

# BOXER-8220AI

Compact Fanless Embedded AI@Edge Box PC with NVIDIA® Jetson Nano<sup>™</sup> User's Manual 4<sup>th</sup> Ed

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#### Packing List

Compact Fanless Embedded Al@Edge Box PC

Before setting up your product, please make sure the following items have been shipped:

ltem		Quantity
•	BOXER-8220AI	1
•	Wall mount bracket	2
•	Power Connector	1

If any of these items are missing or damaged, please contact your distributor or sales representative immediately.

This User's Manual contains all the essential information, such as detailed descriptions and explanations on the product's hardware and software features (if any), its specifications, dimensions, jumper/connector settings/definitions, and driver installation instructions (if any), to facilitate users in setting up their product.

Users may refer to the AAEON.com for the latest version of this document.

# BOXER-8220AI

#### Safety Precautions

Please read the following safety instructions carefully. It is advised that you keep this manual for future references

- 1. All cautions and warnings on the device should be noted.
- All cables and adapters supplied by AAEON are certified and in accordance with the material safety laws and regulations of the country of sale. Do not use any cables or adapters not supplied by AAEON to prevent system malfunction or fires.
- 3. Make sure the power source matches the power rating of the device.
- 4. Position the power cord so that people cannot step on it. Do not place anything over the power cord.
- Always completely disconnect the power before working on the system's hardware.
- No connections should be made when the system is powered as a sudden rush of power may damage sensitive electronic components.
- If the device is not to be used for a long time, disconnect it from the power supply to avoid damage by transient over-voltage.
- 8. Always disconnect this device from any AC supply before cleaning.
- 9. While cleaning, use a damp cloth instead of liquid or spray detergents.
- 10. Make sure the device is installed near a power outlet and is easily accessible.
- 11. Keep this device away from humidity.
- 12. Place the device on a solid surface during installation to prevent falls
- 13. Do not cover the openings on the device to ensure optimal heat dissipation.
- 14. Watch out for high temperatures when the system is running.
- 15. Do not touch the heat sink or heat spreader when the system is running
- 16. Never pour any liquid into the openings. This could cause fire or electric shock.

Preface

- 17. As most electronic components are sensitive to static electrical charge, be sure to ground yourself to prevent static charge when installing the internal components. Use a grounding wrist strap and contain all electronic components in any static-shielded containers.
- 18. If any of the following situations arises, please the contact our service personnel:
  - i. Damaged power cord or plug
  - ii. Liquid intrusion to the device
  - iii. Exposure to moisture
  - Device is not working as expected or in a manner as described in this manual
  - v. The device is dropped or damaged
  - vi. Any obvious signs of damage displayed on the device

19. DO NOT LEAVE THIS DEVICE IN AN UNCONTROLLED ENVIRONMENT WITH TEMPERATURES BEYOND THE DEVICE'S PERMITTED STORAGE TEMPERATURES (SEE CHAPTER 1) TO PREVENT DAMAGE.

#### FCC Statement



This device complies with Part 15 FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received including interference that may cause undesired operation.

#### Caution:

There is a danger of explosion if the battery is incorrectly replaced. Replace only with the same or equivalent type recommended by the manufacturer. Dispose of used batteries according to the manufacturer's instructions and your local government's recycling or disposal directives.

#### Attention:

Il y a un risque d'explosion si la batterie est remplacée de façon incorrecte. Ne la remplacer qu'avec le même modèle ou équivalent recommandé par le constructeur. Recycler les batteries usées en accord avec les instructions du fabricant et les directives gouvernementales de recyclage.

# China RoHS Requirements (CN)

# 产品中有毒有害物质或元素名称及含量

#### AAEON System

#### QO4-381 Rev.A0

	有毒有害物质或元素					
部件名称	铅	汞	镉	六价铬	多溴联苯	多溴二苯
	(Pb)	(Hg)	(Cd)	(Cr(VI))	(PBB)	醚(PBDE)
印刷电路板		0	0	0	$\cap$	$\sim$
及其电子组件	×	0	0	0	0	0
外部信号		0	0	0	$\bigcirc$	$\sim$
连接器及线材	×	0	0	0	0	0
外壳	0	0	0	0	0	0
中央处理器	×	0	0	0	$\bigcirc$	$\bigcirc$
与内存	×	0	0	0	0	0
硬盘	×	0	0	0	0	0
液晶模块	×	×	0	0	0	0
光驱	×	0	0	0	0	0
触控模块	×	0	0	0	0	0
电源	×	0	0	0	0	0
电池	×	0	0	0	0	0

本表格依据 SJ/T 11364 的规定编制。

〇:表示该有毒有害物质在该部件所有均质材料中的含量均在 GB/T 26572标准规定的限量要求以下。

×:表示该有害物质的某一均质材料超出了GB/T 26572的限量要求,然而该 部件

仍符合欧盟指令2011/65/EU 的规范。

备注:

一、此产品所标示之环保使用期限,系指在一般正常使用状况下。

二、上述部件物质中央处理器、内存、硬盘、光驱、电源为选购品。

三、上述部件物质液晶模块、触控模块仅一体机产品适用。

# **Hazardous and Toxic Materials List**

# AAEON System

# QO4-381 Rev.A0

		Haz	ardous or	Toxic Materia	als or Elements	5
Component Name	Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Hexavalent Chromium (Cr(VI))	Polybrominat ed biphenyls (PBBs)	Polybrominat ed diphenyl ethers (PBDEs)
PCB and Components	Х	0	0	0	0	0
Wires & Connectors for Ext.Connections	Х	0	0	0	0	0
Chassis	0	0	0	0	0	0
CPU & RAM	Х	0	0	0	0	0
HDD Drive	Х	0	0	0	0	0
LCD Module	Х	Х	0	0	0	0
Optical Drive	Х	0	0	0	0	0
Touch Control Module	Х	0	0	0	0	0
PSU	Х	0	0	0	0	0
Battery	Х	0	0	0	0	0

This form is prepared in compliance with the provisions of SJ/T 11364.

O: The level of toxic or hazardous materials present in this component and its parts is below the limit specified by GB/T 26572.

X: The level of toxic of hazardous materials present in the component exceed the limits specified by GB/T 26572, but is still in compliance with EU Directive 2011/65/EU (RoHS 2).

Notes:

1. The Environment Friendly Use Period indicated by labelling on this product is applicable only to use under normal conditions.

2. Individual components including the CPU, RAM/memory, HDD, optical drive, and PSU are optional.

3. LCD Module and Touch Control Module only applies to certain products which feature these components.

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# Chapter 1

Product Specifications

# 1.1 Specifications

System	
AI Accelerator	NVIDIA® Jetson Nano™
CPU	Quad Core ARM® Cortex®-A57 MPCore
	Proccessor
System Memory	4GB LPDDR4
Storage Device	16GB microSD or eMMC
Display Interface	HDMI 2.0
Ethernet	10/100/1000Base-TX x 5
I/O	USB 3.2 Gen 1 x 4
	LAN x 5
	RS-232 x 2
	HDMI x 1
	Micro-USB for Flash OS x 1
	DC Power Input x 1
	Power Button x 1
	Recovery Button x 1
Expansion	—
Indicator	Power LED x 1
OS Support	Linux (AAEON ACLinux 4.9)
	Linux (NVIDIA JetPack 4.5)

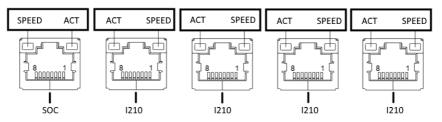
Power Supply	
Power Requirement	10~24V DC with 2-pin terminal block
Mechanical	
Mounting	Wallmount
Dimensions (W x D x H)	6.06" x 3.98" x 1.18" (154 mm x 101 mm x 30 mm)
Gross Weight	4.40 lbs. (2 kg)
Net Weight	2.20 lbs. (1 kg)
Environmental	
Operating Temperature	-4°F ~ 140°F (-20°C ~ 60°C, according to
	IEC60068-2 with 0.5 m/s airflow)
Storage Temperature	-49°F ~ 176°F (-45°C ~ 80°C)
Storage Humidity	95% at 40°C, non-condensing
Anti-Vibration	3 Grms/ 5 ~ 500Hz/ operation – eMMC

#### 1.2 Product Notice

Micro-USB: Micro-USB port is ideally for flashing image only.

USB ports: USB ports are not support USB DVD ROM because of file system.

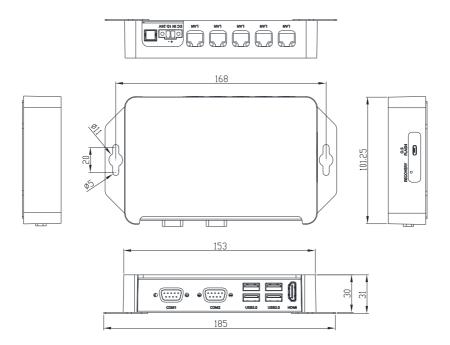
LAN Indicator Behavior:



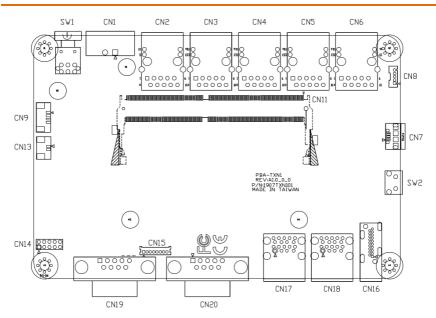
# Chapter 2

Hardware Information

## 2.1 Dimensions



#### 2.2 Jumpers and connectors



#### 2.3 List of Jumpers

The board has a number of jumpers that allow you to configure your system to suit your application.

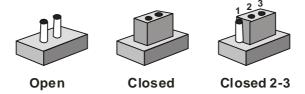
The table below shows the function of each of the board's jumpers

Label	Function
CN14 (Pin 7-8)	AT/ATX mode select

#### 2.3.1 Setting Jumpers

You can configure your system to match the needs of your application by setting jumpers. A jumper is the simplest kind of electric switch. It consists of two metal pins and a small metal clip (often protected by a plastic cover) that slides over the pins to connect them. To "close" a jumper you connect the pins with the clip. To "open" a jumper you remove the clip. Sometimes a jumper will have three pins,

labeled 1, 2 and 3. In this case you would connect either pins 1 and 2 or 2 and 3.



A pair of needle-nose pliers may be helpful when working with jumpers.

If you have any questions about the best hardware configuration for your application,

contact your local distributor or sales representative before you make any changes.

Generally, you simply need a standard cable to make most connections.

The AT/ATX Mode Select functions by connecting pins 7 and 8 of CN14. To prevent damage to the system, do not connect pins 7 and 8 to any other pin.





Closed – ATX Mode (Default)

8

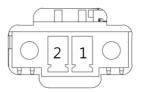
CN14 pins 7-8	Function
7-8 Open	AT Power Mode
7-8 Closed	ATX Power Mode (Default)

# 2.4 List of Connectors

The board has a number of connectors that allow you to configure your system to suit your application.

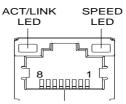
The table below shows the function of each of the board's connectors

Label	Function
CN1	DC Power In connector
CN2	Jetson NANO Giga LAN Connector
CN3	I210AT Giga LAN Connector
CN4	I210AT Giga LAN Connector
CN5	I210AT Giga LAN Connector
CN6	I210AT Giga LAN Connector
CN7	USB 2.0 Connector for Flash Image
CN8	USB 2.0 Connector
CN9	FAN Connector
CN11	Jetson NANO CPU module connector
CN13	RTC Battery Connector
CN14	Front Panel Connector
CN15	Debug UART/I2C
CN16	HDMI connector
CN17	USB 3.0 Connector
CN18	USB 3.0 Connector
CN19	COM 1 connector /dev/ttyTHS1
CN20	COM 2 connector /dev/ttyTHS2
SW1	Power switch
SW2	Recovery switch



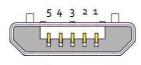
Pin	Signal	Pin	Signal
1	PWR IN	2	GND

# 2.4.2 LAN RJ45 Port (CN2-CN6)



Pin	Signal	Pin	Signal
1	MDI0+	2	MDI0-
3	MDI1+	4	MDI1-
5	MDI2+	6	MDI2-
7	MDI3+	8	MDI3-

**Note:** CN2 is the Jetson Nano Gigabit LAN port. Ports CN3, CN4, CN5, and CN6 are I210AT Gigabit LAN Ports.





Pin	Signal	Pin	Signal	
1		2	USB1-	
3	USB1+	4		
5	GND			

# 2.4.4 Jetson Nano CPU Module Connector (CN11)

Signal Name	Pin # Top Odd	Pin # Bottom Even	Signal Name	Signal Name	Pin # Top Odd	Pin # Bottom Even	Signal Name
GND	1	2	GND	PCIE0 RX0 P	133	134	PCIE0 TX0 N
CSI1 D0 N	3	4	CSI0 D0 N	GND	135	136	PCIE0 TX0 P
CSI1 D0 P	5	6	CSI0 D0 P	PCIED RX1 N	137	138	GND
GND	7	8	GND	PCIE0 RX1 P	139	140	PCIE0 TX1 N
RSVD	9	10	CSI0 CLK N	GND	141	142	PCIE0 TX1 P
RSVD	11	12	CSI0 CLK P	RSVD	143	144	GND
GND	13	14	GND	KEY	KEY	KEY	KEY
CSI1 D1 N	15	16	CSI0 D1 N	RSVD	145	146	GND
CSI1 D1 P	17	18	CSI0 D1 N	GND	143	148	PCIE0 TX2 N
	19	20		PCIE0 RX2 N	149	150	
GND		20	GND		149		PCIE0_TX2_P
CSI3_D0_N	21		CSI2_D0_N	PCIE0_RX2_P		152	GND
CSI3 D0 P	23	24	CSI2 D0 P	GND	153	154	PCIE0 TX3 N
GND	25	26	GND	PCIED RX3 N	155	156	PCIE0 TX3 P
CSI3_CLK_N	27	28	CSI2_CLK_N	PCIE0_RX3_P	157	158	GND
CSI3 CLK P	29	30	CSI2 CLK P	GND	159	160	PCIE0 CLK N
GND	31	32	GND	USBSS RX N	161	162	PCIE0 CLK P
CSI3 D1 N	33	34	CSI2 D1 N	USBSS RX P	163	164	GND
CSI3 D1 P	35	36	CSI2 D1 P	GND	165	166	USBSS TX N
GND	37	38	GND	RSVD	167	168	USBSS TX P
DP0 TXD0 N	39	40	CSI4 D2 N	RSVD	169	170	GND
DP0_TXD0_P	41	42	CSI4_D2_P	GND	171	172	RSVD
GND	43	44	GND	RSVD	173	174	RSVD
DP0 TXD1 N	45	46	CSI4 D0 N	RSVD	175	176	GND
DP0 TXD1 P	47	48	CSI4 D0 P	GND	177	178	MOD SLEEP*
GND	49	50	GND	PCIE WAKE*	179	180	PCIE0 CLKREQ*
DP0_TXD2_N	51	52	CSI4_CLK_N	PCIE0_RST*	181	182	RSVD
DP0 TXD2 P	53	54	CSI4 CLK P	RSVD	183	184	GBE MDI0 N
GND	55	56	GND	I2CO SCL	185	186	GBE MDI0 P
DP0 TXD3 N	57	58	CSI4 D1 N	12C0 SDA	187	188	GBE LED LINK
DP0 TXD3 P	59	60	CSI4 D1 P	1200 000A	189	190	GBE MDI1 N
GND	61	62	GND	12C1 SDA	191	192	GBE MDI1 P
DP1 TXD0 N	63	64	CSI4 D3 N	I2SU DOUT	193	194	GBE LED ACT
DP1 TXD0 P	65	66	CSI4 D3 N	1250_0001	195	196	GBE MDI2 N
GND	67	68	GND	1250_DIN	197	198	GBE MDI2 P
DP1 TXD1 N	69	70	DSI D0 N	1250 FS	199	200	GND
	71	70			201	200	
DP1 TXD1 P GND	73	74	DSI D0 P GND	GND UART1 TXD	201	202	GBE MDI3 N GBE MDI3 P
DP1 TXD2 N	75	74	DSI CLK N	UART1_TAD	205	204	GBE_MDI3_P GPI007
	77	78			203	206	0.1001
DP1 TXD2 P	79	78	DSI CLK P	UART1 RTS*	207	208	GPIO08
GND		80	GND	UART1_CTS*	209	210	CLK_32K_OUT
DP1_TXD3_N	81		DSI_D1_N	GPI009			GPIO10
DP1 TXD3 P	83	84	DSI D1 P	CAM 12C SCL	213	214	FORCE RECOVERY
GND	85	86	GND	CAM I2C SDA	215	216	GPIO11
GPI00	87	88	DP0 HPD	GND	217	218	GPIO12
SPI0_MOSI	89	90	DP0_AUX_N	SDMMC_DAT0	219	220	I2S1_DOUT
SPID SCK	91	92	DP0 AUX P	SDMMC DAT1	221	222	I2S1 DIN
SPI0_MISO	93	94	HDMI CEC	SDMMC DAT2	223	224	12S1 FS
SPI0_CS0*	95	96	DP1_HPD	SDMMC_DAT3	225	226	I2S1_SCLK
SPI0_CS1*	97	98	DP1_AUX_N	SDMMC_CMD	227	228	GPIO13
UARTO TXD	99	100	DP1 AUX P	SDMMC CLK	229	230	GPIO14
UARTO RXD	101	102	GND	GND	231	232	I2C2 SCL
UARTO RTS*	103	104	SPI1 MOSI	SHUTDOWN REQ*	233	234	I2C2 SDA
UARTO CTS*	105	106	SPI1 SCK	PMIC BBAT	235	236	UART2 TXD
GND	107	108	SPI1 MISO	POWER EN	237	238	UART2 RXD
USB0 D N	109	110	SPI1 CS0*	SYS RESET*	239	240	SLEEP/WAKE*
USB0 D N	111	112	SPI1 CS1*	GND	241	242	GND
GND	113	114	CAMO PWDN	GND	243	244	GND
USB1 D N	115	114	CAMO PVVDN CAMO MCLK	GND	245	244	GND
	115	118			245	240	
USB1_D_P	11/	118	GPIO01	GND	247	240	GND
GND			CAM1 PWDN	GND			GND
USB2 D N	121 123	122	CAM1 MCLK	VDD IN	251 253	252 254	VDD IN
USB2 D P			GPIO02	VDD IN			VDD IN
GND	125	126	GPI003	VDD IN	255	256	VDD IN
GPIO04	127 129	128 130	GPIO05 GPIO06	VDD IN VDD IN	257 259	258 260	VDD IN
GND							VDD IN

#### 2.4.5 RTC Battery Connector (CN13)

Pin	Signal	Pin	Signal
1	+3V	2	GND

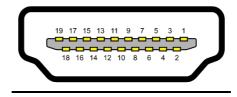
#### 2.4.6 Front Panel Connector (CN14)

1		2
3		4
5		6
7		8
9		10

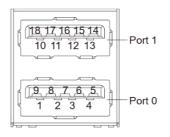
Pin	Signal	Pin	Signal
1	Button power	2	GND
3	Recovery	4	GND
5	Reset	6	GND
7	Latch set	8	Latch set
9	PWR LED	10	+5V

**Note:** Pin 7 and 8 are used for setting AT/ATX Power Mode. See **Chapter 2.3.2** for information. To prevent damage to your system, do not connect Pins 7 and 8 with any other pin.

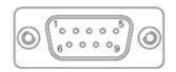
# 2.4.7 HDMI Connector (CN16)



Pin	Signal	Pin	Signal
1	HDMI_DATA2_P	2	GND
3	HDMI_DATA2_N	4	HDMI_DATA1_P
5	GND	6	HDMI_DATA1_N
7	HDMI_DATA0_P	8	GND
9	HDMI_DATA0_N	10	HDMI_CLK_P
11	GND	12	HDMI_CLK_N
13	NC	14	NC
15	HDMI_SCL	16	HDMI_SDA
17	GND	18	HDMI_PWR
19	HDMI_HDP		



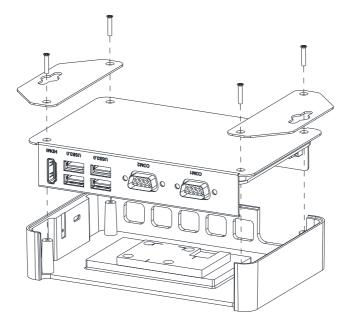
Pin	Signal	Pin	Signal
U1	VBUS_1	U10	VBUS_2
U2	(A)D-	U11	(B)D-
U3	(A)D+	U12	(B)D+
U4	GND	U13	GND
U5	(A)SSRX-	U14	(B)SSRX-
U6	(A)SSRX+	U15	(B)SSRX+
U7	GND	U16	GND
U8	(A)SSTX-	U17	(B)SSTX-
U9	(A)SSTX+	U18	(B)SSTX+

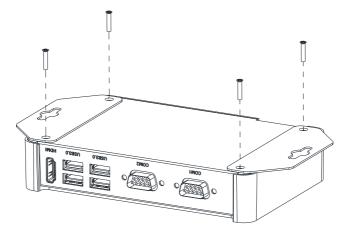


Pin	RS-232	UART
1		UART RXD
2	RXD	
3	TXD	
4		
5	GND	
6		UART TXD
7	RTS	
8	CTS	
9		

Label	System Reference	
COM1	/dev/ttyTHS1	
COM2	/dev/ttyTHS2	

## 2.5 Wall Mount Assembly





# Chapter 3

OS Flash guide

#### 3.1 Introduction

This chapter details the steps to flash the Linux operating system to your BOXER-8220AI system with NVIDIA Jetson Nano. The instructions are divided into two parts depending 1) the NVIDIA JetPack version included with your Linux OS image and 2) whether your Jetson Nano has onboard eMMC storage or SD Card slot.

Jetson Nano module with SD Card slot (no onboard eMMC):

Flash to SD Card	Linux OS with JetPack version prior to 4.5
Flash to System	Linux OS with JetPack versions 4.5 and later
ard slot):	Jetson Nano module with onboard eMMC (no SD Car
Flash to System	All versions of JetPack

If you are unsure which Jetson Nano module you have, check Ch 3.1.1 Verifying Your Jetson Nano Module.

If you are unsure which image to use, visit the AAEON support page or contact your AAEON representative.

#### Download the OS Image

Download the OS image from the product page at AAEON.com by clicking the link: https://www.aaeon.com/en/p/edge-ai-box-pc-nvidia-jetson-nano-boxer-8220ai

#### Caution: Do Not Update via Terminal

When flashing a Linux operating system, it is common practice to use the commands **sudo apt-get update** and **sudo apt-get upgrade** to ensure you have the latest version available. <u>DO NOT USE THESE COMMANDS</u> with your BOXER-8220AI system.

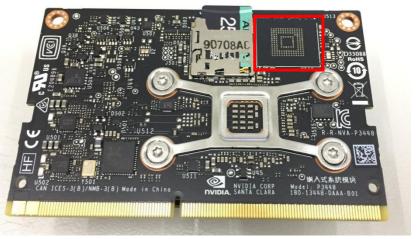
The images provided on AAEON's website include drivers and software which allows the NVIDIA SoC to recognize the various hardware features of the BOXER-8220AI. Attempting to update via terminal can erase this software and cause your system to be unable to recognize peripherals or I/O ports.

To ensure you have the latest OS image, visit the product page at the link above regularly.

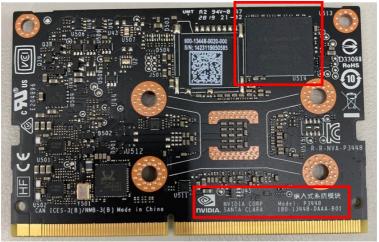
#### Security Notice WARNING:

Using an image with Boot from External Storage function may carry a security risk, i.e. SD Card or SSD. AAEON cannot guarantee that devices other than eMMC as boot media are able to maintain complete security and scalability, even if Secure Boot is enabled.

If you are unsure which storage type your Jetson Nano module uses, you can perform a quick visual inspection to see if it has eMMC memory or an SD Card slot.



Jetson Nano module with SD Card slot. You can see the SD Card slot easily, as well as the lack of eMMC storage in the highlighted area.



Jetson Nano module with eMMC storage. Note the eMMC module in the highlighted square as well as the missing SD Card slot next to it.

## 3.2 Flash to microSD Card

This section details the steps to flashing the Linux OS image to a microSD Card for your BOXER-8220AI NVIDIA Jetson Nano system.

**Note:** This section is only applicable to installing images with JetPack versions prior to 4.5 onto Jetson Nano modules with onboard microSD Card slot (no eMMC). Read the previous section to determine if this is applicable to your system.

The steps outlined apply to ACLinux build 3 or later. To identify the build number, check the file name of the download. It should be formatted as follows, with {BN} being the build number.

#### ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.{BN}.tar.gz

For example, build number 4 will be named as:

#### ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.4.tar.gz

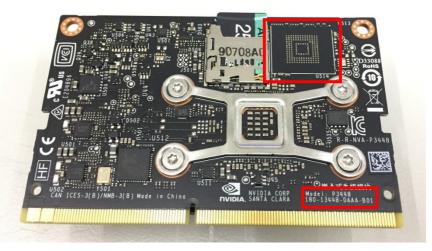
If you have any questions or are unsure which build number you have, or need help installing an older build, please contact AAEON support or ask your AAEON representative for assistance.

#### 3.2.1 Before You Begin

Before beginning the process ensure you have the following:

- ACLinux Image Build 3 or later
- One host PC with operating system Ubuntu 16.04 or 18.04
- microSD Card 16GB or larger
- microSD Card USB adapter/reader (if host PC does not have a microSD Slot)
- Jetson Nano Development Kit B01 module (no onboard eMMC storage); see

image below for reference



AAEON recommends downloading balenaEtcher for the image flash process. You can download Etcher from the balena website: <u>https://www.balena.io/etcher/</u>

Finally, before starting, on the Linux host PC, extract the image file you downloaded using the following command in terminal (remember to replace {BN} with the actual build number in the file name):

#### \$ tar xzf ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.{BN}.tar.gz

## 3.2.3 Flash Image to microSD Card

Step 1: Insert the microSD card you want to flash into the host PC.

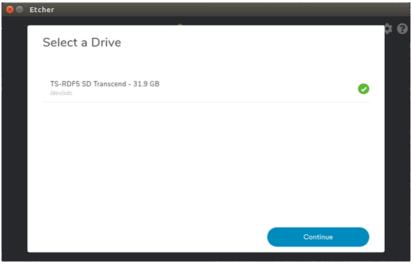
🕽 🔵 Etch	er			
		🜍 balena Etcher		<b>\$ 0</b>
				1
	+		- 7	
	Select image	TS-RDF5 SD Transcend		)

**Step 3**: Click "Select image" and choose the image file you extracted. File name should look like:

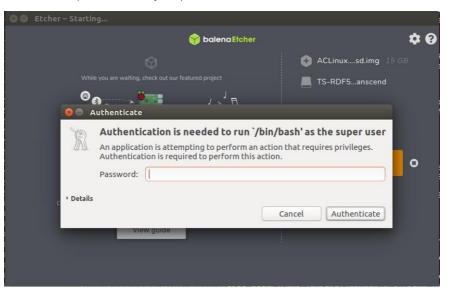
O Recent Home Name Size Modified Desktop ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.2.sd.img ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.2.tar.gz 5.6 GB Documents 21 -Ubuntu\_18.04\_UB1804D.NV03.BOXER-8220AI.0.tar.gz 6.4 GB 1 + 2019 Downloads JJ Music Pictures Videos 1 tools 15 GB Volume + Other Locati... OS Images 🔻 Cancel Open

ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.{BN}.sd.img

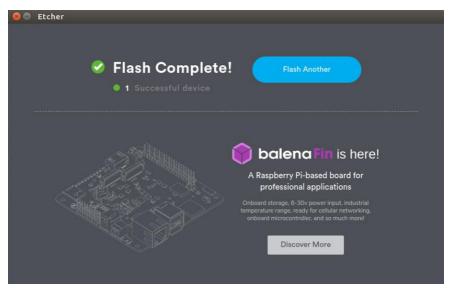
**Step 4:** Etcher will automatically choose a USB device to write to. Click "Change" to select the correct device if Etcher has not defaulted to the SD Card.



**Step 5:** Click "Flash!" to flash image to your SD Card. Ubuntu may ask for a password to continue the operation. Enter your password to continue.

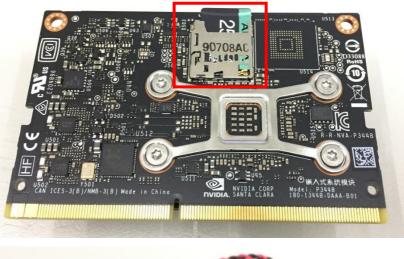


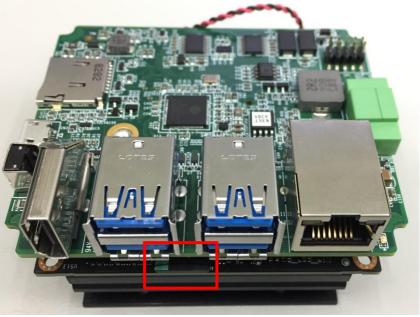
#### Step 6: Wait for Etcher to complete the process.



BOXER-8220A

**Step 7:** After Etcher successfully finishes, remove the microSD Card from the host PC, insert the microSD card into the NVIDIA Jetson Nano SOC, then insert the Jetson Nano SOC into the BOXER-8220Al board if you have not already done so.





#### 3.3 Flash to System

This section details the steps to flashing the Linux OS to your BOXER-8220AI system.

Note: This section is applicable to the following two installation types:

For Jetson Nano modules with eMMC storage and all versions of NVIDIA JetPack For Jetson Nano modules with microSD storage and NVIDIA JetPack 4.5 or later

If you are using a Jetson Nano module with microSD storage and wish to install an OS image with a version of JetPack prior to 4.5, see the previous section, Ch 3.2 Flash to microSD Card.

If you have any questions or are unsure which Linux OS image you should download, or need help with installation, please contact AAEON support or ask your AAEON representative for assistance.

#### 3.3.1 Before Installation

Before beginning the process ensure you have the following:

- One host PC with operating system Ubuntu 16.04 or 18.04
- Operating System image downloaded to host computer
- USB Cable with at least one Micro USB connector
- For Jetson Nano modules without eMMC storage, insert a microSD Card with a capacity 16MB or greater.

Make sure the NVIDIA Jetson Nano module is installed onto the BOXER-8220AI carrier board/ system, and the system is turned off and power disconnected.

Download the compressed OS image file. The file name will follow the format of:

ACLinux\_4.9\_{OS\_IF}.{PLF\_IF}.{PJ\_IF}.{BN}.tar.gz

For example:

#### ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.5.tar.gz

Note: Filename may differ from this example.

- I. {OS\_IF} is OS Information.
- II. {PLF\_IF} is Platform Information; e.g. NV03 for Jetson Nano
- III. {PJ\_IF} is Project Information; e.g. BOXER-8220AI
- IV. {BN} is Build Number; e.g. 0, 1, 2, etc.

## 3.3.2 Connecting to PC/ Force Recovery Mode

On Host Computer, open Linux terminal and enter the following command to extract compressed OS image files (*file name may vary*):

#### \$ tar -zxvf ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8220AI.5.tar.gz

Next, perform the following steps to force the system to start in USB Recovery Mode:

- Connect the Micro-USB plug on the USB cable to the Recovery Port on the BOXER-8220AI and the other end to an available USB port on the host PC.
- 2. Connect the BOXER-8220AI power supply.
- Press and hold the recovery key button. While holding the recovery key button, power on the system, and continue to hold the recovery key button for two seconds, then release. The BOXER-8220AI should enter recovery mode.

You can use Isusb command on host PC to check if the device is in recovery mode:

#### \$ lsusb | grep 0955:7f21

You should see the following return if device is in recovery mode:

0955:7f21 Nvidia Corp



micro USB

#### 3.3.3 Flash Image to Board

Use the following steps to flash the OS to the BOXER-8220AI.

- 1. Open terminal on Ubuntu host PC, then access the bootloader folder you extracted in the previous section.
- 2. Enter the following command in terminal to flash the image:

#### \$ sudo ./flashall.sh

3. Wait as the image is installed. Once finished you should see the following:

F 1 7000	] Sending BCTs
	] tegrarcmdownload bct P3448_A00_4GB_Micron_4GB_lpddr4_204Mhz_P987.bct
1.7427	] Applet version 00.01.0000
	] Sending bct
[ 1.7650	] [] 100%
1.9759	]
[ 1.9762	
1.9848	] tegrarcmdownload ebt cboot.bin 0 0download rp1 tegra210-p3448-0000-p3449-0000-a02.dtb 0
	Applet version 00.01.0000
	1 Sending ebt
2.0173	] [] 100%
	j Šending rp1
2 1673	] [] 100%
2.2013	] [] 100%
	j tegrarcmboot recovery
	Applet version 00.01.0000
2.2465	Apprec version do.or.oddo
2.2467	
	] tegrarcmoem platformdetails storage storage_info.bin
2.2626	] Applet is not running on device. Continue with Bootloader
[ 3.3943	
[ 3.4003	] tegradevflashoem platformdetails storage storage_info.bin
3.4093	
	] Saved platform info in storage_info.bin
3.4237	]
3.4245	] Flashing the device
3.4339	] tegradevflashpt flash.xml.binstorageinfo storage_info.bincreate
3.4397	Cboot version 00.01.0000
3.4453	] Writing partition GPT with gpt.bin
3,4485	j [] 100%
3,4582	] Writing partition NVC with nvtboot.bin.encrypt
	] [] 100%
	Writing partition PT with flash.xml.bin
31.4071	] [] 100%
31.4118	] Writing partition VER with qspi_bootblob_ver.txt
31.6668	] [] 100%
	Writing partition APP with system.img
	[] 100%
1359 2431	] Writing partition TBC with nvtboot_cpu.bin.encrypt
1366 3357	] [ ] 100%
1366 3495	] Writing partition RP1 with tegra210-p3448-0000-p3449-0000-a02.dtb.encrypt
1366 3018	] m ( ( ( m g ) a ( ( ( ( ( ( ( ( ( ( ( ( ( ( ( ( ( (
1266 4210	] [] 100% ] Writing partition EBT with cboot.bin.encrypt
1366.4759	
	] Writing partition WB0 with warmboot.bin.encrypt
[ 1366.7052	] [] 100%
[ 1366.7088	
[ 1366.7488	
1300.7587	] Writing partition TOS with tos-mon-only.img.encrypt
	] [] 100%
1366.8119	] Writing partition DTB with tegra210-p3448-0000-p3449-0000-a02.dtb.encrypt
	] [] 100%
[ 1366.8644	
[ 1366.9316	
1366.9756	
	] Writing partition EKS with eks.img
[ 1367.0892	] [] 100%
[ 1367.0927	
1367.1349	
[ 1367.1487	
[ 1367.1917	
[ 1367.2571	
	] tegradevflashwrite BCT P3448_A00_4GB_Micron_4GB_lpddr4_204Mhz_P987.bct
[ 1367.2749	] Cboot version 00.01.0000
[ 1367.2778	
[ 1367.2857	] [] 100%
[ 1373.9389	]
[ 1373.9392	] Flashing completed