are missing or damaged, please contact your distributor or sales representative immediately.

## About this Document

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This User's Manual contains all the essential information, such as detailed descriptions and explanations on the product's hardware and software features (if any), its specifications, dimensions, jumper/connector settings/definitions, and driver installation instructions (if any), to facilitate users in setting up their product.

Users may refer to the [AAEON.com](http://AAEON.com) for the latest version of this document.

## Safety Precautions

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Please read the following safety instructions carefully. It is advised that you keep this manual for future references

1. All cautions and warnings on the device should be noted.
2. Make sure the power source matches the power rating of the device.
3. Position the power cord so that people cannot step on it. Do not place anything over the power cord.
4. Always completely disconnect the power before working on the system's hardware.
5. No connections should be made when the system is powered as a sudden rush of power may damage sensitive electronic components.
6. If the device is not to be used for a long time, disconnect it from the power supply to avoid damage by transient over-voltage.
7. Always disconnect this device from any AC supply before cleaning.
8. While cleaning, use a damp cloth instead of liquid or spray detergents.
9. Make sure the device is installed near a power outlet and is easily accessible.
10. Keep this device away from humidity.
11. Place the device on a solid surface during installation to prevent falls
12. Do not cover the openings on the device to ensure optimal heat dissipation.
13. Watch out for high temperatures when the system is running.
14. Do not touch the heat sink or heat spreader when the system is running
15. Never pour any liquid into the openings. This could cause fire or electric shock.
16. As most electronic components are sensitive to static electrical charge, be sure to ground yourself to prevent static charge when installing the internal components. Use a grounding wrist strap and contain all electronic components in any static-shielded containers.

17. If any of the following situations arises, please contact our service personnel:
  - i. Damaged power cord or plug
  - ii. Liquid intrusion to the device
  - iii. Exposure to moisture
  - iv. Device is not working as expected or in a manner as described in this manual
  - v. The device is dropped or damaged
  - vi. Any obvious signs of damage displayed on the device
18. **DO NOT LEAVE THIS DEVICE IN AN UNCONTROLLED ENVIRONMENT WHERE THE STORAGE TEMPERATURE IS BELOW -20° C (-4°F) OR ABOVE 60°C (140°F) TO PREVENT DAMAGE.**

### **Warning!**



This device complies with Part 15 FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received including interference that may cause undesired operation.

### **Caution:**

*There is a danger of explosion if the battery is incorrectly replaced. Replace only with the same or equivalent type recommended by the manufacturer. Dispose of used batteries according to the manufacturer's instructions and your local government's recycling or disposal directives.*

### **Attention:**

*Il y a un risque d'explosion si la batterie est remplacée de façon incorrecte. Ne la remplacer qu'avec le même modèle ou équivalent recommandé par le constructeur. Recycler les batteries usées en accord avec les instructions du fabricant et les directives gouvernementales de recyclage.*



## China RoHS Requirements (CN)

产品中有毒有害物质或元素名称及含量

AAEON Main Board/ Daughter Board/ Backplane

部件名称	有毒有害物质或元素					
	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴联苯 (PBB)	多溴二苯醚 (PBDE)
印刷电路板 及其电子组件	○	○	○	○	○	○
外部信号 连接器及线材	○	○	○	○	○	○
<p>O: 表示该有毒有害物质在该部件所有均质材料中的含量均在 SJ/T 11363-2006 标准规定的限量要求以下。</p> <p>X: 表示该有毒有害物质至少在该部件的某一均质材料中的含量超出 SJ/T 11363-2006 标准规定的限量要求。</p> <p>备注: 此产品所标示之环保使用期限, 系指在一般正常使用状况下。</p>						

## China RoHS Requirement (EN)

Poisonous or Hazardous Substances or Elements in Products

AAEON Main Board/ Daughter Board/ Backplane

Component	Poisonous or Hazardous Substances or Elements					
	Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Hexavalent Chromium (Cr(VI))	Polybrominated Biphenyls (PBB)	Polybrominated Diphenyl Ethers (PBDE)
PCB & Other Components	○	○	○	○	○	○
Wires & Connectors for External Connections	○	○	○	○	○	○
<p>O: The quantity of poisonous or hazardous substances or elements found in each of the component's parts is below the SJ/T 11363-2006-stipulated requirement.</p> <p>X: The quantity of poisonous or hazardous substances or elements found in at least one of the component's parts is beyond the SJ/T 11363-2006-stipulated requirement.</p> <p><b>Note:</b> The Environment Friendly Use Period as labeled on this product is applicable under normal usage only</p>						

# Table of Contents

---

<b>Chapter 1 - Product Specifications</b> .....	<b>1</b>
1.1 Specifications .....	2
<b>Chapter 2 – Hardware Information</b> .....	<b>4</b>
2.1 Dimensions .....	5
2.2 Jumpers and Connectors.....	8
2.3 List of Jumpers .....	10
2.3.1 Clear CMOS Jumper (JP1 1, 3, 5).....	11
2.3.2 Auto Power Button Enable/Disable Selection (JP1 2, 4, 6).....	11
2.3.3 LVDS Port Operating Voltage Selection (JP2 1,3,5) .....	11
2.3.4 LVDS Port Backlight Inverter Voltage Selection Selection (JP2 2,4,6)	11
2.3.5 LVDS Port Backlight Lightness Control Mode (JP3) .....	12
2.4 List of Connectors.....	12
2.4.1 Digital IO Port (CN1).....	14
2.4.2 LVDS Port Inverter / Backlight Connector (CN2).....	14
2.4.3 Front Panel (CN3).....	15
2.4.4 Mini-Card Slot (Half-Mini Card) (CN4) .....	16
2.4.5 BIO connector (CN7) .....	18
2.4.6 SATA Port (CN8).....	20
2.4.7 Battery (CN9) .....	21
2.4.8 LAN (RJ-45) Port (CN10).....	21
2.4.9 USB3.0 Ports 0 and 1 (CN11).....	22
2.4.10 +5V Output for SATA HDD (CN12).....	23
2.4.11 HDMI Port (CN13).....	24
2.4.12 External +12V Input (CN14).....	25
2.4.13 DDR3L SO-DIMM Slot (CN15) .....	25

2.4.14	LVDS Port (CN16).....	25
2.4.15	COM Port 1/2 & line out connector (CN17).....	27
2.4.16	COM port2 RS-485.....	28
2.4.17	COM port2 RS-422.....	29
2.4.18	LPC port2 (CN18) .....	29
2.4.19	USB 2.0 Port 1 (CN19) .....	30
2.4.20	Specifications for I/O Port .....	31
2.4.21	Function Block .....	33
<b>Chapter 3 - AMI BIOS Setup .....</b>		<b>34</b>
3.1	System Test and Initialization .....	35
3.2	AMI BIOS Setup .....	36
3.3	Setup Submenu: Main .....	37
3.4	Setup Submenu: Advanced.....	38
3.4.1	CPU configuration .....	40
3.4.2	SATA Configuration.....	41
3.4.3	Hardware Monitor.....	42
3.4.4	SIO Configuration .....	43
3.4.4.1	Serial Port Configuration.....	44
3.4.5	Dio Configuration.....	44
3.4.6	Power Management .....	46
3.4.7	Setup submenu: Chipset.....	47
3.4.8	North Bridge .....	48
3.5	LVDS Panel Configuration.....	49
3.5.1	South Bridge.....	52
3.5.1.1	Setup submenu: Security .....	52
3.5.2	Setup submenu: Boot.....	54
3.6	Setup submenu: Exit .....	55
<b>Chapter 4 – Drivers Installation.....</b>		<b>56</b>

4.1	Product CD/DVD .....	57
<b>Appendix A - Watchdog Timer Programming.....</b>		<b>59</b>
A.1	Watchdog Timer Registers .....	60
A.2	Watchdog Sample Program.....	61
<b>Appendix B - I/O Information .....</b>		<b>64</b>
B.1	I/O Address Map .....	65
B.2	Memory Address Map .....	66
B.3	IRQ Mapping Chart.....	67
<b>Appendix C – Mating Connectors .....</b>		<b>68</b>
C.1	List of Mating Connectors and Cables.....	69
<b>Appendix D – DIO .....</b>		<b>72</b>
D.1	DIO .....	73
<b>Appendix E – PICO-APL1-SEMI Quick Installation Guide.....</b>		<b>78</b>
E.1	Packing List .....	79
E.2	Assembly procedure.....	81
<b>Appendix F – PICO-APL1 AI Core Kit Installation Guide .....</b>		<b>87</b>
F.1	Product Brief.....	88
F.2	Update Ubuntu and Kernel .....	89
F.3	Install NCSDK.....	92
F.4	Download Movidius Ncappzoo.....	95
F.5	Example in Movidius Ncappzoo.....	99
F.6	Appendix.....	101

# Chapter 1

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Product Specifications

## 1.1 Specifications

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### System

● Form Factor	PICO-APL1
● Processor	Intel® Pentium Processor N4200 Intel® Celeron Processor N3350
● System Memory	204-pin DDR3L SODIMM x 1, DDR3L 1867MHz, Max. 8GB
● Chipset	Intel® Pentium N4200/Celeron N3350 integrated
● BIOS	AMI / SPI
● Wake On LAN	Yes
● Watchdog Timer	255 levels
● Power Requirement	DC 12 V
● Power Supply Type	AT/ATX (default). lockable connector optional
● System Cooling	Head spreader & Heatsink (optional)
● Board Size	100 x 72 mm (3.94 x 2.84")
● Gross Weight	200 g (0.44 .lb)
● Operating Temperature	0 ~ 60°C (32 ~ 140°F )
● Storage Temperature	-40 ~ 80°C (-40 ~176°F)
● Operation Humidity	0 ~ 90% relative humidity, non-condensing

### Display

- **Chipset** Intel® Pentium N4200/Celeron N3350 integrated graphic
- **Resolution** LVDS (18/24bit 2CH) 1920 x 1200  
HDMI up to 3840 x 2160  
DDI (BIO)
- **LCD Interface** LVDS (18/24bit) up to 1920 x1200@ 60Hz (optional)

## I/O

- **Storage** SATA 6.0Gb/s x 1,  
mSATA(Default)/MiniCard x 1
- **Ethernet** Intel® Gigabit Ethernet i210AT,  
10/100/1000Base-TX, RJ-45 x 1
- **USB** USB 3.0 x 2, USB 2.0 x 1
- **Serial Port** RS-232 x 1  
RS-232/422/485 x 1 (Ring / +5V / +12V)
- **Audio** Line-out x 1
- **DI/O** 4-bit programmable (2-in/ 2-out)
- **Expansion Slot** Mini Card(Half-size) x 1,  
BIO x 1, (Optional)  
I2C x 1 or Smbus x 1



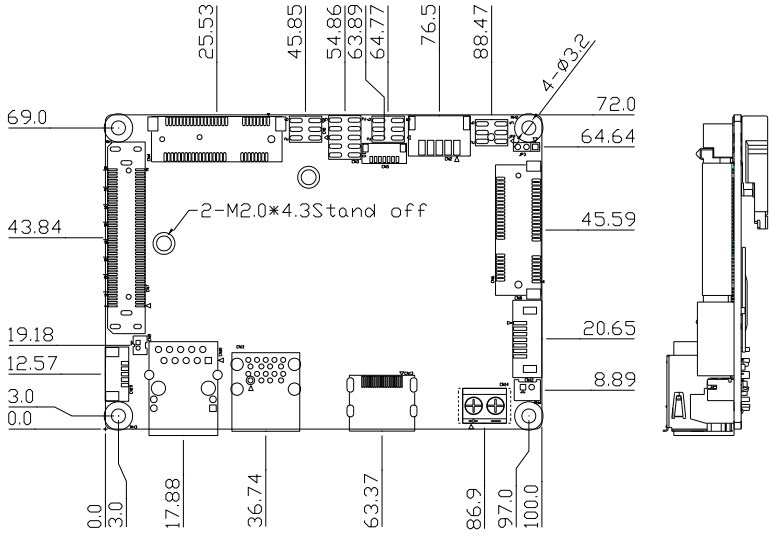
# Chapter 2

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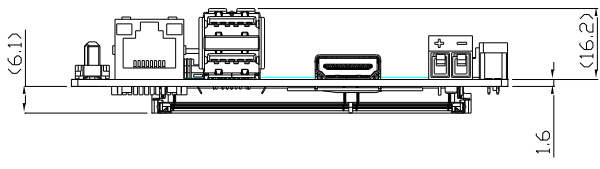
Hardware Information

## 2.1 Dimensions

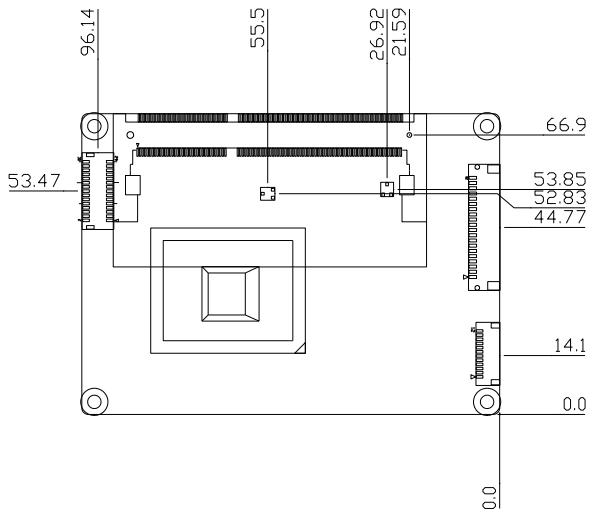
### Component Side



### Component Side

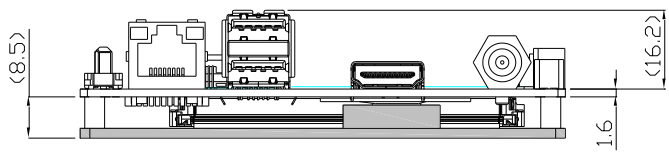
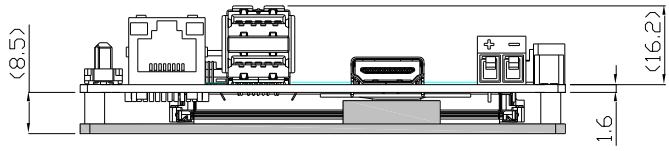
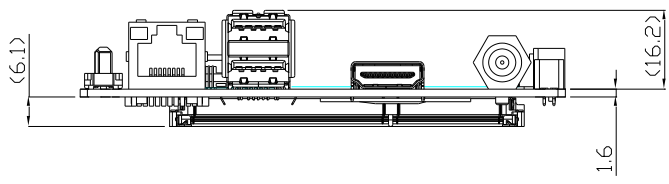
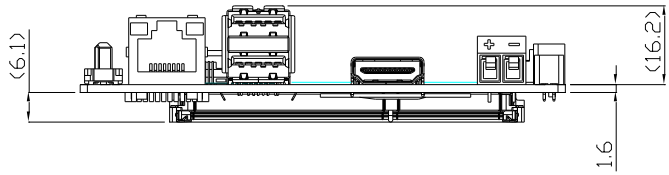


### Solder Side



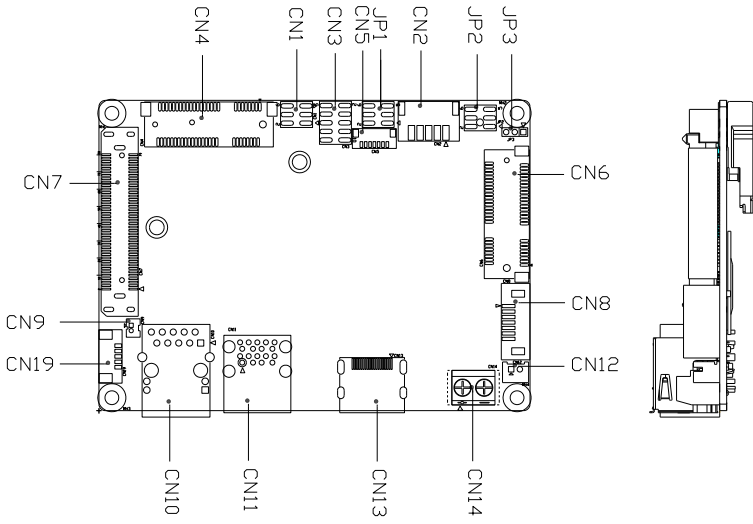
### Solder Side

### Rear I/O Configuration

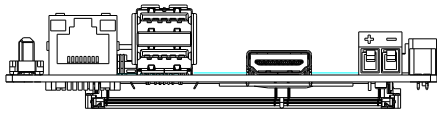


## 2.2 Jumpers and Connectors

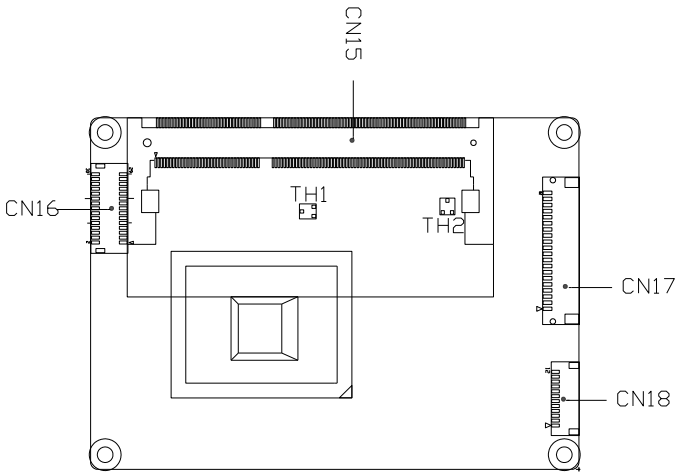
### Component Side



### Component Side



### Solder Side



### Solder Side

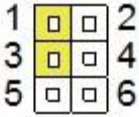
## 2.3 List of Jumpers

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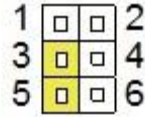
Please refer to the table below for all of the board's jumpers that you can configure for your application

Label	Function
JP1(1,3,5)	Clear CMOS Jumper
JP1(2,4,6)	Auto Power Button Enable/Disable Selection
JP2(1,3,5)	LVDS Port Operating Voltage Selection
JP2(2,4,6)	LVDS Port Backlight Inverter Voltage Selection
JP3	LVDS Port Backlight Lightness Control Mode Selection

### 2.3.1 Clear CMOS Jumper (JP1 1, 3, 5)

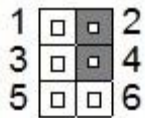


Normal (Default)

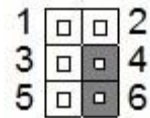


Clear CMOS

### 2.3.2 Auto Power Button Enable/Disable Selection (JP1 2, 4, 6)

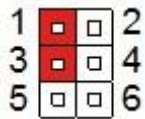


Enable (Default)

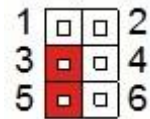


Disable

### 2.3.3 LVDS Port Operating Voltage Selection (JP2 1,3,5)

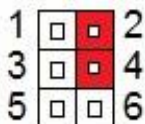


+5V

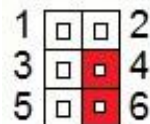


+3.3V (Default)

### 2.3.4 LVDS Port Backlight Inverter Voltage Selection Selection (JP2 2,4,6)



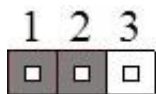
+12V



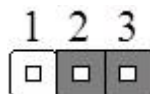
+5V (Default)



### 2.3.5 LVDS Port Backlight Lightness Control Mode (JP3)



VR Mode (Default)



PWM Mode

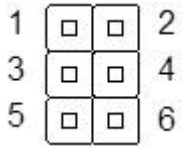
## 2.4 List of Connectors

Please refer to the table below for all of the board's connectors that you can configure for your application

Label	Function
CN1	Digital IO Port
CN2	LVDS Port Inverter / Backlight Connector
CN3	Front Panel
CN4	Mini-Card Slot (Half-Mini Card)
CN5	SPI Programming Header
CN6	Mini-Card Slot (Full-Mini Card)/mSATA (By BOM)
CN7	BIO connector
CN8	SATA Port
CN9	Battery
CN10	LAN (RJ-45) Port
CN11	USB 3.0 Port 1,2
CN12	+5V Output for SATA HDD
CN13	HDMI port
CN14	External +12V Input
CN15	DDR3L SO-DIMM Slot
CN16	LVDS Port

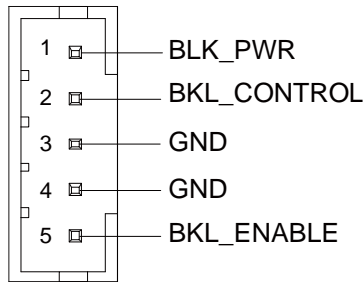
CN17	COM Port 1/2 & line out connector
CN18	LPC Port
CN19	USB 2.0 Port 1

### 2.4.1 Digital IO Port (CN1)



Pin	Pin Name	Signal Type	Pin Name
1	+5V	PWR	+5V
2	DIO0	I/O	+5V
3	DIO1	I/O	+5V
4	DIO2	I/O	+5V
5	DIO3	I/O	+5V
6	GND	GND	

### 2.4.2 LVDS Port Inverter / Backlight Connector (CN2)



Pin	Pin Name	Signal Type	Signal level
1	BKL_PWR	PWR	+5V / +12V

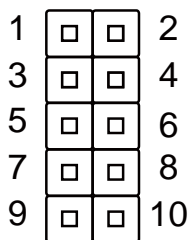
Pin	Pin Name	Signal Type	Signal level
2	BKL_CONTROL	OUT	
3	GND	GND	
4	GND	GND	
5	BKL_ENABLE	OUT	+3.3V

※ LVDS/BKL\_PWR can be set to +5V or +12V by JP2.

※ LVDS/BKL\_CONTROL can be set by JP3.

※ The driving current supports up to 2A.

### 2.4.3 Front Panel (CN3)



Pin	Pin Name	Pin	Pin Name
1	PWR_BTN-	2	PWR_BTN+
3	HDD_LED-	4	HDD_LED+
5	SPEAKER-	6	SPEAKER+
7	PWR_LED-	8	PWR_LED+
9	H/W RESET-	10	H/W RESET+

## 2.4.4 Mini-Card Slot (Half-Mini Card) (CN4)

Pin	Pin Name	Signal Type	Signal Level
1	PCIE_WAKE#	IN	
2	+3.3VSB	PWR	+3.3V
3	NC		
4	GND	GND	
5	NC		
6	+1.5V	PWR	+1.5V
7	PCIE_CLK_REQ#	IN	
8	NC	PWR	
9	GND	GND	
10	NC	I/O	
11	PCIE_REF_CLK-	DIFF	
12	NC	IN	
13	PCIE_REF_CLK+	DIFF	
14	NC		
15	GND	GND	
16	NC	PWR	
17	NC		
18	GND	GND	
19	NC		

20	W_DISABLE#	OUT	+3.3V
21	GND	GND	
22	PCIE_RST#	OUT	+3.3V
23	PCIE_RX-	DIFF	
24	+3.3VSB	PWR	+3.3V
25	PCIE_RX+	DIFF	
26	GND	GND	
27	GND	GND	
28	+1.5V	PWR	+1.5V
29	GND	GND	
30	SMB_CLK	I/O	+3.3V
31	PCIE_TX-	DIFF	
32	SMB_DATA	I/O	+3.3V
33	PCIE_TX+	DIFF	
34	GND	GND	
35	GND	GND	
36	USB_D-	DIFF	
37	GND	GND	
38	USB_D+	DIFF	
39	+3.3VSB	PWR	+3.3V
40	GND	GND	

41	+3.3VSB	PWR	+3.3V
42	NC		
43	GND	GND	
44	NC		
45	NC		
46	NC		
47	NC		
48	+1.5V	PWR	+1.5V
49	NC		
50	GND	GND	
51	NC		
52	+3.3VSB	PWR	+3.3V

### 2.4.5 BIO connector (CN7)

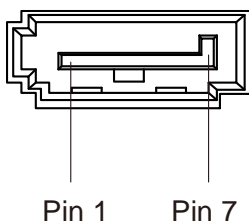
Pin	Pin Name	Pin	Pin Name
1	+12VSB	2	GND
3	GND	4	PCIE_TXN0
5	PCIE_RXN0	6	PCIE_TXP0
7	PCIE_RXP0	8	GND
9	GND	10	PCIE_TXN4
11	PCIE_RXN4	12	PCIE_TXP4

Pin	Pin Name	Pin	Pin Name
13	PCIE_RXP4	14	GND
15	GND	16	PS_ON#
17	DDIO_DDCCLK_3P3	18	DDIO_DDCDATA_3P3
19	+5VSB	20	+5VSB
21	+5VSB	22	+5VSB
23	PCIE_REF_CLK0	24	RESET#
25	PCIE_REF_CLK0#	26	GND
27	GND	28	DDIO_TXN1
29	DDIO_TXN0	30	DDIO_TXP1
31	DDIO_TXP0	32	GND
33	GND	34	DDIO_TXN3
35	DDIO_TXN2	36	DDIO_TXP3
37	DDIO_TXP2	38	GND
39	GND	40	BIO_DDIO_HPD
41	DDIO_AUXN	42	GND
43	DDIO_AUXP	44	USB3_TX2_N
45	GND	46	USB3_TX2_P
47	USBN4	48	GND
49	USBP4	50	USB3_RX2_N
51	GND	52	USB3_RX2_P



Pin	Pin Name	Pin	Pin Name
53	SMB_CLK	54	GND
55	SMB_DATA	56	WAKE#
57	GND	58	USB_OC0#
59	+5V	60	USB_OC1#
61	+5V	62	+5V
63	+5V	64	+5V
65	LPC_AD0	66	LPC_FRAME#
67	LPC_AD1	68	SERIRQ
69	LPC_AD2	70	LPC_DRQ
71	LPC_AD3	72	GPIO0/BIO-POWEROK
73	GND	74	AGND
75	LPC_CLK	76	AUD_LINEOUT_L
77	PME#	78	AUD_LINEOUT_R
79	GND	80	GND

## 2.4.6 SATA Port (CN8)

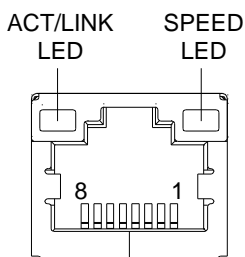


Pin	Pin Name	Signal Type	Signal Level
1	GND	GND	
2	SATA_TX1+	DIFF	
3	SATA_TX1-	DIFF	
4	GND	GND	
5	SATA_RX1-	DIFF	
6	SATA_RX1+	DIFF	
7	GND	GND	

### 2.4.7 Battery (CN9)

Pin	Pin Name	Signal Type	Signal Level
1	+3.3V	PWR	3.3V
2	GND	GND	

### 2.4.8 LAN (RJ-45) Port (CN10)



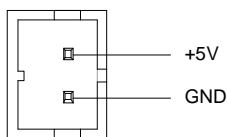
Pin	Pin Name	Signal Type	Signal Level
1	MDI0+	DIFF	
2	MDI0-	DIFF	
3	MDI1+	DIFF	
4	MDI2+	DIFF	
5	MDI2-	DIFF	
6	MDI1-	DIFF	
7	MDI3+	DIFF	
8	MDI3-	DIFF	

#### 2.4.9 USB3.0 Ports 0 and 1 (CN11)

Pin	Pin Name	Signal Type	Signal Level
1	+5VSB	PWR	+5V
2	USB0_D-	DIFF	
3	USB0_D+	DIFF	
4	GND	GND	
5	USB0_SSRX-	DIFF	
6	USB0_SSRX+	DIFF	
7	GND	GND	
8	USB0_SSTX-	DIFF	
9	USB0_SSTX+	DIFF	
10	+5VSB	PWR	+5V

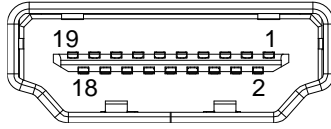
11	USB1_D-	DIFF
12	USB1_D+	DIFF
13	GND	GND
14	USB1_SSRX-	DIFF
15	USB1_SSRX+	DIFF
16	GND	GND
17	USB1_SSTX-	DIFF
18	USB1_SSTX+	DIFF

### 2.4.10+5V Output for SATA HDD (CN12)



Pin	Pin Name	Signal Type	Signal Level
1	+5V	PWR	+5V
2	GND	GND	

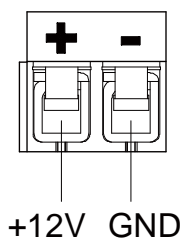
## 2.4.11 HDMI Port (CN13)



Pin	Pin Name	Signal Type	Signal level
1	TMDS_DAT2+	DIFF	
2	GND	GND	
3	TMDS_DAT2-	DIFF	
4	TMDS_DAT1+	DIFF	
5	GND	GND	
6	TMDS_DAT1-	DIFF	
7	TMDS_DAT0+	DIFF	
8	GND	GND	
9	TMDS_DAT0-	DIFF	
10	TMDS_CLK+	DIFF	
11	GND	GND	
12	TMDS_CLK-	DIFF	
13	NC		
14	NC		
15	DDC_CLK	I/O	+5V

Pin	Pin Name	Signal Type	Signal level
16	DDC_DATA	I/O	+5V
17	GND	GND	
18	+5V	I/O	+5V
19	HPLG_DETECT	IN	

#### 2.4.12 External +12V Input (CN14)



Pin	Pin Name	Signal Type	Signal Level
1	+121V	PWR	+12V
2	GND	GND	

#### 2.4.13 DDR3L SO-DIMM Slot (CN15)

Standard specification

#### 2.4.14 LVDS Port (CN16)

※ LVDS LCD\_PWR can be set to +3.3V or +5V by JP2

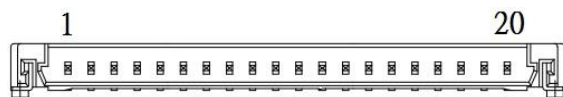
※ The max. driving current is 2A.

Pin	Pin Name	Signal Type	Signal Level
1	BKL_ENABLE	OUT	

2	BKL_CONTROL	OUT	
3	LCD_PWR	PWR	+3.3V/+5V
4	GND	GND	
5	LVDS_A_CLK-	DIFF	
6	LVDS_A_CLK+	DIFF	
7	LCD_PWR	PWR	+3.3V/+5V
8	GND	GND	
9	LVDS_DA0-	DIFF	
10	LVDS_DA0+	DIFF	
11	LVDS_DA1-	DIFF	
12	LVDS_DA1+	DIFF	
13	LVDS_DA2-	DIFF	
14	LVDS_DA2+	DIFF	
15	LVDS_DA3-	DIFF	
16	LVDS_DA3+	DIFF	
17	DDC_DATA	I/O	+3.3V
18	DDC_CLK	I/O	+3.3V
19	LVDS_DB0-	DIFF	
20	LVDS_DB0+	DIFF	
21	LVDS_DB1-	DIFF	
22	LVDS_DB1+	DIFF	

23	LVDS_DB2-	DIFF	
24	LVDS_DB2+	DIFF	
25	LVDS_DB3-	DIFF	
26	LVDS_DB3+	DIFF	
27	LCD_PWR	PWR	+3.3V/+5V
28	GND	GND	
29	LVDS_B_CLK-	DIFF	
30	LVDS_B_CLK+	DIFF	

#### 2.4.15COM Port 1/2 & line out connector (CN17)



Pin	Pin Name	Signal Type	Signal Level
1	DCDB	IN	
2	DSRB	IN	
3	RXB	IN	
4	RTSB	OUT	±9V
5	TXB	OUT	±9V
6	CTSB	IN	
7	DTRB	OUT	±9V
8	RIB/+5V/+12V	IN/ PWR	+5V/+12V



Pin	Pin Name	Signal Type	Signal Level
9	DCDA	IN	
10	DSRA	IN	
11	RXA	IN	
12	RTSA	OUT	±9V
13	TXA	OUT	±9V
14	CTSA	IN	
15	DTRA	OUT	±9V
16	RIA	IN	
17	GND	GND	
18	AGND	GND	
19	LOUT_R	I/O	
20	LOUT_L	I/O	

#### 2.4.16 COM port2 RS-485

Pin	Pin Name	Signal Type	Signal Level
1	RS485_D-	I/O	±5V
2	NC		
3	RS485_D+	I/O	±5V
4	NC		
5	NC		

6	NC		
7	NC		
8	NC/+5V/+12V	PWR	+5V/+12V
17	GNDGND	IN	

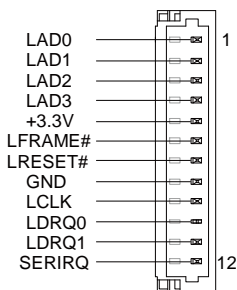
### 2.4.17 COM port2 RS-422

Pin	Pin Name	Signal Type	Signal Level
1	RS422_TX-	OUT	±5V
2	NC		
3	RS422_TX+	OUT	±5V
4	NC		
5	RS422_RX+	IN	
6	NC		
7	RS422_RX-	IN	
8	NC/+5V/+12V	PWR	+5V/+12V
9	GND	GND	

※ COM2 RS-232/422/485 can be set by BIOS setting. Default is RS-232.

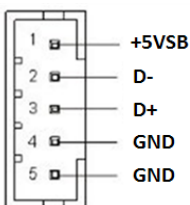
※ COM2 RI/+5V/+12V function can be set by BOM(R248-RI/R256-+12V/R250-+5V)

### 2.4.18 LPC port2 (CN18)



Pin	Pin Name	Signal Type	Signal Level
1	LAD0	I/O	+3.3V
2	LAD1	I/O	+3.3V
3	LAD2	I/O	+3.3V
4	LAD3	I/O	+3.3V
5	+3.3V	PWR	+3.3V
6	LFRAME#	IN	
7	LRESET#	OUT	+3.3V
8	GND	GND	
9	LCLK	OUT	
10	LDRQ0	IN	
11	LDRQ1	IN	
12	SERIRQ	I/O	+3.3V

## 2.4.19USB 2.0 Port 1 (CN19)



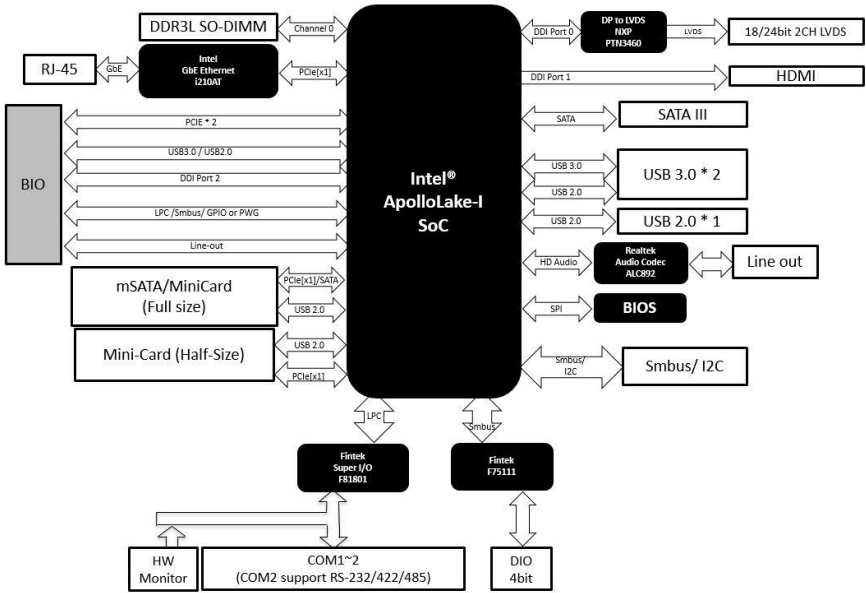
Pin	Pin Name	Signal Type	Signal Level
1	+5VSB	PWR	+5V
2	USBD5-	DIFF	
3	USBD5+	DIFF	
4	GND	GND	
5	GND	GND	

## 2.4.20 Specifications for I/O Port

I/O	Reference	Signal Name	Rate Output
Digital IO Port	CN1	D0~D3	+5V/(Open drain)
LVDS Port Inverter / Backlight Connector	CN2	VDD	+5V/2A or +12V/2A
Mini-Card Slot	CN4	+3.3VSB +1.5V	+3.3V/1.1A +1.5V/0.375A
Mini-Card Slot	CN6	+3.3VSB +1.5V	+3.3V/1.1A +1.5V/0.375A
USB 3.0 Port 1 & 2	CN10	+5VSB	+5VSB/1A (per channel)
+5V Output for SATA HDD	CN12	+5V	+5V/1A
LVDS Port	CN16	VCC	+3.3V/2A or +5V/2A

COM Port 2	CN17	+5V/+12V	+5V/1A or +12V/1A
LPC Port	CN18	+3.3V	+3.3V/0.5A
USB 2.0 Port 1	CN19	+5VSB	+5VSB/0.5A

## 2.4.21 Function Block



# Chapter 3

---

AMI BIOS Setup

## 3.1 System Test and Initialization

---

These routines test and initialize board hardware. If the routines encounter an error during the tests, you will either hear a few short beeps or see an error message on the screen. There are two kinds of errors: fatal and non-fatal. The system can usually continue the boot up sequence with non-fatal errors.

### System configuration verification

These routines check the current system configuration stored in the CMOS memory and BIOS NVRAM. If system configuration is not found or system configuration data error is detected, system will load optimized default and re-boot with this default system configuration automatically.

There are four situations in which you will need to setup system configuration:

1. You are starting your system for the first time
2. You have changed the hardware attached to your system
3. The system configuration is reset by Clear-CMOS jumper
4. The CMOS memory has lost power and the configuration information has been erased.

The PICO-APL1 CMOS memory has an integral lithium battery backup for data retention. However, you will need to replace the complete unit when it finally runs down.



## 3.2 AMI BIOS Setup

---

AMI BIOS ROM has a built-in Setup program that allows users to modify the basic system configuration. This type of information is stored in battery-backed CMOS RAM and BIOS NVRAM so that it retains the Setup information when the power is turned off.

### Entering Setup

Power on the computer and press <Del> or <ESC> immediately. This will allow you to enter Setup.

### Main

Set the date, use tab to switch between date elements.

### Advanced

Enable/disable boot option for legacy network devices.

### Chipset

Host bridge parameters.

### Boot

Enables/disables quiet boot option.

### Security

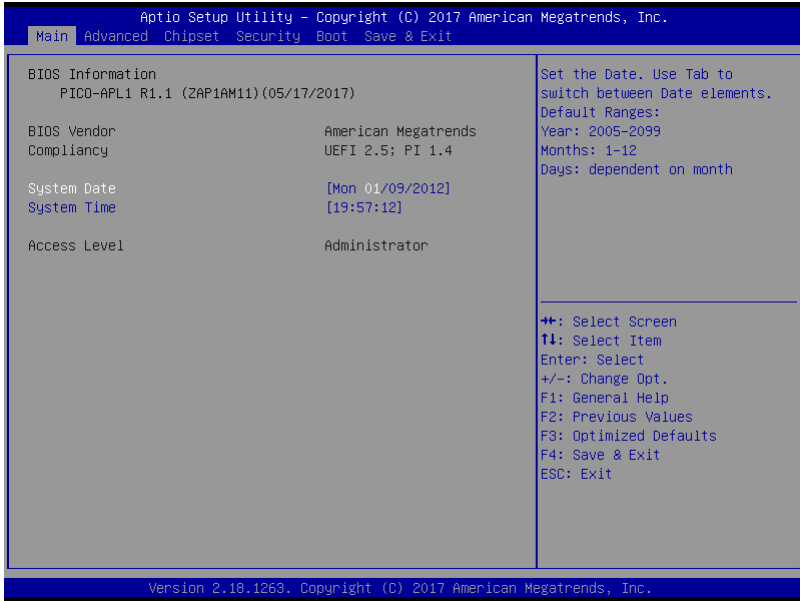
Set setup administrator password.

### Save & Exit

Exit system setup after saving the changes.

### 3.3 Setup Submenu: Main

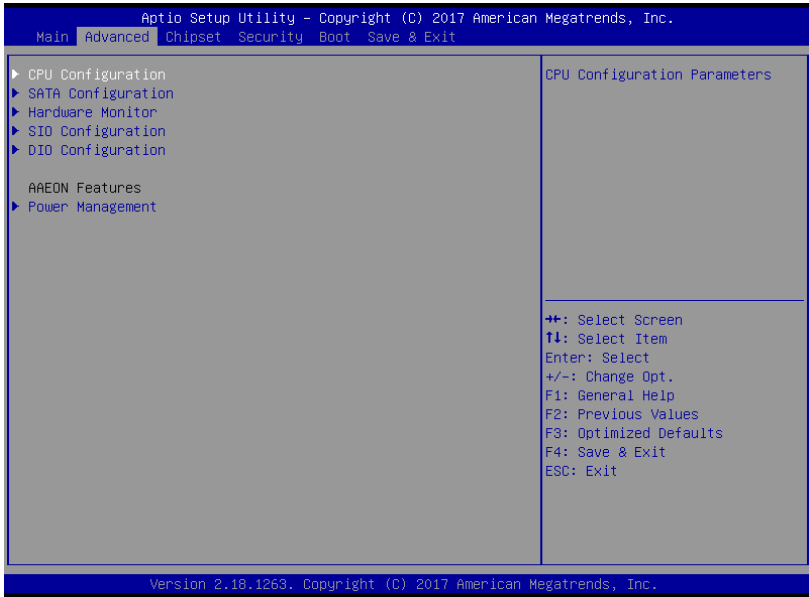
Press “Delete” to enter Setup



Options summary: (*default setting*)

System Date	Day MM:DD:YYYY	
Change the month, year and century. The 'Day' is changed automatically.		
System Time	HH : MM : SS	
Change the clock of the system.		

### 3.4 Setup Submenu: Advanced

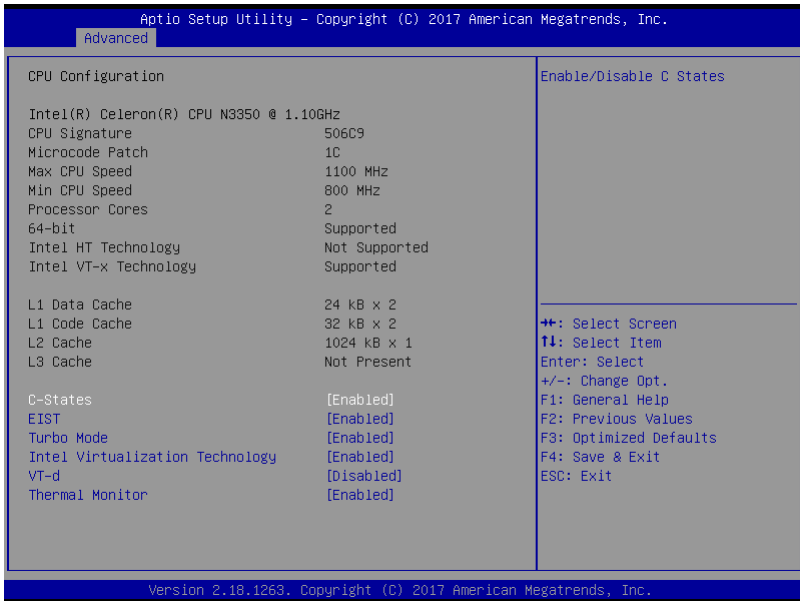


Options summary: (*default setting*)

CPU Configuration		
CPU Configuration Parameters		
SATA Configuration		
SATA Device Configuration		
USB Configuration		
USB Configuration Parameters		
SIO Configuration		
SIO Chip configuration .Enable or Disable SIO Logical Devices, Resources and Features settings, etc.		
Hardware Monitor		

Power Management		
System ACPI/Power Mode/Wake Event Configuration		
Digital IO Port Configuration		
Set Input/Output of digital Port Configuration		

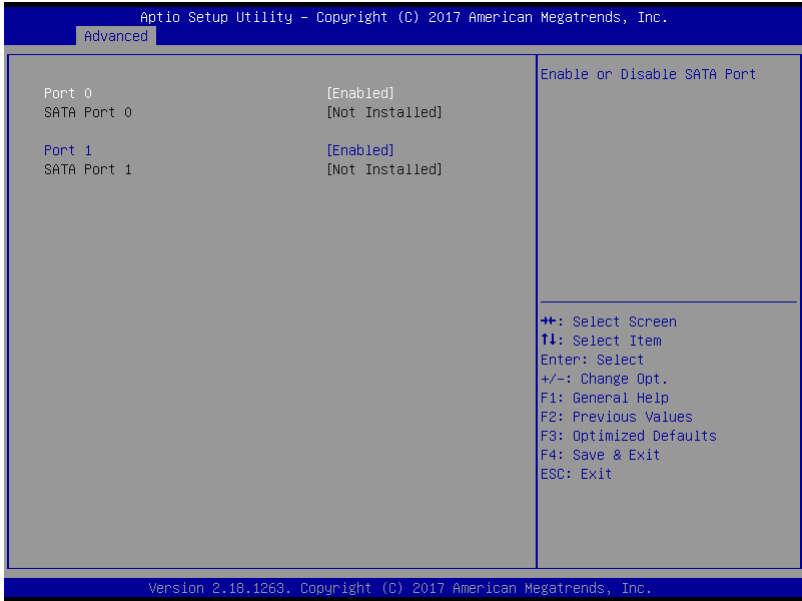
### 3.4.1 CPU configuration



Options summary:

C-States	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable/Disable C States.		
EIST™	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable/Disable Intel SpeedStep.		
Intel Virtualization Technology	Disabled	
	Enabled	Optimal Default, Failsafe Default
When enabled, a VMM can utilize the additional hardware capabilities provided by Vanderpool Technology.		
VT-d	Disabled	Optimal Default, Failsafe Default
	Enabled	
Enable/Disable CPU VT-d		
Thermal Monitor	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable/Disable Thermal Monitor		

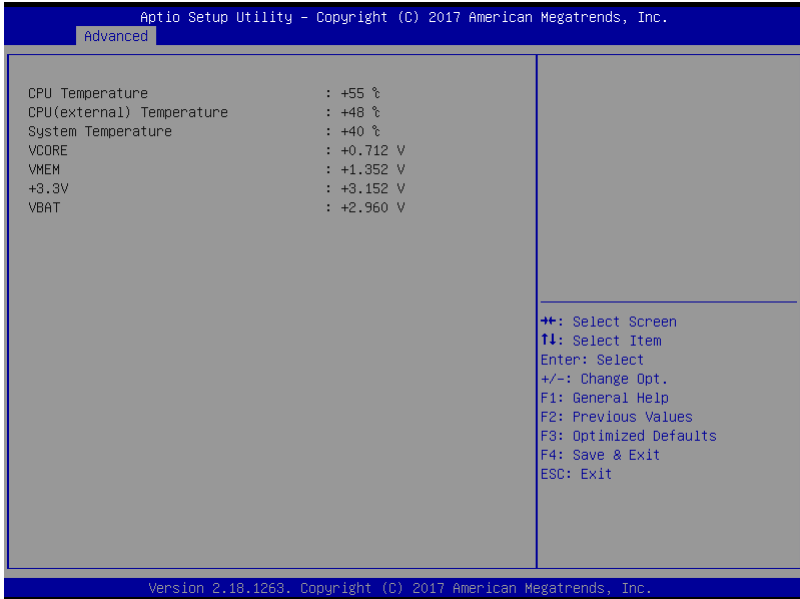
### 3.4.2 SATA Configuration



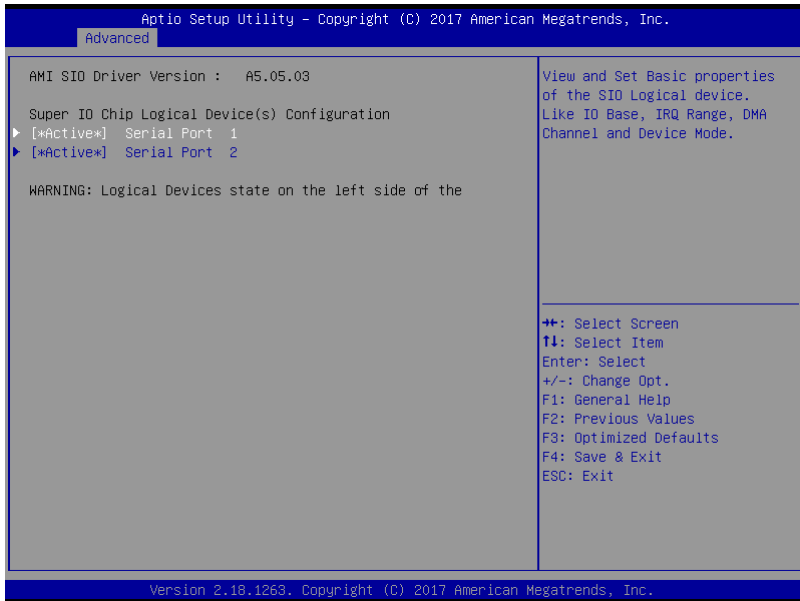
Options summary:

Port 0/1	Disabled	
	Enabled	Optimal Default, Failsafe Default
Enable/Disable SATA port		

### 3.4.3 Hardware Monitor



### 3.4.4 SIO Configuration

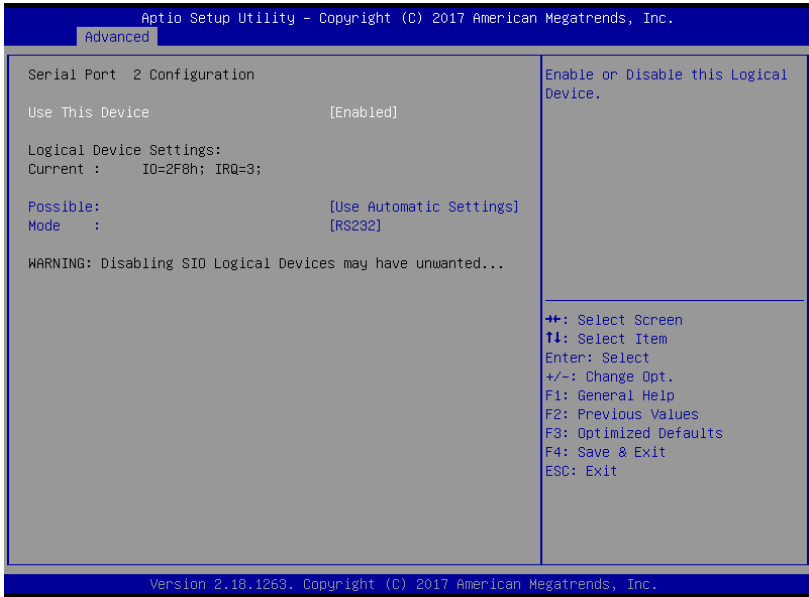


Options summary: (*default setting*)

Serial Port 1/2 Configuration		
View and Set Basic properties of the SIO Logical device. Like IO Base , IRQ Range , DMA Channel and Device Mode.		



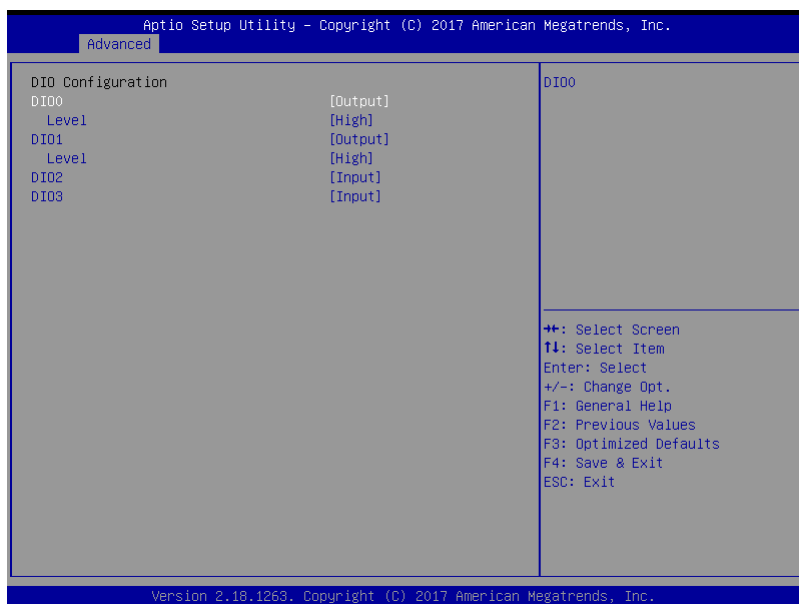
### 3.4.4.1 Serial Port Configuration



Options summary:

Use This Device	Disable	
	Enable	Optimal Default, Failsafe Default
Enable or Disable this Logical Device.		
Possible:	Use Automatic Settings	Optimal Default, Failsafe Default
	IO=2F8h; IRQ=3	
	IO=3F8h; IRQ=4	
Allows user to change Device's Resource settings. New settings will be reflected on This Setup Page after System restarts.		
Mode:	RS232	Optimal Default, Failsafe Default
	RS422	
	RS485	
UART RS232, 422, 485 selection.		

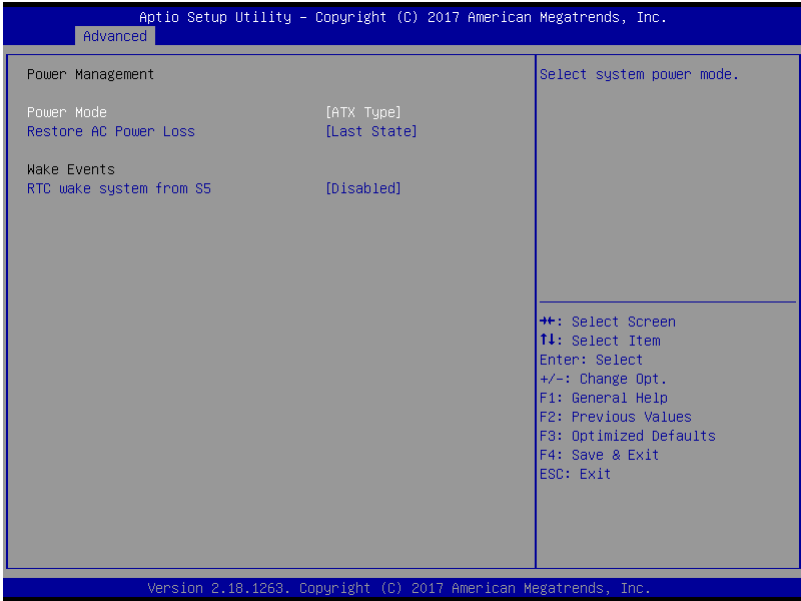
### 3.4.5 Dio Configuration



Options summary:

DIO *	Output	
	Input	
Set DIO as Input or Output		
Level	High	Optimal Default, Failsafe Default
	Low	
Set output level when DIO pin is output		

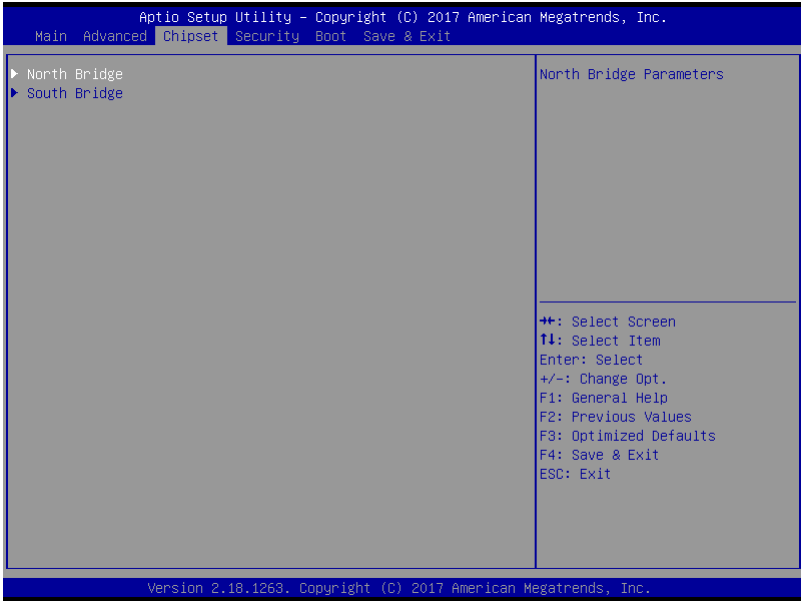
### 3.4.6 Power Management



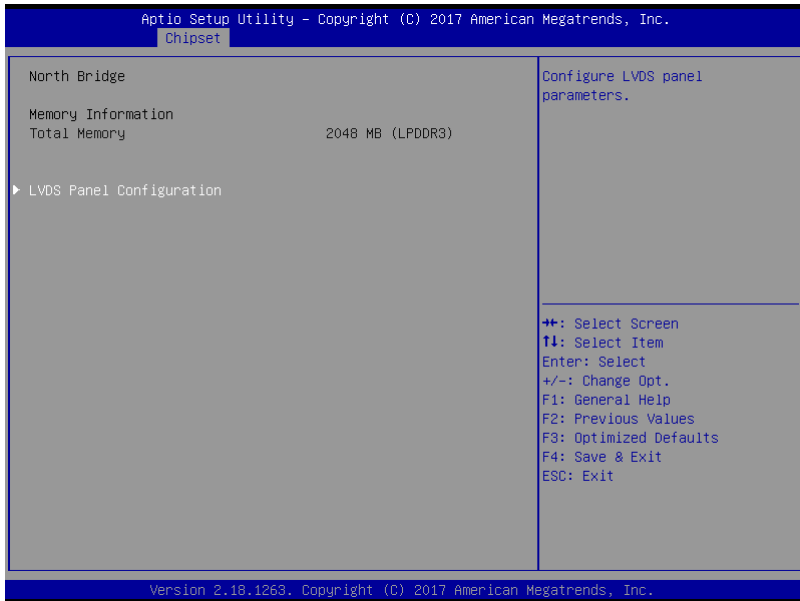
Options summary:

Power Mode	ATX Type	Optimal Default, Failsafe Default
	AT Type	
Select system power mode		
Restore AC Power Loss	Last State	Optimal Default, Failsafe Default
	Always On	
	Always Off	
RTC wake system from S5	Disable	Optimal Default, Failsafe Default
	Fixed Time	
RTC wake		

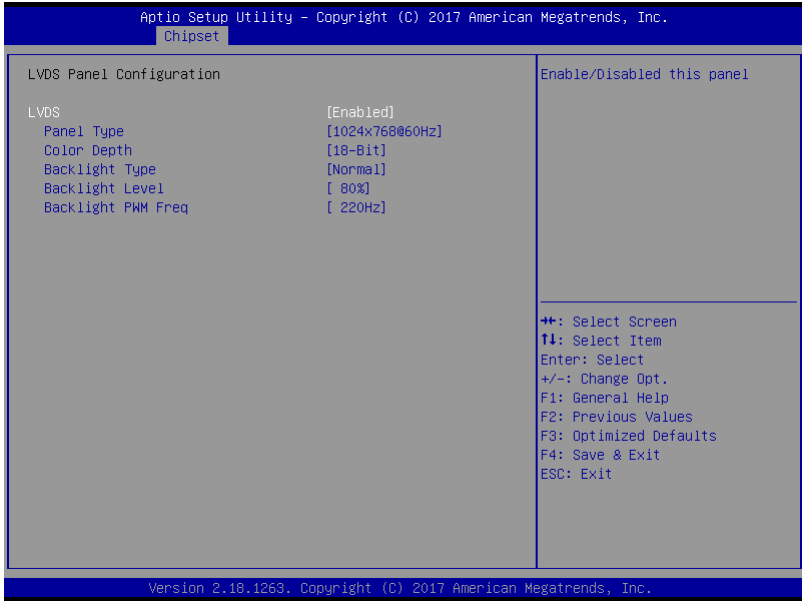
### 3.4.7 Setup submenu: Chipset



## 3.4.8 North Bridge



### 3.5 LVDS Panel Configuration



Options summary:

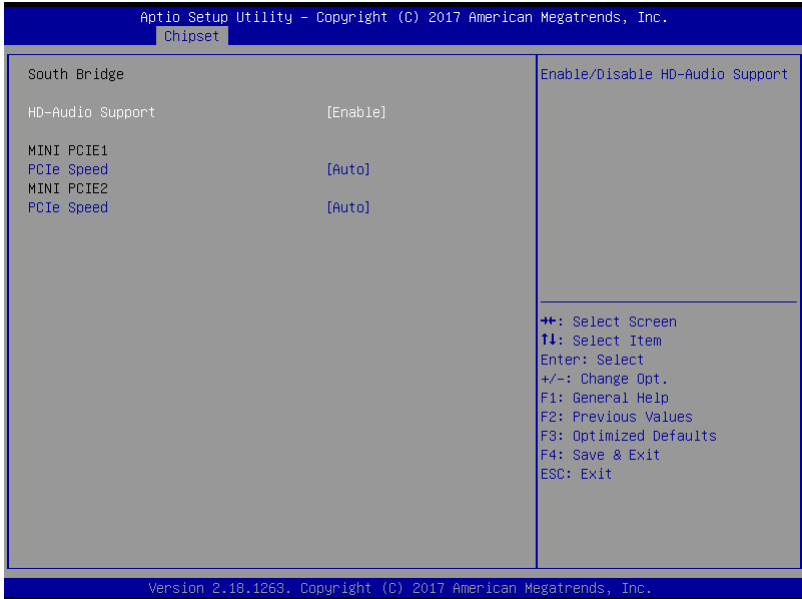
LVDS	Disabled	Optimal Default, Failsafe Default
	Enabled	
Enable/Disabled this panel.		
LVDS Panel Type	640X480@60HZ	
	800X480@60HZ	
	800X600@60HZ	
	1024X600@60HZ	
	1024X768@60HZ	Optimal Default, Failsafe Default
	1280X768@60HZ	
	1280X800@60HZ	
	1280X1024@60HZ	

	1366X768@60HZ	
	1440X900@60HZ	
	1600X1200@60HZ	
	1920X1080@60HZ	
	1920X1200@60HZ	
Select LCD panel used by Internal Graphics Device by selecting the appropriate setup item.		

Color Depth	18-bit	Optimal Default, Failsafe Default
	24-bit	
	36-bit	
	48-bit	
Select panel type		
Backlight Type	Normal	Optimal Default, Failsafe Default
	Inverted	
Select backlight control signal type		
Backlight Level	0%	Optimal Default, Failsafe Default
	10%	
	20%	
	30%	
	40%	
	50%	
	60%	
	70%	
	80%	
	90%	
100%		
Select backlight control level		
Backlight PWM Freq	100Hz	Optimal Default, Failsafe Default
	200Hz	
	220Hz	
	500Hz	
	1.1KHz	
	2.2KHz	
	6.5KHz	
Select PWM frequency of backlight control signal		



### 3.5.1 South Bridge



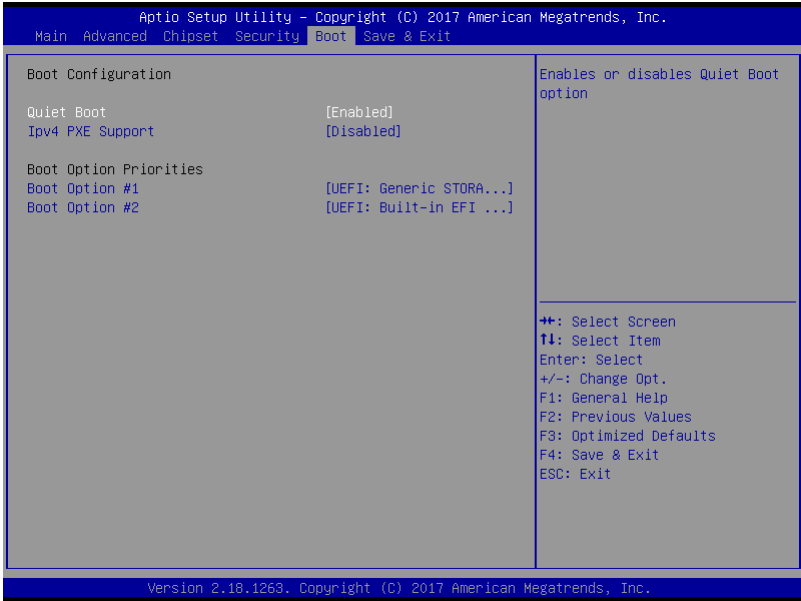
Options summary:

HD-Audio Support	Disabled	Optimal Default, Failsafe Default
	Enabled	
Enable/Disabled HD audio		
PCIe Speed	Auto	Optimal Default, Failsafe Default
	Gen1	
	Gen2	
Configure PCIe Speed		

#### 3.5.1.1 Setup submenu: Security



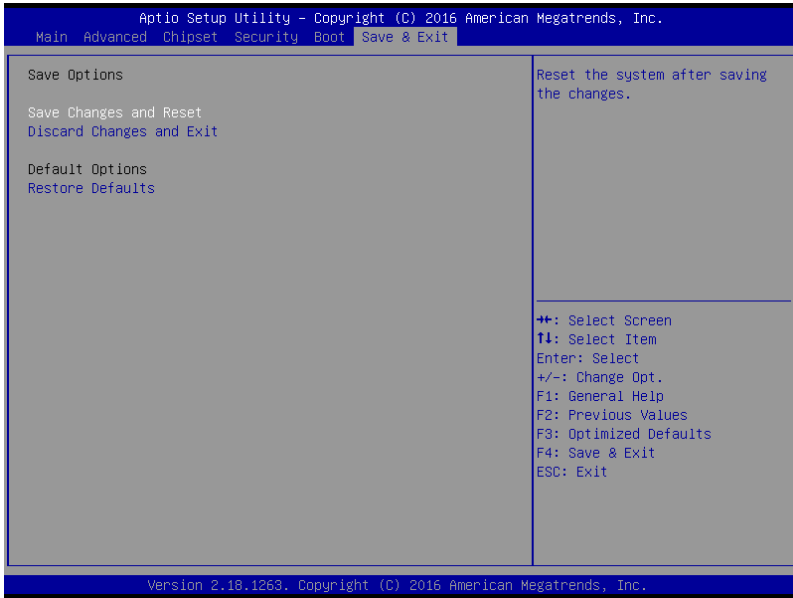
### 3.5.2 Setup submenu: Boot



Options summary:

Quiet Boot	Disabled	Optimal Default, Failsafe Default
	Enabled	
Enable/Disable showing boot logo.		
Monitor Mwait	Disable	Optimal Default, Failsafe Default
	Enabled	
	Auto	
Enable/Disable Monitor Mwait. To install Linux OS, please set this item to disable.		
Ipv4 PXE Support	Disabled	Optimal Default, Failsafe Default
	Enabled	
Enable Ipv4 PXE Boot Support. If disabled IPV4 PXE boot option will not be created.		

### 3.6 Setup submenu: Exit



# Chapter 4

---

Drivers Installation

## 4.1 Product CD/DVD

---

The PICO-APL1 comes with a product DVD that contains all the drivers and utilities you need to setup your product. Insert the DVD and follow the steps in the autorun program to install the drivers.

In case the program does not start, follow the sequence below to install the drivers.

### Step 1 – Install Chipset Driver

1. Open the **STEP1 - CHIPSET** folder and open the **SetupChipset.exe** file
2. Follow the instructions
3. Drivers will be installed automatically

### Step 2 – Install Graphic Driver

1. Open the **STEP2 - VGA** folder and open the **Setup.exe** file
2. Follow the instructions
3. Driver will be installed automatically

### Step 3 – Install LAN Driver

1. Open the **STEP3 - LAN** folder and select your OS
2. Open the **.exe** file in the folder
3. Follow the instructions
4. Driver will be installed automatically

#### Step 4 – Install Audio Driver

1. Open the **STEP4 - AUDIO** folder and open the **0006-64bit\_Win7\_Win8\_Win81\_Win10\_R279.exe** file
2. Follow the instructions
3. Driver will be installed automatically

#### Step 5 – Install TXE Driver

1. Open the **STEP5 - TXE** folder and open the **SetupTXE.exe** file
2. Follow the instructions
3. Driver will be installed automatically

#### Step 6 – Install FintekSerial\_Patch\_T4R8 Driver

1. Open the **STEP6-FintekSerial\_Patch\_T4R8** folder and open the **Setup.exe** file
2. Follow the instructions
3. Driver will be installed automatically

#### Step 7 – Install GPIO Driver

1. Open the **STEP7 - GPIO** folder and open the **SetupSerialIO.exe** file
2. Follow the instructions
3. Driver will be installed automatically

# Appendix A

---

## Watchdog Timer Programming



## A.1 Watchdog Timer Registers

Table 1 : Watch dog relative IO address		
	Default Value	Note
I/O Base Address	0x2E	I/O Base address for Watchdog operation. This address is assigned by SIO LDN7

Table 2 : Watchdog relative register table				
Register	Offset	BitNum	Value	Note
Watchdog WDRST# Enable	0x00	7	1	Enable/Disable time out output via WDRST# 0: Disable 1: Enable
Pulse Width	0x05	0:1	01	Width of Pulse signal 00: 1ms (do not use) 01: 25ms 10: 125ms 11: 5s <b>Pulse width is must longer then 16ms.</b>
Signal Polarity	0x05	2	0	0: low active 1: high active <b>Must set this bit to 0</b>
Counting Unit	0x05	3	0	Select time unit. 0: second 1: minute
Output Signal Type	0x05	4	1	0: Level 1: Pulse <b>Must set this bit to 1</b>
Watchdog Timer Enable	0x05	5	1	0: Disable 1: Enable
Timeout Status	0x05	6	1	1: timeout occurred. Write a 1 to clear timeout status
Timer Counter	0x06			Time of watchdog timer (0~255)

## A.2 Watchdog Sample Program

```
*****
// WDT I/O operation relative definition (Please reference to Table 1)
#define WDTAddr    0x510 // WDT I/O base address
Void WDTWriteByte(byte Register, byte Value);
byte WDTReadByte(byte Register);
Void WDTSetReg(byte Register, byte Bit, byte Val);
// Watch Dog relative definition (Please reference to Table 2)
#define DevReg     0x00 // Device configuration register
    #define WDRstBit 0x80 // Watchdog WDTRST# (Bit7)
    #define WDRstVal 0x80 // Enabled WDTRST#
#define TimerReg   0x05 // Timer register
    #define PSWidthBit 0x00 // WDTRST# Pulse width (Bit0:1)
    #define PSWidthVal 0x01 // 25ms for WDTRST# pulse
    #define PolarityBit 0x02 // WDTRST# Signal polarity (Bit2)
    #define PolarityVal 0x00 // Low active for WDTRST#
    #define UnitBit    0x03 // Unit for timer (Bit3)
    #define ModeBit    0x04 // WDTRST# mode (Bit4)
    #define ModeVal    0x01 // 0:level 1: pulse
    #define EnableBit  0x05 // WDT timer enable (Bit5)
    #define EnableVal  0x01 // 1: enable
    #define StatusBit  0x06 // WDT timer status (Bit6)
#define CounterReg 0x06 // Timer counter register
*****

*****
VOID Main() {
    // Procedure : AaeonWDTConfig
    // (byte)Timer : Counter of WDT timer.(0x00~0xFF)
    // (boolean)Unit : Select time unit(0: second, 1: minute).
    EnterSIOconfig();
    SetWDT();
    AaeonWDTConfig(Counter, Unit);
    // Procedure : AaeonWDTEnable
    // This procedure will enable the WDT counting.
    AaeonWDTEnable();
    ExitSIOconfig();
}
*****
```

```

*****
// Procedure : AaeonWDTEnable
VOID EnterSIOconfig (){
    IOWriteByte (IoConfAddr,0x87);
    IOWriteByte (IoConfAddr,0x87);
}

VOID ExitSIOconfig (){
    IOWriteByte (IoConfAddr,0xAA);
}

VOID SetWDT ()
    IOWriteByte (IoConfAddr,0x2B);
    IOWriteByte(IoConfAddr+1, (IOReadByte(IoConfAddr+1)&0xFC));
}

// Procedure : AaeonWDTEnable
VOID AaeonWDTEnable (){
    WDTEnableDisable(1);
}

// Procedure : AaeonWDTConfig
VOID AaeonWDTConfig (byte Counter, BOOLEAN Unit){
    // Disable WDT counting
    WDTEnableDisable(0);
    // Clear Watchdog Timeout Status
    WDTClearTimeoutStatus();
    // WDT relative parameter setting
    WDTParameterSetting(Timer, Unit);
}

VOID WDTEnableDisable(byte Value){
    If (Value == 1)
        WDTSetBit(TimerReg, EnableBit, 1);
    else
        WDTSetBit(TimerReg, EnableBit, 0);
}

VOID WDTParameterSetting(byte Counter, BOOLEAN Unit){
    // Watchdog Timer counter setting
    WDTWriteByte(CounterReg, Counter);
    // WDT counting unit setting

```

```

    WDTSetBit(TimerReg, UnitBit, Unit);
    // WDT output mode set to pulse
    WDTSetBit(TimerReg, ModeBit, ModeVal);
    // WDT output mode set to active low
    WDTSetBit(TimerReg, PolarityBit, PolarityVal);
    // WDT output pulse width is 25ms
    WDTSetBit(TimerReg, PSWidthBit, PSWidthVal);
    // Watchdog WDTRST# Enable
    WDTSetBit(DevReg, WDRstBit, WDRstVal);
}

VOID WDTClearTimeoutStatus(){
    WDTSetBit(TimerReg, StatusBit, 1);
}

*****

*****

VOID WDTWriteByte(byte Register, byte Value){
    IOWriteByte(WDTAddr+Register, Value);
}

byte WDTReadByte(byte Register){
    return IOReadByte(WDTAddr+Register);
}

VOID WDTSetBit(byte Register, byte Bit, byte Val){
    byte TmpValue;

    TmpValue = WDTReadByte(Register);
    TmpValue &= ~(1 << Bit);
    TmpValue |= Val << Bit;
    WDTWriteByte(Register, TmpValue);
}

*****

```

# Appendix B

---

I/O Information

## B.1 I/O Address Map

Pico-ITX Board

PICO-APL1

Address Range	Device Name
[0000000000000000 - 000000000000006F]	PCI Express Root Complex
[0000000000000020 - 0000000000000021]	Programmable interrupt controller
[0000000000000024 - 0000000000000025]	Programmable interrupt controller
[0000000000000028 - 0000000000000029]	Programmable interrupt controller
[000000000000002C - 000000000000002D]	Programmable interrupt controller
[000000000000002E - 000000000000002F]	Motherboard resources
[0000000000000030 - 0000000000000031]	Programmable interrupt controller
[0000000000000034 - 0000000000000035]	Programmable interrupt controller
[0000000000000038 - 0000000000000039]	Programmable interrupt controller
[000000000000003C - 000000000000003D]	Programmable interrupt controller
[0000000000000040 - 0000000000000043]	System timer
[000000000000004E - 000000000000004F]	Motherboard resources
[0000000000000050 - 0000000000000053]	System timer
[0000000000000060 - 0000000000000060]	Standard PS/2 Keyboard
[0000000000000061 - 0000000000000061]	Motherboard resources
[0000000000000063 - 0000000000000063]	Motherboard resources
[0000000000000064 - 0000000000000064]	Standard PS/2 Keyboard
[0000000000000065 - 0000000000000065]	Motherboard resources
[0000000000000067 - 0000000000000067]	Motherboard resources
[0000000000000070 - 0000000000000070]	Motherboard resources
[0000000000000070 - 0000000000000077]	System CMOS/real time clock
[0000000000000078 - 00000000000000CF7]	PCI Express Root Complex
[0000000000000080 - 000000000000008F]	Motherboard resources
[0000000000000092 - 0000000000000092]	Motherboard resources
[00000000000000A0 - 00000000000000A1]	Programmable interrupt controller
[00000000000000A4 - 00000000000000A5]	Programmable interrupt controller
[00000000000000A8 - 00000000000000A9]	Programmable interrupt controller
[00000000000000AC - 00000000000000AD]	Programmable interrupt controller
[00000000000000B0 - 00000000000000B1]	Programmable interrupt controller
[00000000000000B2 - 00000000000000B3]	Motherboard resources
[00000000000000B4 - 00000000000000B5]	Programmable interrupt controller
[00000000000000B8 - 00000000000000B9]	Programmable interrupt controller
[00000000000000BC - 00000000000000BD]	Programmable interrupt controller
[00000000000002F8 - 00000000000002FF]	Communications Port (COM2)
[00000000000003F8 - 00000000000003FF]	Communications Port (COM1)
[0000000000000400 - 000000000000047F]	Motherboard resources
[00000000000004D0 - 00000000000004D1]	Programmable interrupt controller
[0000000000000500 - 00000000000005FE]	Motherboard resources
[0000000000000680 - 000000000000069F]	Motherboard resources
[0000000000000A00 - 0000000000000A0F]	Motherboard resources
[0000000000000A10 - 0000000000000A1F]	Motherboard resources
[0000000000000D00 - 0000000000000FFF]	PCI Express Root Complex
[0000000000000E00 - 0000000000000FFF]	Intel(R) Celeron(R)/Pentium(R) Processor PCI Express Root Port - 5AD8
[000000000000F000 - 000000000000F03F]	Intel(R) HD Graphics
[000000000000F040 - 000000000000F05F]	Intel(R) Celeron(R)/Pentium(R) Processor SMBUS - 5AD4
[000000000000F060 - 000000000000F07F]	Standard SATA AHCI Controller
[000000000000F080 - 000000000000F083]	Standard SATA AHCI Controller
[000000000000F090 - 000000000000F097]	Standard SATA AHCI Controller

## B.2 Memory Address Map

Memory	
[0000000000A0000 - 0000000000BFFFFF]	PCI Express Root Complex
[0000000000C0000 - 0000000000DFFFFF]	PCI Express Root Complex
[0000000000E0000 - 0000000000FFFFFF]	PCI Express Root Complex
[000000007B800001 - 000000007BFFFFFF]	PCI Express Root Complex
[000000007C000001 - 000000007FFFFFFF]	PCI Express Root Complex
[0000000080000000 - 000000008FFFFFFF]	Intel(R) HD Graphics
[0000000080000000 - 00000000CFFFFFFF]	PCI Express Root Complex
[0000000090000000 - 0000000090FFFFFF]	Intel(R) HD Graphics
[0000000091000000 - 00000000910FFFFFFF]	High Definition Audio Controller
[0000000091100000 - 000000009111FFFFF]	Intel(R) I210 Gigabit Network Connection
[0000000091100000 - 00000000911FFFFF]	Intel(R) Celeron(R)/Pentium(R) Processor PCI Express Root Port - 5AD8
[0000000091120000 - 0000000091123FFFF]	Intel(R) I210 Gigabit Network Connection
[0000000091200000 - 000000009120FFFFF]	Intel(R) USB 3.0 eXtensible Host Controller - 1.0 (Microsoft)
[0000000091210000 - 0000000091213FFFF]	High Definition Audio Controller
[0000000091214000 - 0000000091215FFFF]	Standard SATA AHCI Controller
[0000000091218000 - 00000000912180FFF]	Intel(R) Celeron(R)/Pentium(R) Processor SMBUS - 5AD4
[0000000091219000 - 00000000912197FFF]	Standard SATA AHCI Controller
[000000009121A000 - 000000009121A0FFF]	Standard SATA AHCI Controller
[000000009121E000 - 000000009121EFFFF]	Intel(R) Trusted Execution Engine Interface
[00000000D0C00000 - 00000000D0C00653]	Intel(R) Serial IO GPIO Host Controller - INT3452
[00000000D0C40000 - 00000000D0C40763]	Intel(R) Serial IO GPIO Host Controller - INT3452
[00000000D0C50000 - 00000000D0C5076B]	Intel(R) Serial IO GPIO Host Controller - INT3452
[00000000D0C70000 - 00000000D0C70673]	Intel(R) Serial IO GPIO Host Controller - INT3452
[00000000E0000000 - 00000000EFFFFFFF]	Motherboard resources
[00000000E0000000 - 00000000EFFFFFFF]	PCI Express Root Complex
[00000000FEA00000 - 00000000FEAFFFFFFF]	Motherboard resources
[00000000FED00000 - 00000000FED003FF]	High precision event timer
[00000000FED01000 - 00000000FED01FFF]	Motherboard resources
[00000000FED03000 - 00000000FED03FFF]	Motherboard resources
[00000000FED06000 - 00000000FED06FFF]	Motherboard resources
[00000000FED08000 - 00000000FED09FFF]	Motherboard resources
[00000000FED1C000 - 00000000FED1CFFF]	Motherboard resources
[00000000FED80000 - 00000000FED8BFFF]	Motherboard resources
[00000000FEE00000 - 00000000FEEFFFFFFF]	Motherboard resources

## B.3 IRQ Mapping Chart

Pico-ITX Board

PICO-APL1

Interrupt request (IRQ)	
(ISA) 0x00000000 (00)	System timer
(ISA) 0x00000001 (01)	Standard PS/2 Keyboard
(ISA) 0x00000003 (03)	Communications Port (COM2)
(ISA) 0x00000004 (04)	Communications Port (COM1)
(ISA) 0x00000008 (08)	High precision event timer
(ISA) 0x0000000C (12)	PS/2 Compatible Mouse
(ISA) 0x0000000E (14)	Intel(R) Serial IO GPIO Host Controller - INT3452
(ISA) 0x0000000E (14)	Intel(R) Serial IO GPIO Host Controller - INT3452
(ISA) 0x0000000E (14)	Intel(R) Serial IO GPIO Host Controller - INT3452
(ISA) 0x0000000E (14)	Intel(R) Serial IO GPIO Host Controller - INT3452
(ISA) 0x00000036 (54)	Microsoft ACPI-Compliant System
(ISA) 0x00000037 (55)	Microsoft ACPI-Compliant System
(ISA) 0x00000038 (56)	Microsoft ACPI-Compliant System
(ISA) 0x00000039 (57)	Microsoft ACPI-Compliant System
(ISA) 0x0000003A (58)	Microsoft ACPI-Compliant System
(ISA) 0x0000003B (59)	Microsoft ACPI-Compliant System
(ISA) 0x0000003C (60)	Microsoft ACPI-Compliant System
(ISA) 0x000001FF (511)	Microsoft ACPI-Compliant System
(PCI) 0x00000019 (25)	High Definition Audio Controller
(PCI) 0xFFFFFFF3 (-13)	Intel(R) USB 3.0 eXtensible Host Controller - 1.0 (Microsoft)
(PCI) 0xFFFFFFF4 (-12)	Intel(R) I210 Gigabit Network Connection
(PCI) 0xFFFFFFF5 (-11)	Intel(R) I210 Gigabit Network Connection
(PCI) 0xFFFFFFF6 (-10)	Intel(R) I210 Gigabit Network Connection
(PCI) 0xFFFFFFF7 (-9)	Intel(R) I210 Gigabit Network Connection
(PCI) 0xFFFFFFF8 (-8)	Intel(R) I210 Gigabit Network Connection
(PCI) 0xFFFFFFF9 (-7)	Intel(R) I210 Gigabit Network Connection
(PCI) 0xFFFFF9FA (-6)	Intel(R) Trusted Execution Engine Interface
(PCI) 0xFFFFFFF8 (-5)	Intel(R) HD Graphics
(PCI) 0xFFFFFFF4 (-4)	Standard SATA AHCI Controller
(PCI) 0xFFFFFFF3 (-3)	Intel(R) Celeron(R)/Pentium(R) Processor PCI Express Root Port - 5AD6
(PCI) 0xFFFFFFF2 (-2)	Intel(R) Celeron(R)/Pentium(R) Processor PCI Express Root Port - 5AD8



# Appendix C

---

Mating Connectors

## C.1 List of Mating Connectors and Cables

The table notes mating connectors and available cables.

Function	Description	Mating Connector Vendor	Vendor P/N	Pin No.	AAEON P/N	Mating Cable P/N
HDMI	1 x HDMI	FOXCON N	QJ51191 -LFB4-7 F	19	16544019 32	N/A
COM Port	2 x COMs, 1x Line-out Cable.WL125 3H-20P 1.25mm Housing.Dual DB9(M).Line-Out Jack.15cm	PINREX	712-94-20TWR 8	20	16558201 00	17032001 53
LAN	1 x RJ45 Connector, 90D. (F), DIP	UDE	RT7-17F AAM1A	10	16525142 0B	N/A
USB	1 x Dual USB Connector, 90D. (F), DIP	LOTES	ABA-U SB-254 -K01	13	16548018 32	N/A
LVDS LCD	Board to Wrie Conn.15P*2.9 0D(M).SMD.1. 0mm	ACES	50246-03001-001	30	16535152 10	N/A

LCD Inverter	1 x Wafer Box, 5P, 90D. (M) DIP, 2.0mm	PINREX	721-94-05TWR9	5	1655305130	N/A
SATA	1 x SATA Connector, 180D. (M), SMT	TechBest	007-01-00757	7	1654907009	N/A
SATA PWR	1 x Wafer Box, 2P, 180D. (M) DIP, 2.0mm	PINREX	721-81-02TWO0	2	1655302025	1702150155
Power Conn.	TERMINAL.2 P*1.90D(M),D IP	Dinkle	DT-126 VP-S20 16002P	2	1652602105	
Digital I/O	1 x WAFER BOX.6P. 180D.(M),2.0 mm	PINREX	222-97-03GBE1	6	165300320L	N/A
Front Panel	1 x WAFER BOX.10P. 180D.(M),2.0 mm	PINREX	222-97-05GBE1	10	165300520Y	N/A
Audio	2 x COMs, 1x Line-out Cable.WL125 3H-20P 1.25mm	PINREX	712-94-20TWR8	20	<b>1655820100</b>	1703200153

	Housing.Dual DB9(M).Line- Out Jack.15cm					
USB	1 x Wafer Box, 5P, 180D. (M) SMD. ,1.25m m	CATCH	1201-70 0-05SM	5	16559050 37	17000502 07
BIO	Board-Board Connector.80 P:180D(F)..Hir ose.FX18-80P -0.8SV	Hirose	FX18-8 0P-0.8S V	80	16540080 20	N/A

# Appendix D

---

DIO

## D.1 DIO

The F75111 provides one serial access interface, I2C Bus, to read/write internal registers.

The address of Serial Bus is 0x6E (0110\_1110)

The related register for configuring DIO is list as follows:

### Configuration and Control Register – Index 01h

Power-on default [7:0] =0000\_1000b

Bit	Name	R/W	PWR	Description
7	INIT	R/W	VSB3V	Software reset for all registers including Test Mode registers. Users use only.
6	Reserved	R/W	VSB3V	
5	EN_WDT10	R/W	VSB3V	Enable Reset Out. If set to 1, enable WDTOUT10# output. Default is disable.
4	Reserved	R/W	VSB3V	
3	Reserved	R/W	VSB3V	
2	Reserved	R/W	VSB3V	
1	SMART_POWER_MANAGEMENT	R/W	VSB3V	Set this bit to 1 will enable auto power down mode, when all function are idle then 20ms the chip will auto power down, it will wakeup when GPIO state change or read write register
0	SOFT_POWER_DOWN	R/W	VSB3V	Set this bit to 1 will power down all of the analog block and stop internal clock, write 0 to clear this bit or when GPIO state change will auto clear this bit to 0.

### GPIO2x Output Control Register – Index 20h

Power-on default [7:0] =0000\_0000b

Bit	Name	R/W	PWR	Description
7	GP27_OCTRL	R/W	VSB3V	GPIO 27 output control. Set to 1 for output function. Set to 0 for input function(default).
6	GP26_OCTRL	R/W	VSB3V	GPIO 26 output control. Set to 1 for output function. Set to 0 for input function(default).
5	GP25_OCTRL	R/W	VSB3V	GPIO 25 output control. Set to 1 for output function. Set to 0 for input function(default).
4	GP24_OCTRL	R/W	VSB3V	GPIO 24 output control. Set to 1 for output function. Set to 0 for input function(default).

## GPIOx Output Data Register – Index 21h

Power-on default [7:0] =0000\_0000b

Bit	Name	R/W	PWR	Description
7	GP27_ODATA	R/W	VSB3V	GPIO 27 output data.
6	GP26_ODATA	R/W	VSB3V	GPIO 26 output data.
5	GP25_ODATA	R/W	VSB3V	GPIO 25 output data.
4	GP24_ODATA	R/W	VSB3V	GPIO 24 output data.

## GPIOx Input Status Register – Index 22h

Power-on default [7:0] =xxxx\_xxxx

Bit	Name	R/W	PWR	Description
7	GP27_PSTS	RO	VSB3V	Read the GPIO27 data on the pin.
6	GP26_PSTS	RO	VSB3V	Read the GPIO26 data on the pin.
5	GP25_PSTS	RO	VSB3V	Read the GPIO25 data on the pin.
4	GP24_PSTS	RO	VSB3V	Read the GPIO24 data on the pin.

The following is a sample code for 8 input

```
.MODEL SMALL
```

```
.CODE
```

```
begin:
```

```
mov cl,01h
```

```
mov al,80h
```

```
call CT_I2CWriteByte
```

```
call Delay5ms
```

```
mov al,00h
```

```
mov cl,20h
```

```
call CT_I2CWriteByte
```

```
mov cl,22h
```

```
call CT_I2CReadByte
```

```
;Input : CL - register index
```

```
; CH - device ID
;Output : AL - Value read
Ct_I2CReadByte Proc Near
mov ch,06eh
mov dx, F040h + 00h ; Host Control Register
xor al, al ; Clear previous commands
out dx, al
call Delay5ms
mov dx, F040h + 04h ; Transmit Slave Address Register
inc ch ; Set the slave address and
mov al, ch ; prepare for a READ command
out dx, al
mov dx, F040h + 05h ; Host Command Register
mov al, cl ; offset to read
out dx, al
mov dx, F040h + 06h

xor al, al ; Clear old data
out dx, al
mov dx, F040h + 01h ; Host Status Register
mov al, 07h ; Clear all status bits
out dx, al

mov dx, F040h + 00h ; Host Control Reegister
mov al, 12h ; Start a byte access
out dx, al
call CT_Chk_SMBus_Ready
mov dx, F040h + 06h
```



```
in al, dx
```

```
ret
```

```
Ct_I2CReadByte Endp
```

```
;Input : CL - register index
```

```
; CH - device ID
```

```
; AL - Value to write
```

```
;Output: none
```

```
Ct_I2CWriteByte Proc Near
```

```
mov ch,06eh
```

```
xchg ah, al
```

```
mov dx, F040h + 00h ; Host Control Register
```

```
xor al, al ; Clear previous commands
```

```
out dx, al
```

```
call Delay5ms
```

```
mov dx, F040h + 04h ; Transmit Slave Address Register
```

```
mov al, ch ; Set the slave address and
```

```
out dx, al ; prepare for a WRITE command
```

```
mov dx, F040h + 05h ; Host Command Register
```

```
mov al, cl ; offset to write
```

```
out dx, al
```

```
mov dx, F040h + 06h
```

```
mov al, ah
```

```
out dx, al
```

```
mov dx, F040h + 01h ; Host Status Register
```

```
mov al, 07h ; Clear all status bits
```

```
out dx, al
mov dx, F040h + 00h ; Host Control Register
mov al, 12h ; Start a byte access
out dx, al
call CT_Chk_SMBus_Ready ;R14
ret
Ct_I2CWriteByte Endp
; Wait until the busy bit clears, indicating that the SMBUS
; activity has concluded.
CT_Chk_SMBus_Ready Proc Near
mov dx, F040h + 01h ; Host Status Register
Check_I2C_ByteRead_ForBusy:
in al, dx
test al, 08h
jnz Check_I2C_ByteRead_ForBusy
Check_I2C_ByteRead_ForStatus:
in al, dx
test al, 07h ; HSTS[2:0]=All clearable status bits
jz Check_I2C_ByteRead_ForStatus
ret
CT_Chk_SMBus_Ready Endp
END begin
```

# Appendix E

---

PICO-APL1-SEMI Quick Installation Guide

## E.1 Packing List

Before setting up your product, please make sure the following items have been shipped:

Item	Description	Remark
1	PICO-APL1	MB
2	Chassis (Major parts)	
3	Bottom Cover of Chassis	
4	Accessory kits (w/ power button)	
5	Driver DVD w/User Manual (in pdf)	
6	QIG ( This Doc.)	A0.3

1



2



3



4



5



## E.2 Assembly procedure

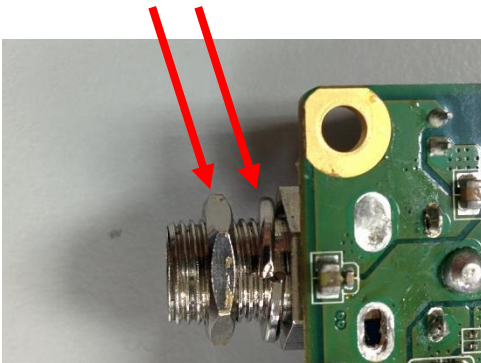
---

### Step 1. Assemble the MB

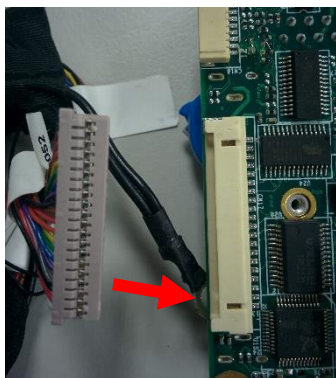
- a. Insert memory into the socket at about 30 degrees. Push it down until it is attached.



- b. Loosen the hexagon shim ring of the DC-Jack on the MB (including a circular shim ring and a hexagonal shim ring).

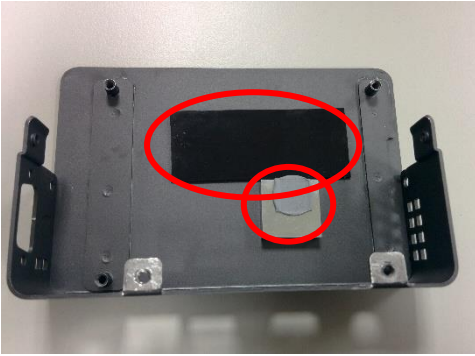


- c. Insert the COM Port 1/2 & line out connector cable until it clicks in (as in the picture below).

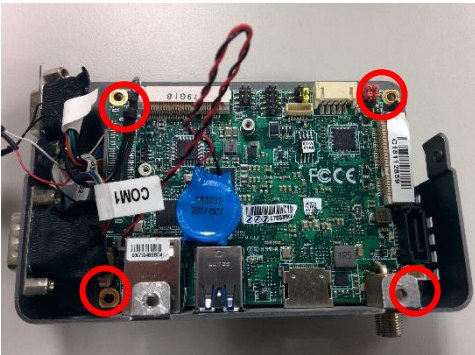


## Step 2. Implement MB into the Chassis

- a. Remove the protection liner from thermal PAD.

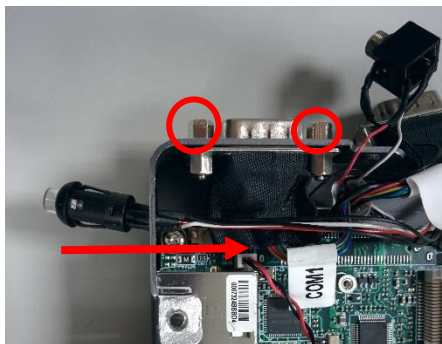


- b. Install the MB into the chassis, then fasten 4 screws in the corner to the Chassis).





- c. Fasten 2 screws on the side of the chassis for COM Port.
- d. Thread the power button cable from outside to inside of the chassis.

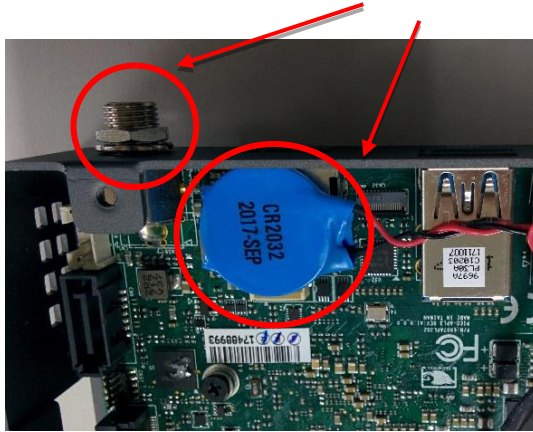


- e. Connect the power button cable to CN3 PIN1,2,3.

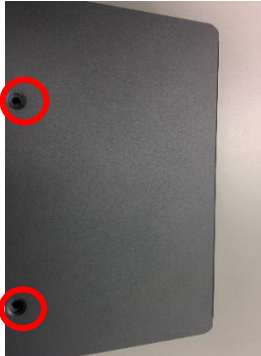


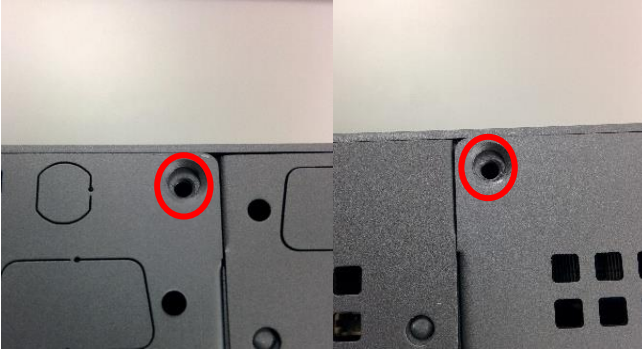
### Step 3. Complete the system

- a. Fasten the hexagon shim ring of DC-Jack on MB
- b. Stick the battery to the board



- c. Put the two sides of the chassis together
- d. Fasten the chassis with four flat black screws





# Appendix F

---

PICO-APL1 AI Core Kit Installation Guide

## F.1 Product Brief

---

The AAeon PICO-APL1 AI (artificial intelligence) Core product is bundled with the Intel Movidius Myriad 2 VPU. Before you start to set up the development environment, we suggest you prepare the following items:

- 1 Up to 2G DRAM
- 2 At least 4GB of free storage space connected to the CN8 or CN12 SATA connector for SATA +5V power
- 3 HDMI monitor
- 4 USB keyboard/mouse
- 5 Ubuntu 16.04
- 6 An Internet connection

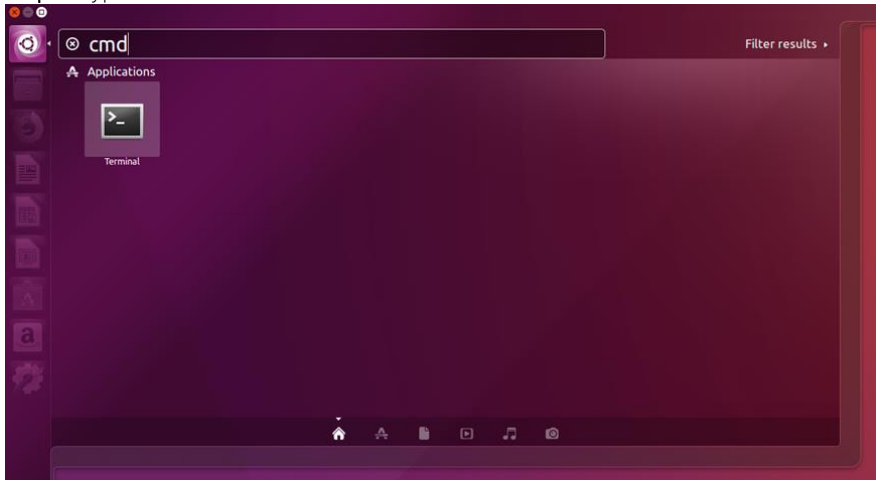
Connect all the above peripherals, then power on and go into CMD (command mode) in Ubuntu.

## F.2 Update Ubuntu and Kernel

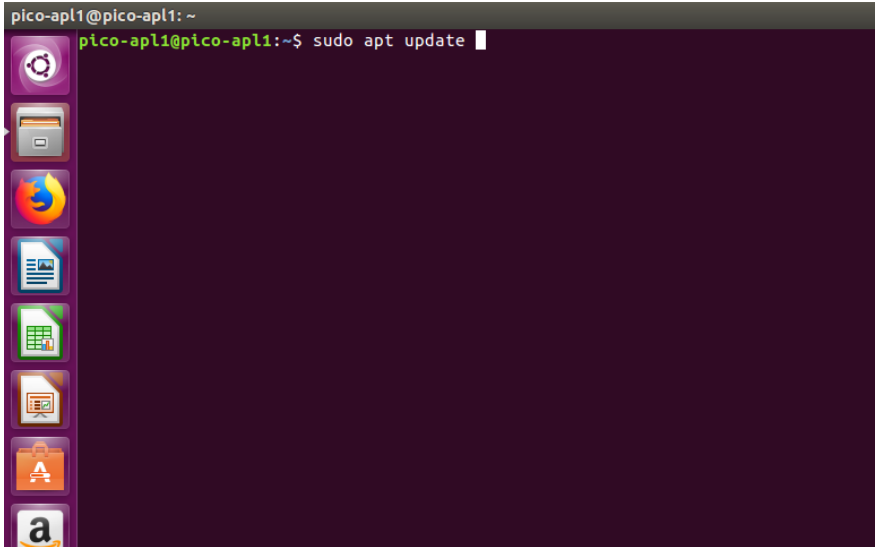
**Step 1.** To open the terminal, select search



**Step 2.** Type 'cmd' or 'terminal'



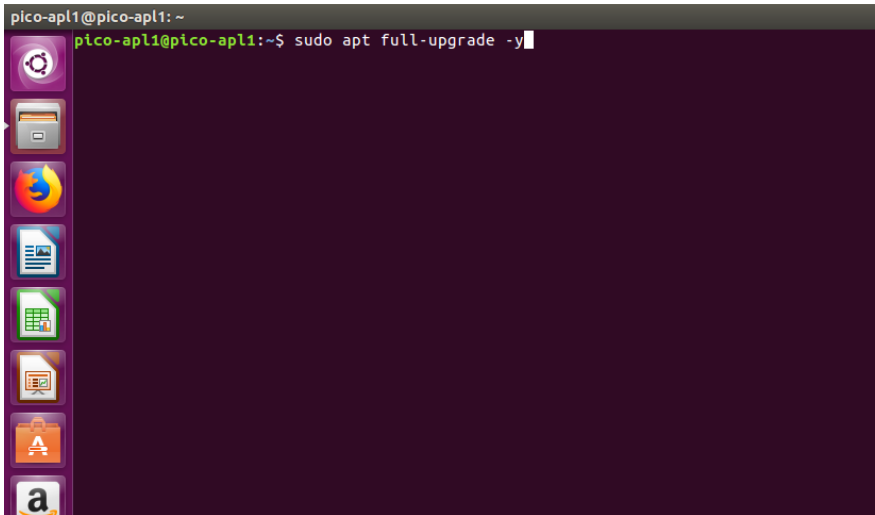
Step 3. Type 'sudo apt update'



```
pico-apl1@pico-apl1: ~  
pico-apl1@pico-apl1:~$ sudo apt update
```

The screenshot shows a terminal window with a dark purple background. On the left side, there is a vertical dock containing several application icons: a gear (system settings), a folder (file manager), Firefox, LibreOffice Writer, LibreOffice Calc, LibreOffice Impress, and Amazon. The terminal prompt is 'pico-apl1@pico-apl1: ~'. The command 'sudo apt update' has been entered and is followed by a white cursor.

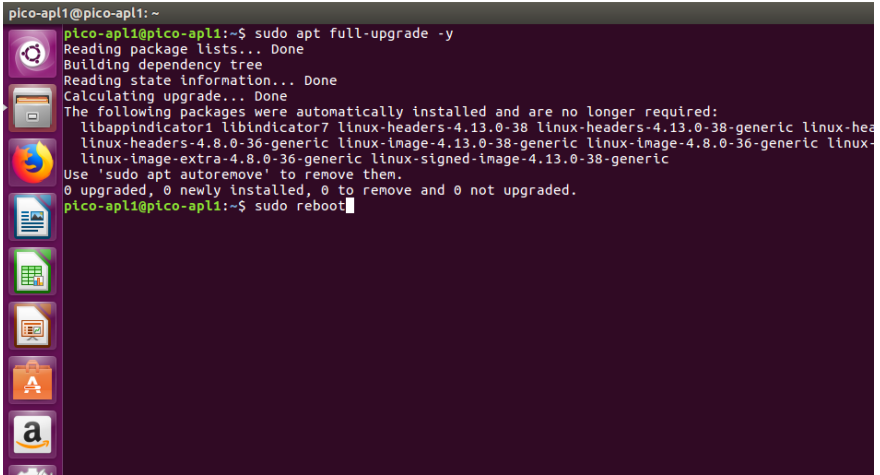
Step 4. Type 'sudo apt full-upgrade -y'



```
pico-apl1@pico-apl1: ~  
pico-apl1@pico-apl1:~$ sudo apt full-upgrade -y
```

The screenshot shows a terminal window with a dark purple background. On the left side, there is a vertical dock containing several application icons: a gear (system settings), a folder (file manager), Firefox, LibreOffice Writer, LibreOffice Calc, LibreOffice Impress, and Amazon. The terminal prompt is 'pico-apl1@pico-apl1: ~'. The command 'sudo apt full-upgrade -y' has been entered and is followed by a white cursor.

Step 5. Type 'sudo reboot' and the computer will restart



```
pico-apl1@pico-apl1:~  
pico-apl1@pico-apl1:~$ sudo apt full-upgrade -y  
Reading package lists... Done  
Building dependency tree  
Reading state information... Done  
Calculating upgrade... Done  
The following packages were automatically installed and are no longer required:  
  libappindicator1 libindicator7 linux-headers-4.13.0-38 linux-headers-4.13.0-38-generic linux-headers-4.8.0-36-generic linux-image-4.13.0-38-generic linux-image-4.8.0-36-generic linux-image-extra-4.8.0-36-generic linux-signed-image-4.13.0-38-generic  
Use 'sudo apt autoremove' to remove them.  
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.  
pico-apl1@pico-apl1:~$ sudo reboot
```

Step 6. After the restart, open the terminal again

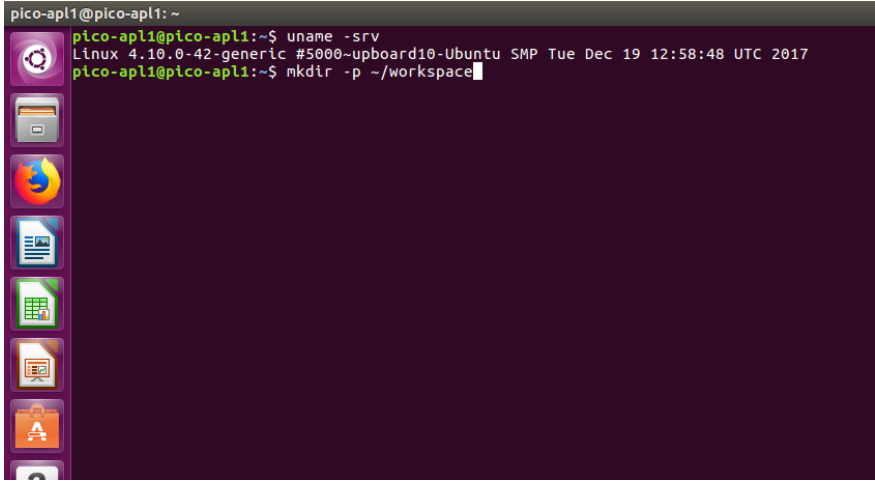


## F.3 Install NCSDK

---

(Please refer to <https://developer.movidius.com/start>)

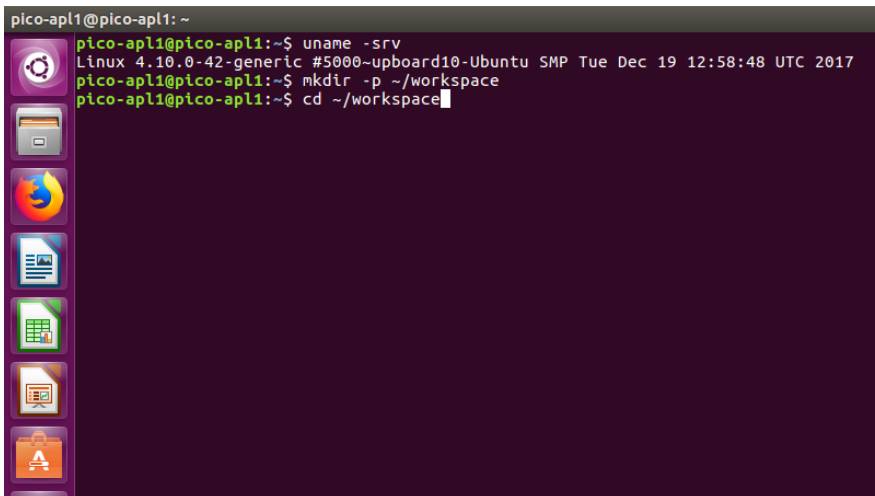
### Step 1. Type 'mkdir -p ~/workspace'



A terminal window on a PICO-APL1 board. The prompt is 'pico-apl1@pico-apl1: ~'. The user enters 'uname -srv' and the output is 'Linux 4.10.0-42-generic #5000-upboard10-Ubuntu SMP Tue Dec 19 12:58:48 UTC 2017'. Then the user enters 'mkdir -p ~/workspace' and the prompt returns.

```
pico-apl1@pico-apl1: ~
pico-apl1@pico-apl1:~$ uname -srv
Linux 4.10.0-42-generic #5000-upboard10-Ubuntu SMP Tue Dec 19 12:58:48 UTC 2017
pico-apl1@pico-apl1:~$ mkdir -p ~/workspace
```

### Step 2. Type 'cd~/workspace'



A terminal window on a PICO-APL1 board. The prompt is 'pico-apl1@pico-apl1: ~'. The user enters 'uname -srv' and the output is 'Linux 4.10.0-42-generic #5000-upboard10-Ubuntu SMP Tue Dec 19 12:58:48 UTC 2017'. Then the user enters 'mkdir -p ~/workspace'. Then the user enters 'cd ~/workspace' and the prompt returns.

```
pico-apl1@pico-apl1: ~
pico-apl1@pico-apl1:~$ uname -srv
Linux 4.10.0-42-generic #5000-upboard10-Ubuntu SMP Tue Dec 19 12:58:48 UTC 2017
pico-apl1@pico-apl1:~$ mkdir -p ~/workspace
pico-apl1@pico-apl1:~$ cd ~/workspace
```

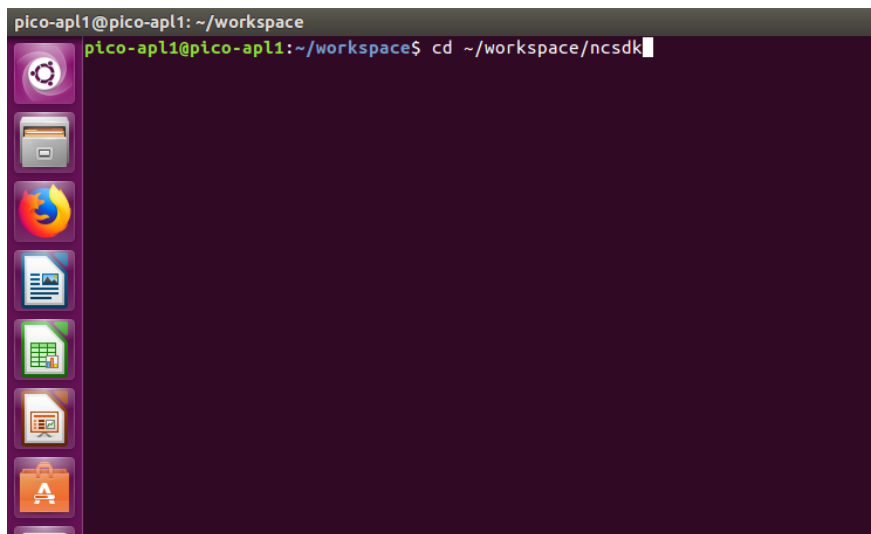
### Step 3. Type 'sudo apt install git'

```
pico-apl1@pico-apl1: ~/workspace
pico-apl1@pico-apl1:~$ uname -srv
Linux 4.10.0-42-generic #5000-upboard10-Ubuntu SMP Tue Dec 19 12:58:48 UTC 2017
pico-apl1@pico-apl1:~$ mkdir -p ~/workspace
pico-apl1@pico-apl1:~$ cd ~/workspace
pico-apl1@pico-apl1:~/workspace$ sudo apt install git
```

### Step 4. Type 'git clone <https://github.com/movidius/ncsdk.git>'

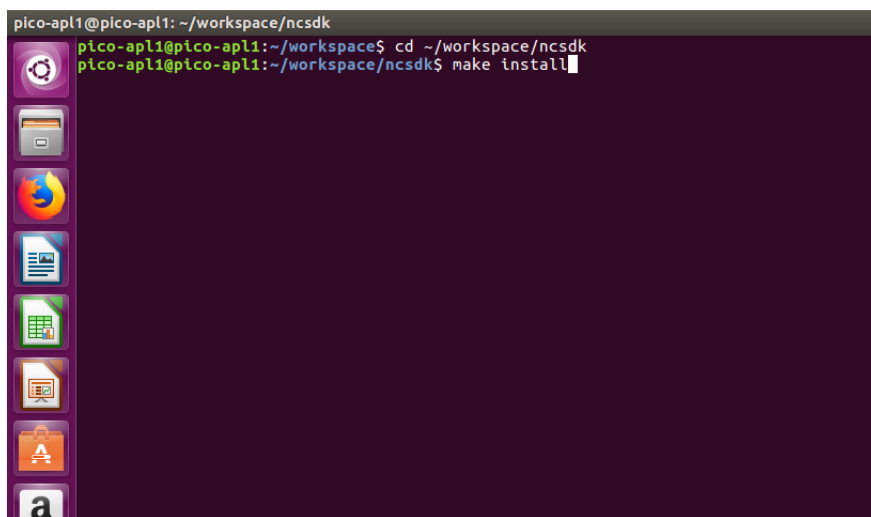
```
pico-apl1@pico-apl1: ~/workspace
pico-apl1@pico-apl1:~$ uname -srv
Linux 4.10.0-42-generic #5000-upboard10-Ubuntu SMP Tue Dec 19 12:58:48 UTC 2017
pico-apl1@pico-apl1:~$ mkdir -p ~/workspace
pico-apl1@pico-apl1:~$ cd ~/workspace
pico-apl1@pico-apl1:~/workspace$ sudo apt install git
[sudo] password for pico-apl1:
Reading package lists... Done
Building dependency tree
Reading state information... Done
git is already the newest version (1:2.7.4-0ubuntu1.3).
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
pico-apl1@pico-apl1:~/workspace$ git clone https://github.com/movidius/ncsdk.git
```

Step 5. Type 'cd ~/workspace/ncsdk'



```
pico-apl1@pico-apl1: ~/workspace
pico-apl1@pico-apl1:~/workspace$ cd ~/workspace/ncsdk
```

Step 6. Type 'make install'



```
pico-apl1@pico-apl1: ~/workspace/ncsdk
pico-apl1@pico-apl1:~/workspace$ cd ~/workspace/ncsdk
pico-apl1@pico-apl1:~/workspace/ncsdk$ make install
```

**Note:** If the installation fails, run 'make install' again.

## F.4 Download Movidius Ncappzoo

### Step 1. Type 'cd ~/workspace'

```
pico-apl1@pico-apl1: ~/workspace/ncsdk
Adding caffe to PYTHONPATH
export PYTHONPATH="$PYTHONPATH:/opt/movidius/caffe/python"
Removing NCSDK toolkit file.../usr/local/bin/mvNCCheck
Removing NCSDK toolkit file.../usr/local/bin/mvNCCProfile
Removing NCSDK toolkit file.../usr/local/bin/mvNCCCompile
Removing NCSDK toolkit file.../usr/local/bin/ncsdk
dpkg-query: package 'python3-mvnc' is not installed and no information is available
Use dpkg --info (= dpkg-deb --info) to examine archive files,
and dpkg --get-selections (= dpkg-deb --get-selections) to list their contents.
dpkg-query: package 'mvnc-dev' is not installed and no information is available
Use dpkg --info (= dpkg-deb --info) to examine archive files,
and dpkg --get-selections (= dpkg-deb --get-selections) to list their contents.
dpkg-query: package 'mvnc' is not installed and no information is available
Use dpkg --info (= dpkg-deb --info) to examine archive files,
and dpkg --get-selections (= dpkg-deb --get-selections) to list their contents.
Processing ./NCSDK/ncsdk-x86_64/apl
Installing collected packages: mvnc
Found existing installation: mvnc 1.12.0.1
Uninstalling mvnc-1.12.0.1:
Successfully uninstalled mvnc-1.12.0.1
Running setup.py install for mvnc: started
Running setup.py install for mvnc: finished with status 'done'
Successfully installed mvnc-1.12.0.1
Processing ./NCSDK/ncsdk-x86_64/apl
Installing collected packages: mvnc
Found existing installation: mvnc 1.12.0.1
Uninstalling mvnc-1.12.0.1:
Successfully uninstalled mvnc-1.12.0.1
Running setup.py install for mvnc: started
Running setup.py install for mvnc: finished with status 'done'
Successfully installed mvnc-1.12.0.1
NCS Libraries have been installed in /usr/local/lib
NCS Toolkit binaries have been installed in /usr/local/bin
NCS Include files have been installed in /usr/local/include
NCS Python API has been installed in /opt/movidius, and PYTHONPATH environment variable updated
Updatingudev rules...
Adding user 'pico-apl1' to 'users' group
Setup is complete.
The PYTHONPATH environment variable was added to your .bashrc as described in the Caffe documentation.
Keep in mind that only newly spawned terminals can see this variable!
This means that you need to open a new terminal in order to be able to use the NCSDK.
Please provide feedback in our support forum if you encountered difficulties.
pico-apl1@pico-apl1:~/workspace/ncsdk$ cd ~/workspace
```

Step 2. Type 'git clone <https://github.com/movidius/ncappzoo>'

```
pico-apl1@pico-apl1: ~/workspace
export PYTHONPATH=${PYTHONPATH}:/opt/movidius/caffe/python"
Removing NCSDK toolkit file.../usr/local/bin/mvNCCheck
Removing NCSDK toolkit file.../usr/local/bin/mvNCPProfile
Removing NCSDK toolkit file.../usr/local/bin/mvNCCompile
Removing NCSDK toolkit file.../usr/local/bin/ncsdk
dpkg-query: package 'python3-mvnc' is not installed and no information is available
Use dpkg --info (= dpkg-deb --info) to examine archive files,
and dpkg --contents (= dpkg-deb --contents) to list their contents.
dpkg-query: package 'mvnc-dev' is not installed and no information is available
Use dpkg --info (= dpkg-deb --info) to examine archive files,
and dpkg --contents (= dpkg-deb --contents) to list their contents.
dpkg-query: package 'mvnc' is not installed and no information is available
Use dpkg --info (= dpkg-deb --info) to examine archive files,
and dpkg --contents (= dpkg-deb --contents) to list their contents.
Processing ./NCSDK/ncsdk-x86_64/api
Installing collected packages: mvnc
  Found existing installation: mvnc 1.12.0.1
  Uninstalling mvnc-1.12.0.1:
    Successfully uninstalled mvnc-1.12.0.1
  Running setup.py install for mvnc: started
  Running setup.py install for mvnc: finished with status 'done'
Successfully installed mvnc-1.12.0.1
Processing ./NCSDK/ncsdk-x86_64/api
Installing collected packages: mvnc
  Found existing installation: mvnc 1.12.0.1
  Uninstalling mvnc-1.12.0.1:
    Successfully uninstalled mvnc-1.12.0.1
  Running setup.py install for mvnc: started
  Running setup.py install for mvnc: finished with status 'done'
Successfully installed mvnc-1.12.0.1
NCS Libraries have been installed in /usr/local/lib
NCS Toolkit binaries have been installed in /usr/local/bin
NCS Include files have been installed in /usr/local/include
NCS Python API has been installed in /opt/movidius, and PYTHONPATH environment variable
Updating udev rules...
Adding user 'pico-apl1' to 'users' group
Setup is complete.
The PYTHONPATH environment variable was added to your .bashrc as described in the Caffe d
Keep in mind that only newly spawned terminals can see this variable!
This means that you need to open a new terminal in order to be able to use the NCSDK.
Please provide feedback in our support forum if you encountered difficulties.
pico-apl1@pico-apl1:~/workspace/ncsdk$ cd ~/workspace
pico-apl1@pico-apl1:~/workspace$ git clone https://github.com/movidius/ncappzoo
```

Step 3. Type 'cd ~/workspace/ncappzo/apps/street\_cam && make opencv'

After installing NCSDK, Ncappzoo and OpenCV, you can start running demos.

**Step 1.** Type `cd ~/workspace/ncappzoo/apps'`

**Step 2.** Type `'ls -l'`

You will see the names of many different folders. Choose one you want.

```
pico-apl1@pico-apl1: ~/workspace/ncappzoo/apps
pico-apl1@pico-apl1:~/workspace$ cd ~/workspace/ncappzoo/apps
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps$ ls -l
total 104
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 benchmarkncls
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  11 17:15 birds
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 classifier-gui
drwxrwxr-x 7 pico-apl1 pico-apl1 4096  11 17:11 gender_age_lbp
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  11 16:11 hello_ncs_cpp
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 hello_ncs_py
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 image-classifier
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 live-image-classifier
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 log-image-classifier
-rw-rw-r-- 1 pico-apl1 pico-apl1  553  11 16:11 Makefile
drwxrwxr-x 4 pico-apl1 pico-apl1 4096  11 17:12 multistick_cpp
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 Multistick_GoogleNet
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 Multistick_TF_Inception
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 16:11 rapid-image-cclassifier
-rw-rw-r-- 1 pico-apl1 pico-apl1 9148  11 16:11 README.md
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  11 16:11 stream_infer
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 17:13 stream_ty_gn
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 17:15 stream_ty_gn_threaded
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 17:15 street_cam
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  11 17:16 street_cam_threaded
drwxrwxr-x 4 pico-apl1 pico-apl1 4096  12 11:43 topcoder_example
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  14 12:47 video_face_matcher
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  11 16:11 video_face_matcher_multipleFace
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  13 14:00 video_objects
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps$
```

Step 3. Type 'cd <folder's name>'

Step 4. Type 'make help'

You will see all the commands you can use on each page.

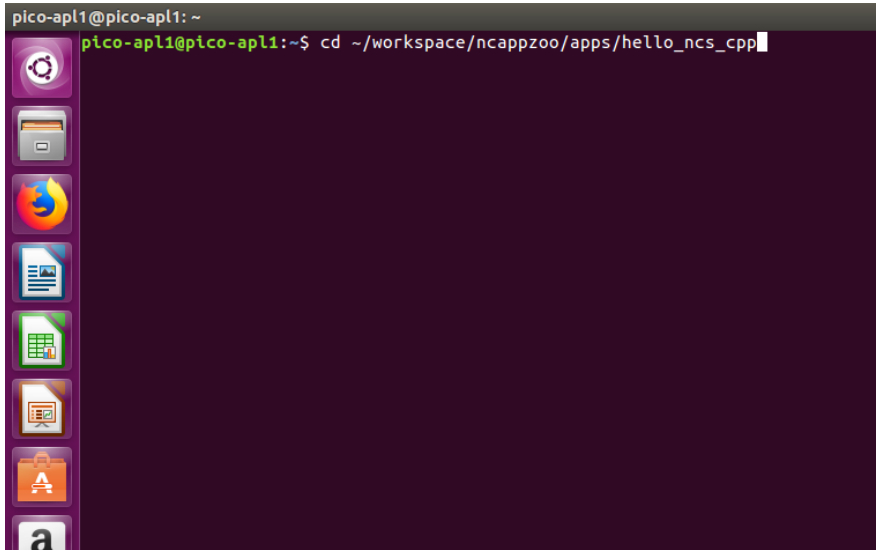
```
pico-apl1@pico-apl1: ~/workspace/ncappzoo/apps
pico-apl1@pico-apl1:~/workspace$ cd ~/workspace/ncappzoo/apps
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps$ ls -l
total 104
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 benchmarkncls
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  四 11 17:15 birds
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 classifier-gui
drwxrwxr-x 7 pico-apl1 pico-apl1 4096  四 11 17:11 gender_age_lbp
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  四 11 16:11 hello_ncs_cpp
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 hello_ncs_py
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 image-classifier
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 live-image-classifier
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 log-image-classifier
-rw-rw-r-- 1 pico-apl1 pico-apl1 553  四 11 16:11 Makefile
drwxrwxr-x 4 pico-apl1 pico-apl1 4096  四 11 17:12 multistick_cpp
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 MultiStick_GoogLeNet
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 MultiStick_TF_Inception
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 16:11 rapid-image-classifier
-rw-rw-r-- 1 pico-apl1 pico-apl1 9148  四 11 16:11 README.md
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  四 11 16:11 stream_infer
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 17:13 stream_ty_gn
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 17:15 stream_ty_gn_threaded
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 17:15 street_cam
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 11 17:16 street_cam_threaded
drwxrwxr-x 4 pico-apl1 pico-apl1 4096  四 12 11:43 topcoder_example
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  四 14 12:47 video_face_matcher
drwxrwxr-x 3 pico-apl1 pico-apl1 4096  四 11 16:11 video_face_matcher_multipleFace
drwxrwxr-x 2 pico-apl1 pico-apl1 4096  四 13 14:00 video_objects
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps$ make help
Possible make targets:
make help - shows this message
make all - does make all in each sub directory
make clean - does make clean in each subdirectory
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps$
```

## F.5 Example in Movidius Ncappzoo

---

\*(example: `cd ~/workspace/ncappzoo/apps/hello_ncs_cpp && make run`)

**Step 1.** Type `'cd ~/workspace/ncappzoo/apps/hello_ncs_cpp'`



```
pico-apl1@pico-apl1: ~  
pico-apl1@pico-apl1:~$ cd ~/workspace/ncappzoo/apps/hello_ncs_cpp
```

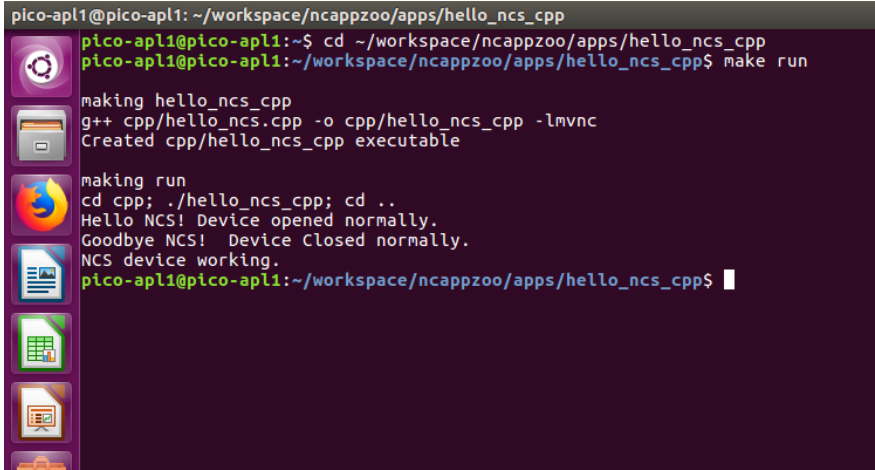
The image shows a terminal window with a dark purple background. On the left side, there is a vertical dock containing several application icons: a gear (system settings), a folder (file manager), a Firefox browser, a document with a magnifying glass (text editor), a spreadsheet (LibreOffice Calc), a presentation (LibreOffice Impress), a briefcase (software center), and a letter 'a' (application launcher). The terminal prompt is `pico-apl1@pico-apl1: ~` and the command `cd ~/workspace/ncappzoo/apps/hello_ncs_cpp` has been entered, with a cursor at the end of the line.



**Step 2.** Type 'make help'

You will see all the commands you can use on each page.

**Step 3.** Type 'make run'

A terminal window screenshot showing the execution of 'make run' in a PICO-APL1 environment. The terminal has a dark purple background and a light-colored text. The prompt is 'pico-apl1@pico-apl1: ~/workspace/ncappzoo/apps/hello\_ncs\_cpp'. The user enters 'cd ~/workspace/ncappzoo/apps/hello\_ncs\_cpp' and then 'make run'. The output shows the compilation of 'hello\_ncs.cpp' and the execution of the 'run' target, which prints 'Hello NCS! Device opened normally.', 'Goodbye NCS! Device Closed normally.', and 'NCS device working.'.

```
pico-apl1@pico-apl1: ~/workspace/ncappzoo/apps/hello_ncs_cpp
pico-apl1@pico-apl1:~$ cd ~/workspace/ncappzoo/apps/hello_ncs_cpp
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps/hello_ncs_cpp$ make run
making hello_ncs_cpp
g++ cpp/hello_ncs.cpp -o cpp/hello_ncs_cpp -lmvnc
Created cpp/hello_ncs_cpp executable

making run
cd cpp; ./hello_ncs_cpp; cd ..
Hello NCS! Device opened normally.
Goodbye NCS! Device Closed normally.
NCS device working.
pico-apl1@pico-apl1:~/workspace/ncappzoo/apps/hello_ncs_cpp$
```

## F.6 Appendix

---

With some relative directories, for example “video or graphic” relative directories, you need to install “*opencv*” before you can start working.

You can install “*opencv*” in the following directory:

```
cd~ workspace/ncappzo/apps/stree_cam
make opencv.
```

### Other

Some demos might need 2 or more Movidius modules, an Internet connection or a USB Camera. Customers can purchase more USB type Movidius Neural Compute Sticks and plug them in to a USB port.

Good link to check:

<https://developer.movidius.com/start>

<https://github.com/movidius/ncappzoo>

### AAEON Accessory:

968C064G52 : 64GB SATA DOM with Power Cable.

PICO-APL1-HSP01: Heat-spreader

PICO-APL1-HSK01: Heat-sink, to be used with Heat-spreader